



1 *Conference Proceedings Paper*

2 **Design of a Lebanese Cube Satellite**

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8 **Abstract:** Nowadays, nanosatellites are widely used in space technology due to their small size, ease
9 of deployment and relatively short development period. CubeSat specifications have been
10 suggested as an effort to standardize nanosatellite mission design. Standardization opens the door
11 for inter-CubeSat communications that can be used to form a CubeSat Cloud and mimic regular
12 large multifunctional satellites with wide range of features, measurements and sensing capabilities.
13 In this paper, we introduce a Comprehensive CubeSat (CoCube) online database. CoCube database
14 focuses mainly on the different subsystems used during the design and implementation stages of
15 existing CubeSat missions. Based on the lessons learned from comparing various CubeSat design
16 alternatives and components' structure and analyzing the best practices of CubeSat development,
17 LibanSAT design is introduced. LibanSAT is a 1U CubeSat that serves two main objectives: (i)
18 greenhouse gases observation and (ii) educational purposes. We benchmarked off-the-shelf
19 subsystems from various suppliers and chose the most suitable for our target mission based on cost,
20 size, weight and power consumption. Finally, we introduce a new CubeSat security algorithm based
21 on predefined anomaly detection baseline that serves as intrusion prevention system for the control
22 channel.

23 **Keywords:** Nanosatellites; CubeSat; Satellite Security; Greenhouse Gases Observation

25 **1. Introduction**

26 Designed using accessible off-the shelf technology, nanosatellites technology has drawn
27 significant attention in research communities and industrial sectors. This is mainly due to their small
28 size that does not compromise the needed performance. A nanosatellite development period is
29 relatively short which results in a reduction of the overall cost budget [1].

30 In order to standardize the design of nanosatellites mission, and develop the skills necessary for
31 manufacturing and testing nanosatellites, CubeSat Design specification (CDS) [2] has been suggested
32 [2]. Satellites are usually classified based on mass but volume is the critical factor in the case of
33 CubeSats. A unit referred to as "U" is introduced: 1U CubeSat is a satellite with maximum mass of
34 1.33 Kg and typical size of 10×10×10 cm. Initially, CDS included standards for 1 to 3U designs only
35 where 3U can be defined as a triple 1U CubeSat. Need for larger CubeSat missions required a CDS
36 extension to provide 6U to 12U standard specification.

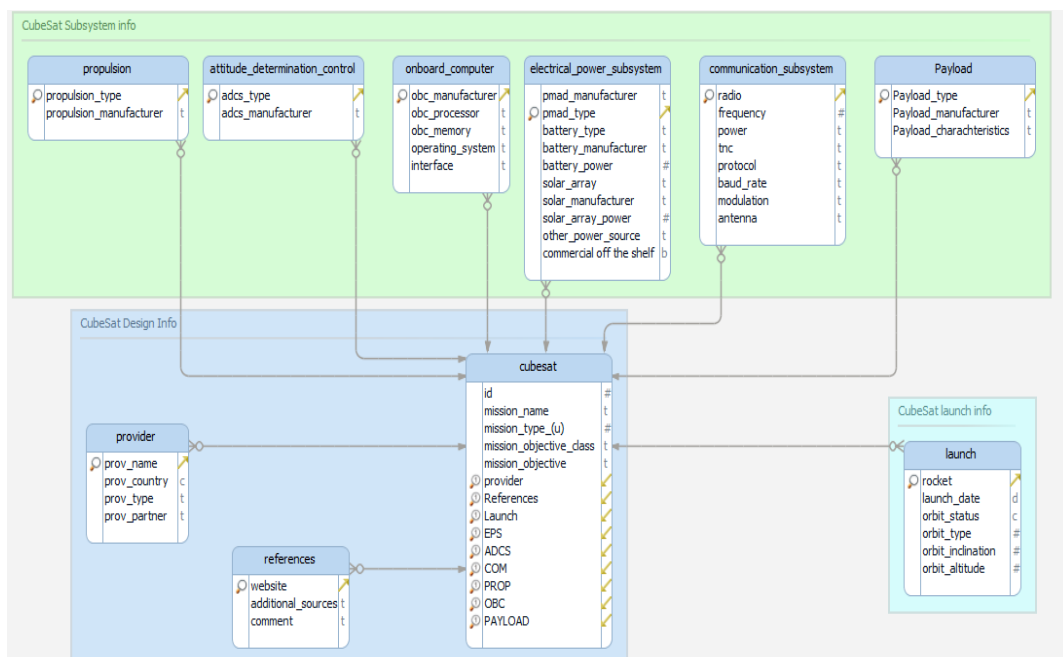
37 The contribution of this paper is threefold: (i) First, we introduce a database of all existing
38 CubeSat missions with focus on different subsystems used during the design and implementation
39 phases. (ii) Based on the lessons learned from previous missions' database, we designed LibanSat,
40 the first CubeSat for Lebanon. This is a 1U CubeSat built using ready to use off-the-shelf-components.
41 (iii) Finally, the third contribution is to introduce a new CubeSat communication security algorithm
42 based on predefined anomaly detection that serves as intrusion prevention system for the control
43 channel.

