

1 *Proceedings*

2 **Influence of Ponsse Gazzelle forwarder passes on** 3 **the soil environment and soil deformation.**

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6 **Abstract:** During the harvesting and skidding process, machine runs have a strong influence on the
7 soil environment. The study analyzed the influence of 20 runs of the Ponsse Gazzelle forwarder on
8 the change of soil compactness, moisture and deformation. The research were carried out in Gidle
9 Forest District, located in southern Poland. Analyzed areas was differing in soil type and
10 hydrological conditions. On the investigated forest areas control sections were established for
11 measurements. The data of changes in soil compactness were gained by using a handheld
12 penetrometer at a depth of 10 and 20 cm. The soil compactnes were measured after each forwarder
13 pass. Soil moisture was also assessed at a depth of 10 and 20 cm before the start of the forwarder
14 operation, and after 20 passes. To obtain data for determining soil deformation UAV were used.
15 Terrain models were created using Agisoft Metashape software. From the generated 3D terrain
16 models, changes in the cross-sections of operational routes were determined. The data were
17 subjected to statistical analysis to determine the relationship between the rate of changes in soil and
18 terrain conditions. The increase of soil compactness was linear on all the examined plots. Statistically
19 significant differences were found in the soil compaction rate. After 20 runs of the forwarder, the
20 humidity in the tested sections decreased almost 3 times. Correlation analysis showed a moderate
21 relationship with the extent of soil deformation and the type of soil
22 and the type of forest habitat.

23 **Keywords:** Forest Operations; UAV; Terrain 3D model; Wood Logging; Soil displacement

24 **1. Introduction**

25 The use of forwarders during forest work enabled a significant increase in the efficiency of
26 timber transport from the harvesting site to the place of temporary storage. Due to their efficiency
27 and greater safety compared to older types of machines, a further increase in the use of these
28 machines in Polish forests seems inevitable [1,2].

29 Forwarders are characterized by high weight which makes their runs negatively affect the soil
30 [3, 4] which results in soil compaction. Soil compaction is connected to decreasing soil porosity and
31 increasing bulk density [5]. An increase in soil compactness is possible to measure by determination
32 of soil penetration resistance, by using penetrometer.

33 The development of technology and the increasing availability of unmanned aerial vehicles on
34 the civil market, along with the growing offer of open-source programs for modeling based on aerial
35 photos, opens up new possibilities for conducting analyzes of post-cut surfaces. [6,7,8].

36 The aim of the research was to analyze the influence of 20 forwarder runs on soil moisture and
37 increase of its compactness. By using aerial photography and geomatic software, an analysis of the
38 logging area, distribution and condition of the network of logging routes was carried out.

39 **2. Materials and methods**

40 The research was carried out in the Gidle Forest District in the southern Poland. For the study,
41 4 cutting areas were selected, differing in the type of soil, stand type and site wetness index (Tab. 1).

42 **Table 1.** Parameters of analyzed cutting areas.

Site nr.	Habitat type	Site moisture index	Soil type
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1	BMW	++++	Bgms
2	BW	+++	Bgts
3	BMŚw	++	RDB
4	BŚW	+	Bw

43 Bśw – fresh coniferous; Bw – moist coniferous; BMśw – fresh mixed coniferous; BMW – moist mixed
 44 coniferous. Bw – podzolic soil Bgms, Bgts - glial-podzolic soil, RDB - rusty podzolic soil
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46 On each of analyzed sites, 30-meter-long control sections were established. On each of this test
 47 sections the changes in soil compactness were determined during 20 forwarder runs. The skidding
 48 process were carried out by the same Ponsse Gazelle forwarder, which was controlled by the same
 49 operator on all the analyzed areas.

50 Changes in soil penetration resistance were measured with an Ejkelkamp hand penetrometer
 51 before skidding proces and after every of 20 forwarder passes. The measurements was made every 1
 52 meter. Measurements were made in the left rut, right rut and in the lane between ruts. The changes
 53 in soil penetration ressitance were measured at a depth of 10 and 20 cm. Changes in soil moisture
 54 before starting work and after 20 forwarder passes were also determined.

