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Abstract: Digital Elevation Model (DEM) is mostly used to extract the terrain parameters for surface 13 and elevation analysis for representing the topography of earth surface in the best possible way. 14 Nowadays smart devices such as smartphones, tablets employed with GPS chipsets are easily avail-15 able in the market. These smart devices can measure elevation data and are cost-effective. The rela-16 tively plain areas of Ratlam City (Madhya Pradesh) were the study area. Vivo 1606 smartphone 17 incorporated with Assisted-GPS (A-GPS) is used with GPS utility App called Mobile Topographer 18 to collect the ground coordinates and elevation data. The ground control points (GCPs) were col-19 lected in parts of urban areas, such as open grounds, streets, parks, and other uniformly distributed 20 GCP locations with few GCPs in outer regions of the city. Using smartphone-derived GCPs as a 21 reference the two openly accessible DEMs namely, CartoDEM V3 R1 and TanDEM-X were evalu-22 ated statistically. Statistical parameters such as Mean Error (ME), Mean Absolute Error (MAE), and 23 Root Mean Square Error (RMSE) were computed for comparative quality analysis between 24 CartoDEM V3 R1, and TanDEM-X 90, using the observed GPS elevation data. The ME (4.60 m), 25 MAE (6.12 m), and RMSE (7.15 m) for TanDEM-X 90 were higher than that of CartoDEM V3 R1, ME 26 (3.09 m), MAE (5.05 m), and RMSE (6.17 m) respectively. The results from A-GPS Smartphone re-27 vealed that the accuracy of CartoDEM V3 R1 is higher and it statistically performs better than Tan-28 DEM-X in plain areas of Ratlam using the Smartphone A-GPS. 29

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Copyright: © 2021 by the authors. Submitted for possible open access publication under the terms and conditions of the Creative Commons Attribution (CC BY) license (https://creativecommons.org/licenses/by/4.0/). 1. Introduction

The digital elevation model (DEM) represents the earth's topographic surface digi-33 tally either as a raster or vector representation incorporating the elevation data. A set of 34 quality ground control points (GCPs) are required to create DEM, in the form of a 2-di-35 mensional array with elevation at every latitude, and longitude location [1], [2]. Openly 36 accessible DEMs are available on various web portals such as BHUVAN for CartoDEM 37 V3 R1 data with 1 arc, 30 m resolution, and GeoServices DLR for TanDEM-X 90 with 90m 38 resolution. The TanDEM-X had challenges in vertical accuracy due to different imaging 39 configurations as well as data processing methods and contains various errors. CartoDEM 40products are used to establish the accurate geographic location of features and make 41 measurements with its improved version-3, release 1; i.e. CartoDEM V3 R1 [2]-[5]. 1 CartoDEM V3 R1 works best with the plain regions when evaluated with the GCPs col-2 lected using differential Global Positioning System (D-GPS) method, which is relatively 3 expensive and provides inputs for erosion mapping, and terrain modeling [4], [6]. Differ-4 ent DEM generation techniques present different accuracies for different applications, 5 making the need for evaluation of DEM accuracy compulsory [7]-[10]. Ionospheric delay 6 is the most potential and unpredictable positioning error. It is frequency-dependent and 7 is directly proportional to total electron content (TEC) [11], [12]. A high-accuracy geodetic 8 GPS receiver gives sub-meters to centimeters level accuracy, depending on its ability to 9 track, identify, and minimize the error in satellite signals during processing. The position-10 ing systems of smartphone-based A-GPS receivers or as Location-Based Services (LBS) are 11 not as accurate as of the geodetic DGPS instruments but the data accuracy is enough for 12 many regional to local-level applications for the management of various services in cities 13 including civil works for water and sewerage pipelines. Qualcomm's gpsOne technology-14 based smartphone supporting multiple modes of A-GPS was used as a GPS receiver for 15 highly reliable positioning capabilities in areas where cellular networks are not accessible 16 [13]. Vivo 1606 is capable of tracking single frequency multi-constellation measurements 17 using GPS (L5), GLONASS (L1), Beidou (B1) frequencies. Smartphones manufactured be-18 fore 2017 were mostly single-frequency receivers [14]. As Smartphone technology has 19 become the predominant tool, millions of people are now using small GPS-capable 20 smartphones not only for navigation but also for many applications such as reality-based 21 gaming apps, bicycle rentals, and so on [13], [15]. Mobile Topographer is one of the an-22 droid apps available on the Google play store, which also has paid as well as free services 23 ideal for surveyors and other users for navigation or collecting the GCPs with preferable 24 DOP (<1.3) values. Its updated features include an increase in GPS accuracy, ability to 25 display and coordinate conversion [16]. New LBS have emerged that requires more accu-26 rate positioning results such as in smartphone-based photogrammetric aerial vehicle sys-27 tem [17]. This study quantitatively examines the openly accessible DEMs using GCPs from 28 a smartphone having A-GPS. 29

2. Material and Method

2.1. Study Area

Ratlam District is having an area of about 4,861 km², primarily characterized as rela-32tively plain terrain. It's located around 23° 20' 3.0084" N and 75° 2' 15.4896" E and is33majorly a part of Malwa Plateau. Ratlam city is well known for Gold Jewelry. The study34is done in Ratlam city and its surroundings (Figure 1).35



