

SIGNAL-TO-NOISE OPTIMIZATION: GAINING INSIGHT INTO **INFORMATION PROCESSING IN NEURAL NETWORKS** Benjamín Pascual^{1,2} and Salva Ardid^{2,3*}

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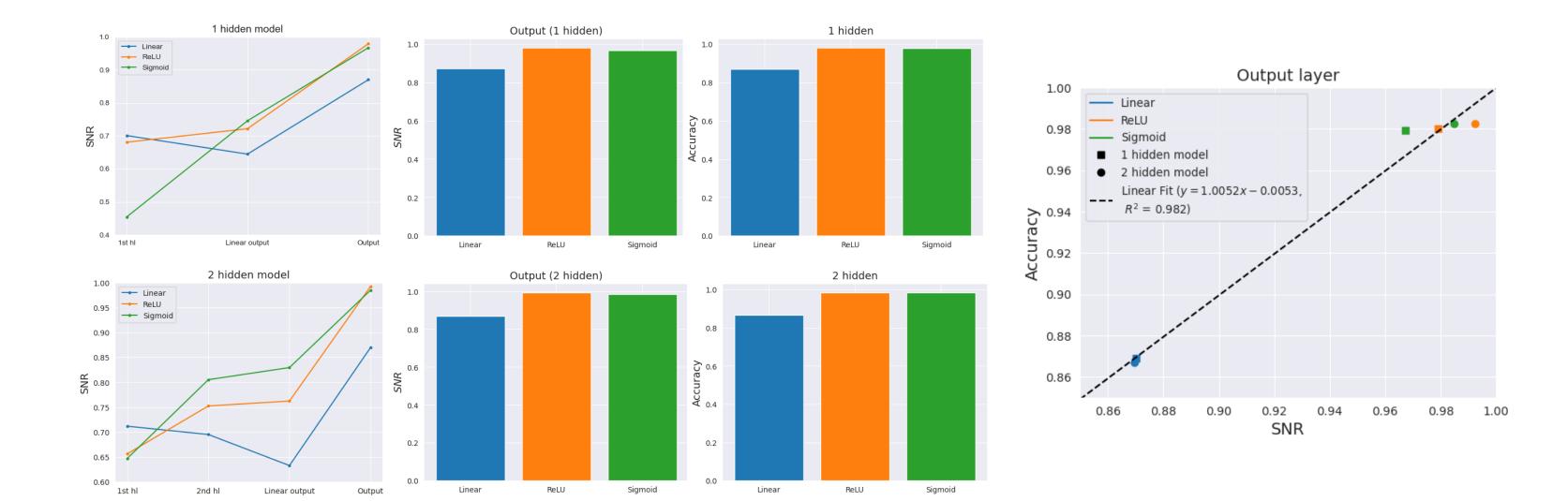
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Introduction

- Mainstream debate in neuroscience and machine learning arguing if neural networks benefit from Low [Op de Beeck et al., 2001, Gao and Ganguli, 2015, Gallego et al., 2017, Ansuini et al., 2019, Recanatesi et al., 2019] vs. High [Elmoznino and Bonner, 2022] dimensional representations.
- We suggest that learning in deep neural networks optimizes **signal-to-noise** processing.

Results

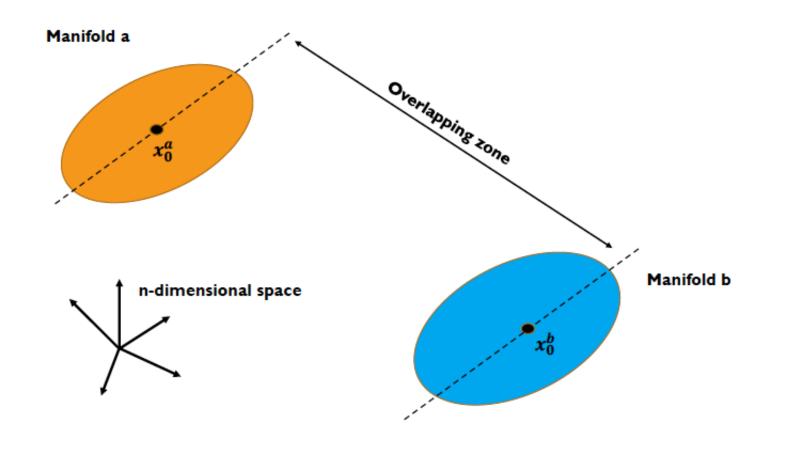
• After training **SNR** is highly predictive of the **Accuracy** (top: 1 hidden layer model, bottom: 2 hidden layers model, right: linear fit Acc. vs. SNR)