44 The rest of the paper is organized as follows: Section 2 elaborates on the Comprehensive CubeSat
 45 database (CoCube) schema. LibanSat primary and secondary goals are discussed in Section 3 where
 46 the proposed mission design is introduced. A novel CubeSat communication security algorithm is
 47 depicted in Section 4. Finally, Conclusion is given in Section 5.

48 2. CoCube Database

49 Our first contribution in this manuscript is the design of a database, referred to as
 50 Comprehensive CubeSat database (CoCube). Several existing CubeSat databases are published
 51 online [2-9]. However, these databases lack precise and updated information about the compiled
 52 missions. More importantly, existing databases do not discuss or contain relevant information about
 53 the subsystems used for each mission design. Subsystems details can be very useful for researches in
 54 this field working towards the design of their own missions. CoCube database is mainly divided into
 55 three sections as shown in Figure 2. Each section is composed of many tables as discussed in the
 56 following:

- 57 • Design Section: contains basic data related to missions under design, or waiting for launch
 58 opportunities, or currently deployed or decommissioned and is made of the following three
 59 tables:
 - 60 ▪ Basic Info Table: such as size and mission goal.
 - 61 ▪ Provider Table: such as provider details and the country of origin.
 - 62 ▪ References Table: useful sources related to the mission.
- 63 • Launch Section: contains one table that includes all launch related details. This section is
 64 restricted to deployed and decommissioned missions only.
- 65 • Subsystems Section: represents the main contribution of the CoCube database as none of the
 66 published databases contains subsystems related data as far as the authors know. Each
 67 subsystem is tabulated alone with respective components and characteristics.



68
 69 Figure 1: CoCube database schema.

70 3. LibanSat mission

71

72 *3.1. Mission goals*

73 Nowadays, developing countries are able to design their own CubeSats, using ready to use
74 Component Off The Shelf (COTS). In this manuscript, we introduce LibanSat, a 1U CubeSat that
75 serves as a remote sensing unit aiming to detect greenhouse gases emissions. Greenhouse gases
76 detection is set as the primary objective for the proposed LibanSat mission, whereas the second
77 objective is an educational one. Data generated from our mission will be published and made
78 available online to contribute towards the international effort to monitor and reduce greenhouse gases
79 emission.

80 In addition to its primary mission goal, LibanSat has an educational secondary purpose. After
81 getting a launch opportunity for our CubeSat, we will transfer the experience gained from this project
82 to local researchers and graduate students through presentations and workshops. In addition to that,
83 we are designing a graduate course module in this field where we will demo a CubeSat prototype
84 we built using Raspberry Pi and low cost equipment.