55 Using an unmanned aerial vehicle (UAV), a flight was made over the analyzed cut areas, during
 56 which the photos were recorded. For the research a DJI UAV Phantom 4 Advanced model was used.
 57 This model is equipped with a camera with a 1-inch CMOS sensor and a resolution of 20 megapixels,
 58 allowing to take photos with a maximum resolution of 5472 × 3078 pixels. The flights were made at
 59 an altitude of 30 meters, and the overlap index of the photos was 80%, both horiontally and vertically.

60 The obtained photos were used to create digital elevation models [DEM] of the terrain and
 61 orthomosaic using Agisoft Metashape software. Obtained data allowed to create numerical models
 62 where a single pixel represents a square with a side of 1.5 cm in the terrain. By assesment of
 63 orthomosaics in Qgis te the skid trail area, lenght and codition was analyzed. By analyzing the DEM
 64 in Qgis software, the soil displacement and rutting depth during forestry work was determined.

65 R studio software was used to perform statistical analyzes. The Kruskal-Wallis test was used to
 66 determine the significance of differences between the studied surfaces. The correlation was calculated
 67 using Pearson correlation test.

68 3. Results and Discussion

69 As noted by Walczyk and Kormanek [9], clear changes in soil compactness are visible at a depth
 70 of up to
 71 25 cm. The most common analysis was the effect of different logging and skidding machines on soil
 72 in plots with similar characteristics. The less common form of research was the assessment of
 73 differences in the rate
 74 of changes of the compactness on the surfaces that differ in such parameters with the use of the same
 75 type of machine.

76 The course of changes in soil density showed a similar character in all tested sections, regardless
 77 of the tested depth. The areas in the BMSw habitat were characterized by the highest degree of soil
 78 compaction after 20 runs of skidding agent. The mean percentage change in compactness was also
 79 the largest on these plots.

80 The forwarder travels had a greater impact on the compactness of the soil at a depth of 20 cm
 81 than on the depth of 10 cm, regardless of the tested section on all tested surfaces.

82 In the left and right rut, the pace of increasing soil compaction was similar in all sections. In
 83 some cases, soil compactness increased almost 4 times at a depth of 10 cm and almost 5 times at a
 84 depth of 20 cm. The t test proven that there is statistically significant differences between soil density
 85 before and after 20 forwarder passes (p value = 0,0000).

86 At a depth of 20 cm, a greater ingresem in compactness can be noticed and that the forwarder
 87 wheels have a stronger impact on the ground between the ruts (Tab. 2).

88 **Table 2.** Changes in soil compactness [%] after 20 passes in relation to the state before the skidding
 89 for analyzed transects.

Placement	Depth	Transect			
		1	2	3	4
Left Rut	10 cm	341.9%	418.7%	422.30%	341.9%
Middle		208.4%	235.6%	273.90%	208.4%
Right Rut		325.9%	316.0%	431.40%	325.9%
Left Rut	20 cm	385.4%	491.9%	341.20%	362.7%
Middle		410.5%	394.3%	204.60%	394.3%
Right Rut		219.7%	283.0%	329.40%	313.4%

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91 Soil moisture was determined by taking soil samples, and determining soil moisture by weighing
 92 and drying them. The change in soil moisture on the tested surfaces is summarized in the table below
 93 (Table 3).

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Table 3. Soil moisture on the examined areas.

Placement	Transect			
	1	2	3	4
Measure outside skid track (refrence)	42.20%	15.50%	13.70%	14.90%
Skid track before forwarder passes	37.30%	9.00%	8.60%	6.00%
Skid track after 20 forwarder passes	14.60%	5.80%	5.80%	3.90%

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Machine travels noticeably lowered the water content in the tested soil. It is worth noting that
 96 the initial values on most surfaces are low from the very beginning. This is due to the fact that the
 97 research was conducted during a large drought durin summer in 2019.

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Carrying out works with the use of forest machines should be performed in particular when the
 99 soil moisture

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is low. As proved by Buliński and Sergiel [10], the rate of compacting the same soil with the same
 101 parameters depends on the current degree of its moisture.

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On the examined plots, differences were found between the area declared and the area measured
 103 on the basis

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of orthophotomaps (Table 4). There was an average of 0.91 km of skidding trails per 1 hectare of the
 105 studied site. These values are in the range of 0.67 to 1.00 km / ha (Table 4). During the research, the
 106 area of the operational routes was determined, on which deformation and damage to the soil
 107 structure caused by machine passes can be expected. Moreover, the area of places where machine
 108 runs caused the uncovering of the mineral layer of the soil were identified (Table 4.).