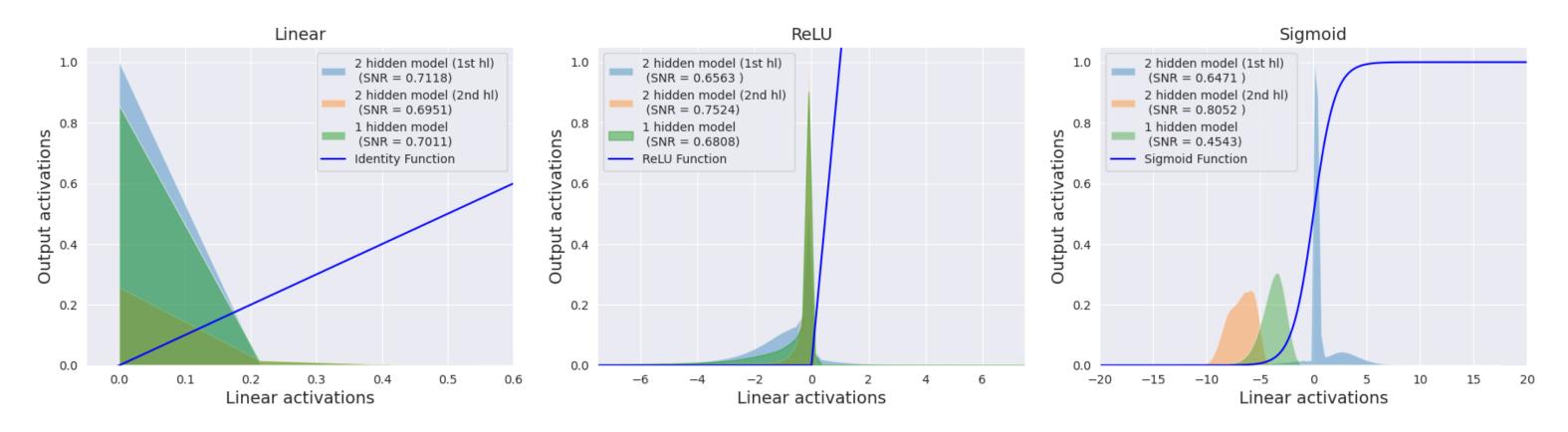
- We also speculate that **nonlinearities** (e.g., in activation functions) facilitate this process.
- To test these hypotheses, we defined a measure of the signal-to-noise ratio (SNR) which can be applied to neural representations associated with predictions of unseen data.

Methods

- In neural networks, patterns of activity define a **manifold**.
- We can analyze these manifolds in **feature space**, e.g., for each class in a categorization task.
- Qualitatively, manifolds' separability can be expressed in terms of the distance between centroids minus their overlap, i.e., the projection of the manifolds in that axis.
- Let's consider two different categories:



- Dimensionality in output layer (probabilities) is always equal to 1 (two-dimensional space with one constraint), so is not predictive of the accuracy.
- Distributions of activations after applying non-linearities show two modes: silent (nonpreferred input) and non-silent (preferred input) activity



- We analyze if using **SNR** compared to the **loss function** better avoids overfitting when using early stopping.

• Our definition of the **SNR** then becomes:

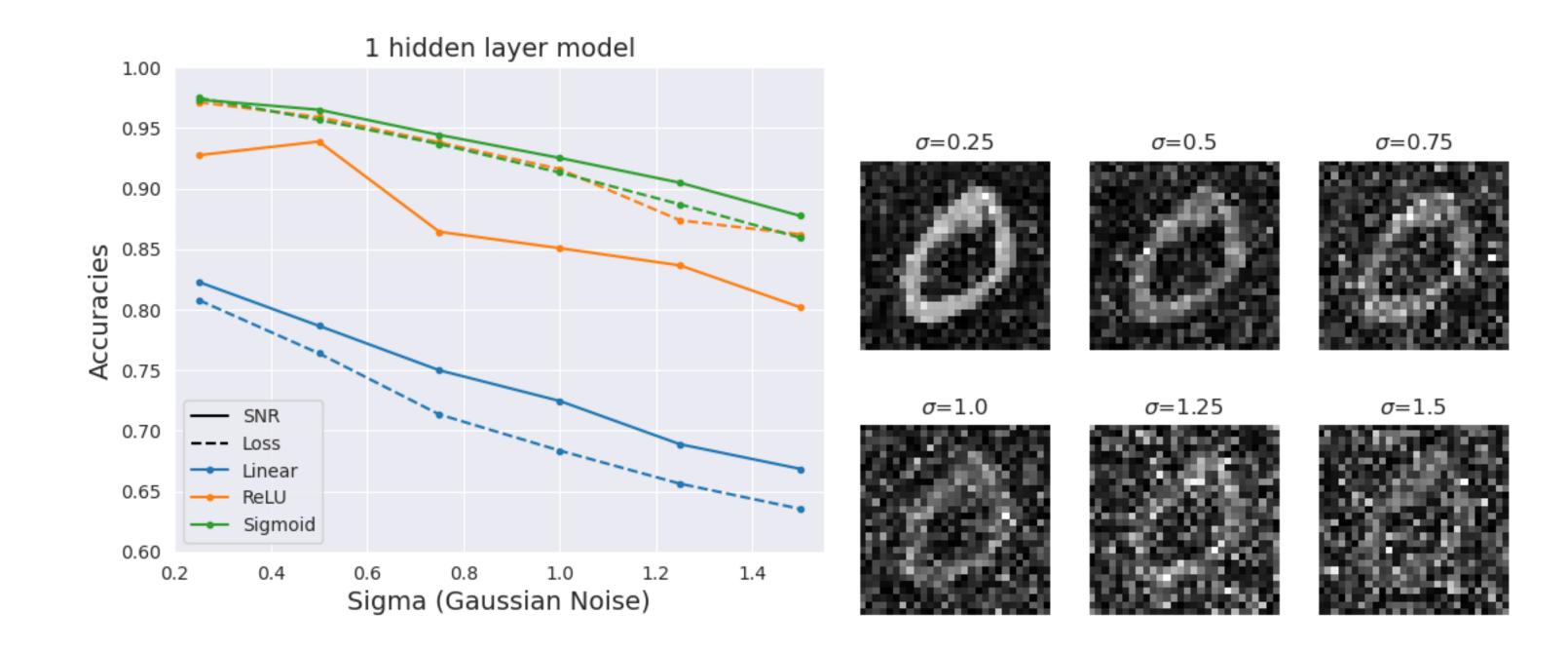
$$SNR = \frac{\|\Delta \mathbf{x}_0\| - N_{lineal}}{\|\Delta \mathbf{x}_0\|} = 1 - \frac{N_{lineal}}{\|\Delta \mathbf{x}_0\|}$$
(1)

- $\|\Delta \mathbf{x}_0\|$: distance between centroids
- $N_{lineal} = \frac{1}{N_T^0} \sum proj_0^- + \frac{1}{N_T^1} \sum proj_1^-$ quantifies the **overlapping zone**.
- Equation (1) can be used to quantify the **SNR** of a subset adding the term $\sum proj$ (because we are considering all cluster, $\sum proj = 0$)
- We calculate the probability of one input image to belong to one category as $p(a_i) = \frac{a_i}{\sum_i a_i}$
- We used the MNIST image dataset.
- Feedforward neural networks were trained to classify digits as even or odd. These neural networks have one or two hidden layers with 784 neurons each one.

Conclusions

• High correlation between Accuracy and SNR supports our hypothesis that

State-of-the-art early stopping approach is using the minimum of the loss function in a reduced dataset (validation). However, this method is sensitive to noise in the validation set [Genkin and Engel, 2020]. Here we adapt the SNR metric (1) assuming that the training and validation sets belong to the same distribution.



- We show that better performance can be achieved by this method when noise is present in the data.
- Remarkably the two non-linearities behave very differently when using early stopping based on SNR: better performance is achieved with the sigmoid function, whereas the ReLU function shows stronger irregularity and worse performance.
- learning optimizes the SNR in neural networks.
- Early stopping based on SNR better avoids overfitting, when using sigmoid and linear function, than the **loss function**.

References

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