85 *3.2. Mission design*

86 The main subsystems typically used in a CubeSat architecture are the following:

- 87 • Structure
- 88 • Payload
- 89 • Onboard Computer (OBC).
- 90 • Electrical Power System (EPS):
 - 91 ○ Power Management and Distribution (PMAD)
 - 92 ○ Battery
 - 93 ○ Solar panels
- 94 • Communication subsystem (COM)
- 95 • Attitude Determination and Control System (ADCS)

96 We will not elaborate on each of these subsystems due to space limitation, but instead we will
97 focus on the payload. Argus-1000 spectrometer functions in the near infrared spectrum and can be
98 effectively used for greenhouse gases detection with a matching mass of 230 g and a suitable volume
99 of 45 mm x 50 mm x 80 mm. In fact, two CubeSat missions, Canx-2 and SNSAT [5], successfully used
100 the Argus-1000 in the outer space. Our contribution lies in the fact that this is the first attempt to the
101 best of our knowledge to include this sensor in a 1U CubeSat.

102 In order to choose the remaining subsystems suitable for our mission and especially our payload,
103 we compare subsystems offered by different companies and choose the most appropriate ones. Due
104 to space limitations, we will not show the detailed comparison matrix, and only selected subsystems
105 are shown in the Table 1 with correspondent characteristics.

106 The EPS COST has all needed power parts including battery and solar panels. We choose solar
107 panels from ISIS as it provides solar panels with antenna holder. Communication subsystem is
108 chosen from GomSpace as it ensures the best baud rate, lightest shape in the market with an
109 acceptable power consumption. A3200 OBC is more expensive than other options in the market,
110 however mass, volume and power consumption had more priority in our design. The chosen OBC
111 serves also as ACDS as it contains 3-Axis magneto resistive sensor and 3-Axis gyroscope. The ground
112 station is provided by GomSpace too to ensure utmost compatibility with the communication
113 subsystem, knowing that it had the best price in the market. Please note that we do not refer to the
114 ACDS in Table 1 as we do not use a standalone subsystem for it, and instead we rely on the solar
115 panel with sun sensors, temperature sensors and magnetorquer and the OBC sensors.

116 Mass and volume budget shown at the end of Table 1 shows a good margin that can be used for
117 wiring and buses, in addition to any future change in the design. It is clear that the payload constitutes
118 around 49% of the cost of the proposed CubeSat design. Selected solar panels deliver around 2.3 W,
119 which is aligned with our power consumption budget that is around 1W calculated with 20%
120 contingency. Finally, the 22Whr battery will be suitable for the eclipse time.

121 Table 1: Mass, height, cost and power budgets of proposed LibanSat components [13-15].

Subsystem	Manufacturer	Module	Mass (g)	Height (mm)	Power (mW)	Duty Cycle (%)	Power (mW) ¹	COST (€)
Structure	ISIS Inc.		87.2					2500
EPS	Crystal Space	P1u	420	13	15	100	18	16,000
COM	GomSpace	AX 100	24.5	6.5	2640 ²	3	95	6000
					180 ³	100	216	
OBC	GomSpace	A 3200	24	7.1	130	100	156	6000
Antenna	ISIS Inc.		100					5000
Payload	Thoth tech.	Argus 1000	230	45	2300	20	552	53,000
Ground station	GomSpace							38,500
Total			888	71.6			1050	127,000
Standard limit			1330	-100				
Margin			- 442	-28.4				

122 ¹ Power consumed during duty cycle with 20% contingency.

123 ² Power consumed during transmission.

124 ³ Power consumed during reception.