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Table 4. Results of analyses based on orthomosaics in Qgis software.

Site	1	2	3	4
Area declared to cut	1.21	1.29	1.84	1.91
Area measured after cut	1.35	1.23	1.75	2.04
Diference [Ha]	0.14	-0.06	-0.09	0.13
Difference %	11.13%	-4.56%	-4.66%	6.70%
Skid trails lenght [km]	1.35	1.23	1.69	1.38
Skid trails per 1 Ha	1.00	1.00	0.97	0.67
Skid trails area [ha]	0.41	0.38	0.42	0.52
% of cut area covered with skid trails	33.72%	29.23%	21.85%	28.05%
Area with soil damage to the mineral layer [Ha]	0.053	0.007	0.05	0.055

Converted to % share in the area of the trails area	10.13%	1.50%	7.81%	10.24%
Converted to % share of measured cut area	3.92%	0.57%	2.85%	2.70%

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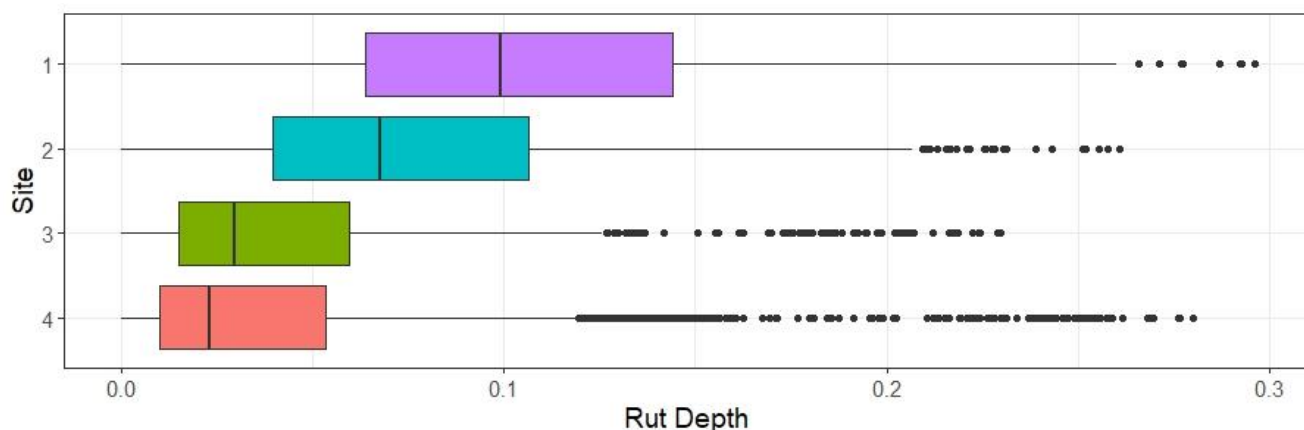
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Digital elevation model [DEM] is a numerical representation of the topographic height of the terrain surface. The topology is defined as a result of applying interpolation algorithms that recreate the shape of the modeled surface. Digital elevation models created on base of aerial photography were used to determine the rutting depth. Using the Qgis software and terrain profile plug-in, the depth of the ruts was determined and compared to the ground level around them. Large differences are noticeable in the depth of the ruts on the tested transects (Fig. 1.)



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Figure 1. The result of rut depth analysis on the tested surfaces based on DEM in Qgis.

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The kruskal-wallis test was used to assess whether there were any statistically significant differences between the depth of the ruts. The obtained result of $p = 0.0000$ indicates that there are statistically significant differences.

By carrying out the Pearson correlation test, the relationship between the tested surface and the size of the created ruts was determined at the level of 0.44 which indicates a moderate correlation.

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4. Conclusion

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1. During the conducted research, differences in the rate of changes in soil compactness within the studied operational routes were found.
2. Soil moisture decreased in a similar manner for all the examined plots.
3. Differences were found between the area declared for cutting and the actual cut area.
4. The share of soil damage to the mineral layer did not exceed more than 4% of the examined areas.
5. Statistically significant differences were found between the size of the ruts formed on the individual examined plots.
6. A moderate correlation was found between the analyzed site and the size of the ruts after 20 forwarder passes.

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5. References

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