Figure 1. Ratlam City and Surroundings overlaid with GCPs (smartphone A-GPS) on the Google Earth platform

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Figure 2. Flow chart of the methodology for DEM evaluation using GCPs collected from A-GPS enabled Smartphone

2.2. Ground Control Point (GCP) Collection

The study area was surveyed using Vivo 1606 phone having the Mobile Topographer 16 app, for the evaluation of DEMs. A survey was carried out for collecting GCPs at ap-17 propriate locations such as parks, streets, urban areas, open grounds, and rural outer 18 areas of Ratlam city for utilization as the check-points for the DEMs. The points were 19 collected in the World Geodetic System (WGS-84) datum. The flowchart in figure 2 20 describes the methodology. 21



Figure 3. Displays Smartphone A-GPS points superimposed on a) TanDEM-X 90m; and (b) CartoDEM V3 R1 DEMs.

According to the researcher's coordinate accuracy can be achieved in the order of 1 m 1 or better after 30- minutes of data collection using smartphone GPS [18]. In this study, 2 the A-GPS smartphone data was collected as reference data for statiscal analysis of 3 DEMs and it was found to attain a minimum PDOP value of about 0.2, in approxi-4 mately 35-minutes of operations at desired GCP locations. Elevation data of TanDEM-5 X 90 and CartoDEM V3 R1 were extracted after superimposing the GCPs (Checkpoints) 6 using ArcGIS as a standard method used in various researches for evaluation of DEMs 7 [19], [20]. Figure 3 displays a set of 30 GCPs obtained from a smartphone superimposed 8 on DEMs. 9

2.3. Statistical Analysis

The elevation or height values extracted from both the DEMs were used to calculate 11 the differences with DEMs. The accuracy estimation with smartphone A-GPS observation datasets is done by calculating ME (equation 1), MAE (equation 2), and RMSE 13 (equation 3) [21], [22]. H_i(DEM) (=H_i(CartoDEM) or H_i(TanDEM-X)) is the extracted elevation from 14 the DEMs dataset and H_i(A-GPS) is the A-GPS observed reference datasets at different 15 GCP locations (i=1 to n). 16

$$ME = \frac{\sum_{i=0}^{n} H_{i(DEM)} - H_{i(A-GPS)}}{n}$$
(1)

$$MAE = \frac{\sum_{i=0}^{n} |H_{i(DEM)} - H_{i(A-GPS)}|}{n} * 100$$
(2)

$$RMSE = \sqrt{\frac{\sum_{i=1}^{n} (H_{i(DEM)} - H_{i(A-GPS)})^2}{n}}$$
(3)

3. Results and Discussion

The difference between A-GPS reference elevation values and the openly accessible 18 DEMs (TanDEM-X 90, and CartoDEM V3 R1) were evaluated as shown in Table 1 for 19 analysis. The range of minimum and maximum values of TanDEM-X 90 using 30 GCPs in 20 the study area is 11.09m and 17.83m. Similarly, the values for CartoDEM V3R1 are 10.71m, 21 and 14.20m respectively. Table 2 indicates the results of statistical analysis between the 22 two DEMs in the form of ME, MAE, and RMSE. 23

S No.	H(TanDEM-X) - H(A-GPS)	(H _(TanDEM-X) - H _{(A-GPS}	5)) ² H(CartoDE	M) - H(A-GPS)	(H(CartoDEM) -H(A-GPS)) ²
1	4.32	18.69	З	.08	9.47
2	6.28	39.45	5	.33	28.37
30	3.38	11.44	-(0.30	0.09
	Table 2.	3R1.			
	DEM	1 ME (m)	MAE (m)	RMSE(r	n)
	TanDEM-	X 90m 4.60	6.12	7.15	
	CartoDEM	IV3R1 3.09	5.05	6.17	

 Table 1. Statistical analysis of TanDEM 90 and CartoDEMV3R1 using Smartphone A-GPS (Sample set)

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The results revealed that the accuracy of CartoDEM V3 R1 is higher as compared 1 with TanDEM-X 90 in plain terrain regions of Ratlam city and surroundings. The elevation 2 accuracy of DEM depends on the slope and land cover of a terrain which allows the user 3 to predict the DEM quality according to the terrain regions utilized as per the user requirements [23], [24]. The difference between TanDEM-X 90, and CartoDEM V3 R1 elevation values is reasonable based on their methods of generation and thus may require more accurate methods for reference data generation such as DGPS or LiDAR datasets. 7

4. Conclusions

The GCPs were obtained with Vivo 1606 Smartphone A-GPS using Mobile Topogra-9 pher app for successful experimentation, with an assessment of openly accessible DEMs. 10 The DEM accuracy of the openly accessible DEMs using low-cost smartphones incorpo-11 rated with A-GPS is computed reasonably, which can serve applications meeting the ac-12 curacy requirement criterion. The methodology developed for the assessment of individ-13 ual accuracies (35 minutes observation, PDOP~0.2) was found good within the margins of 14 the accuracy of an A-GPS Smartphone reference GCPs. The statistical result reveals that 15 the accuracy of CartoDEM V3 R1 is higher as compared to TanDEM-X 90 as found in sim-16 ilar studies [23]. However, the uncertainty in the analysis is governed by the accuracy of 17 A-GPS and local site characteristics. 18

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