125 4. CubeSat Security

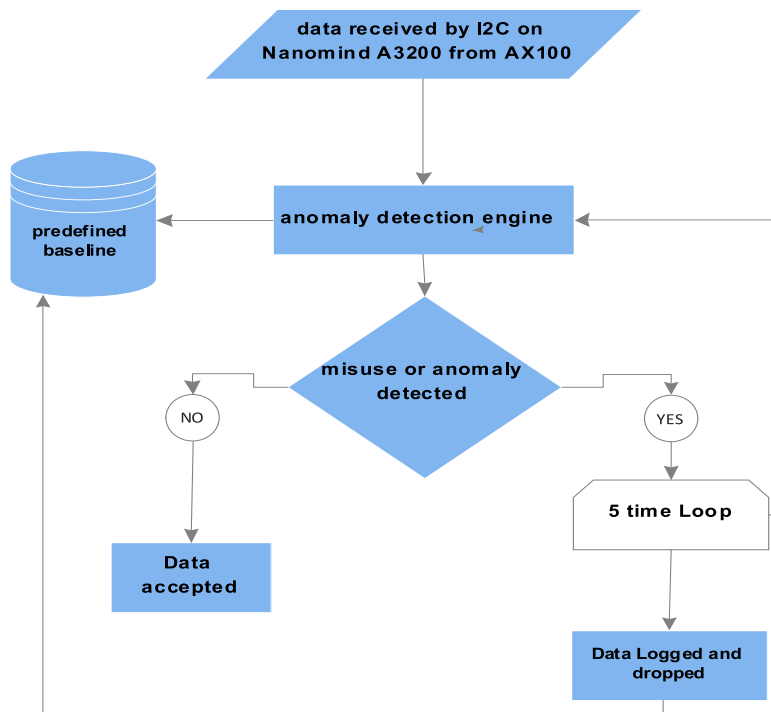
126 The last contribution of this manuscript is the security subsystem. An anomaly based intrusion
127 prevention system is designed and implemented for LibanSat mission. Satellites, like any other
128 wireless technology face some risks and vulnerabilities. In order to understand the security threats
129 of a system, it is important to understand the way it communicates. In our case, the communication
130 subsystem is the first critical part that must be taken into consideration. Although in the present time,
131 CubeSats might not be a priority target for hackers and terrorists, but the rapid evolution of this
132 technology may increase this threat.

133 CubeSats have two types of communication channels: (i) Data channel and (ii) Control channel.
134 Data channel is a downward directional communication link where gathered data by sensors and
135 payloads is sent from the satellite to the ground station. Data encryption algorithms can be utilized
136 for critical data, especially for military missions. However, in the majority of the cases, data gathered
137 is not sensitive. Control channel is critical since it is used for controlling satellite from the ground.
138 CubeSat Space Protocol (CSP) [15], which is a small network/transport layer protocol designed by
139 Aalborg University is widely used nowadays in CubeSat missions design and hence the proposed
140 security algorithm will be implemented on top of this protocol [16].

141 Majority of CubeSat OBC is based on Linux or FreeRTOS open source operating system [20]. In
142 some missions, we even witnessed the use of a smartphone as an OBC [21]. The main threat comes
143 from the fact that once launched, operating systems are no longer updated with regularly released
144 security patches due to tight link capacity.

145 To cope with this problem, we propose a new security protocol for our CubeSat. Due to the
146 power and mass limitations, we introduced a lightweight Intrusion Prevention System (IPS) based
147 on predefined anomaly. We define a baseline state of the network's traffic load, protocol used, and
148 regular package size. In addition, based on orbit parameter, we can easily predict the pass time of
149 CubeSat over corresponding ground station, and thus we use this value in the predefined baseline
150 state. We also use the location of the CubeSat in case of onboard existing GPS module. Any received
151 packet will be monitored by the anomaly detection agent. In case of baseline misuse, the anomaly
152 engine will drop the packet and log it for future forensics. After five misuses, transmitter will be
153 added to our block list and baseline will be updated accordingly. The block diagram of the proposed
154 algorithm is shown in Figure 2.

155



156

157

Figure 2: Flow chart of proposed anomaly detection algorithm.

158 5. Conclusion

159 In this paper, we introduce LibanSat, the first Lebanese 1U CubeSat. LibanSat design is based on
160 learned lessons from Comprehensive CubeSat database that focuses on the subsystems used during
161 the design and implementation phases of previous CubeSat missions. A security algorithm is
162 suggested based on a lightweight intrusion prevention system that does not compromise CubeSat
163 performance. In Future work, we will expand the proposed security algorithm with better detection
164 techniques and overhead simulation.

165 **Conflicts of Interest:** The authors declare no conflict of interest.

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