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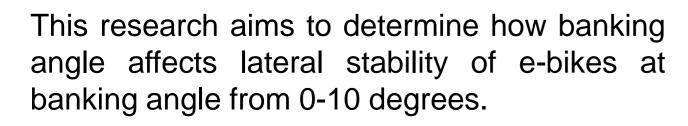
### Simulation-Based Assessment of Banking Angle Effects on Electric Bike Lateral Stability Under Steady-State Conditions

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### INTRODUCTION & AIM

In recent years, the number of consumers of three-wheeled vehicles has increased because of their practicality. However, along with the rise in demand comes a growing concern for safety, in terms of vehicle lateral stability during maneuvers. This highlights the need to understand the factors that influence stability, which this study addresses through multibody dynamics simulations.







**Modeling of Track and E-bike Based** 

on Actual Measurements

☐ Motion (A5)

📠 Initial Conditions Analysis Settings

Standard Earth Gravity

Solution (A6)

Contact Friction Properties

Solution Information Force Reaction Force Reaction 2 Force Reaction 3

**Solution:** Setting up Boundary

Conditions and Running the Simulation

**Static Validation:** 

**Dynamic Validation:** 

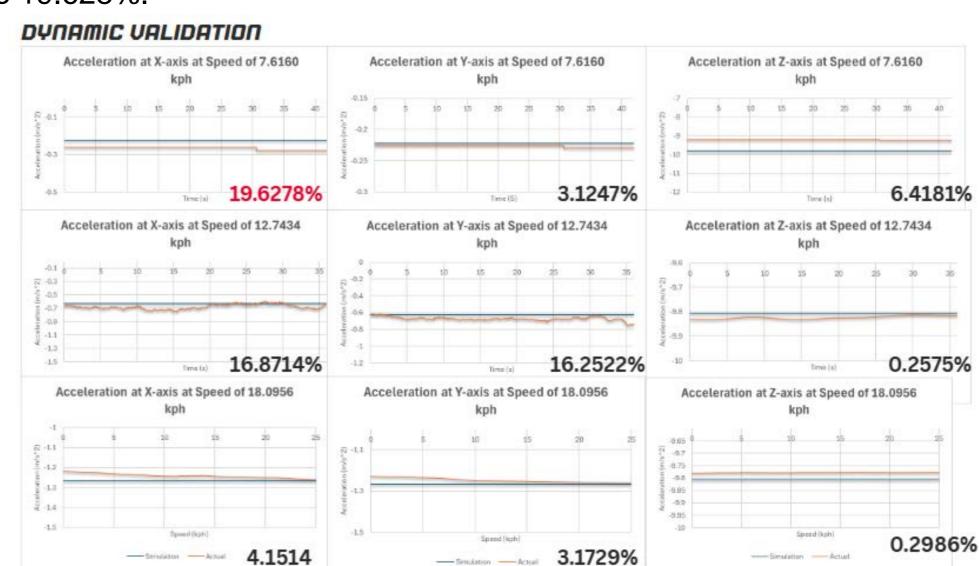
**1.) Mass:** 0.0884%

1.) Acceleration: 19.6278%

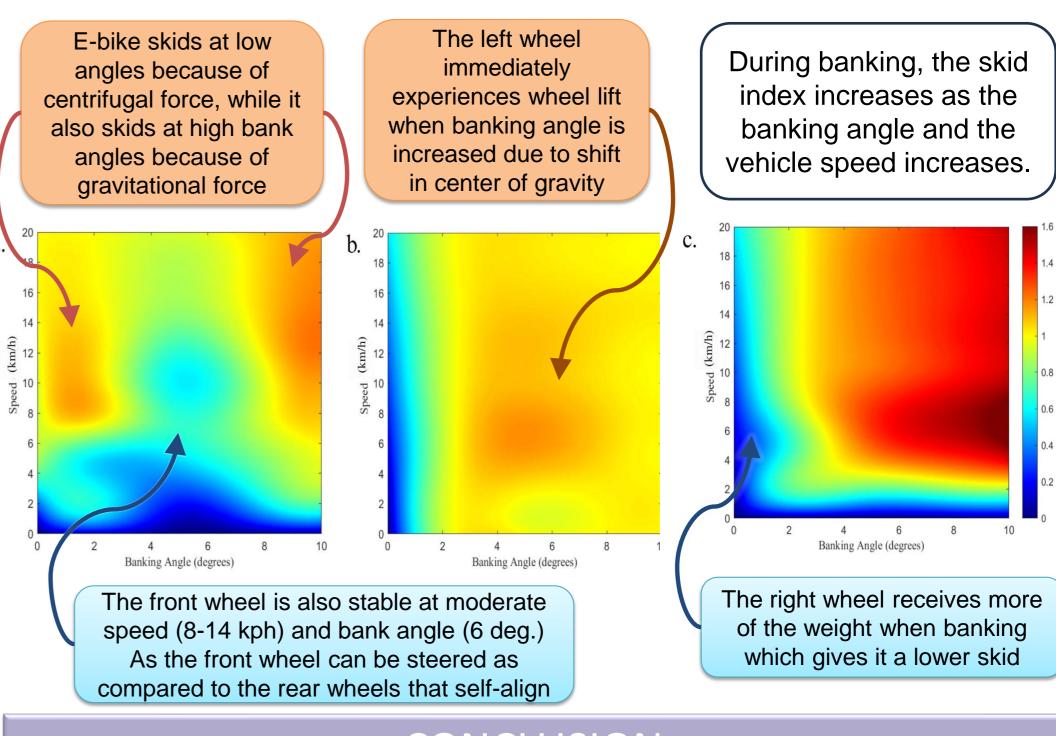
**2.) Forces on Wheels:** 7.6568%

The results show that the static and dynamic models were validated as the solved percent difference between the actual and simulated set-up is limited to 19.628%.

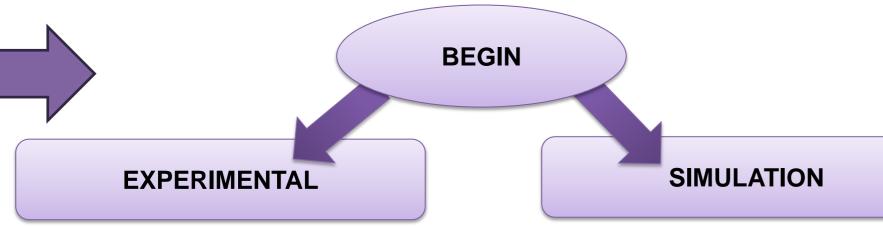
**RESULTS & DISCUSSION** 



Contour Plots of Skid Indices at Increasing Speed and Banking Angle Front (a), Left Rear (b), and Right Rear (c) Wheel

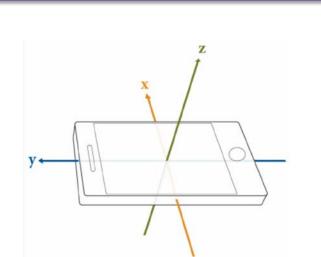


## **METHOD**



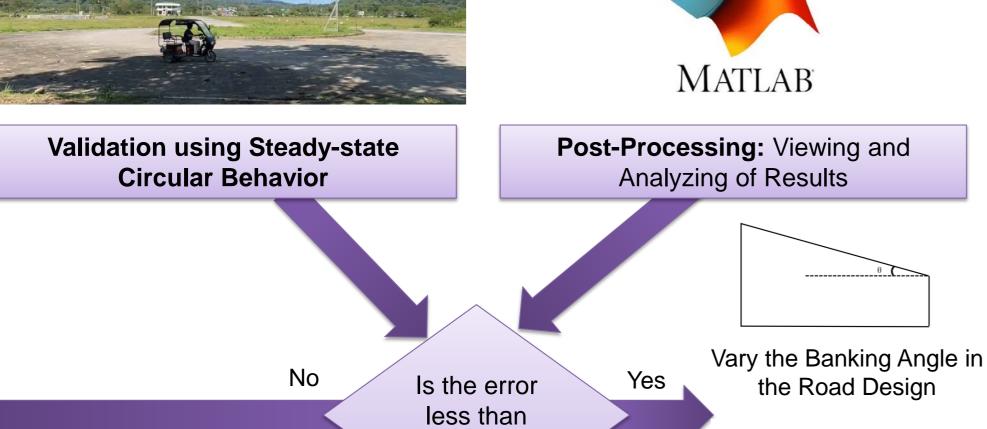


#### **Identify Vehicle Characteristics**



Preparation of Vehicle, Track and **Equipment** 





20%

**Determine Skid Index** 

 $SI = \frac{\sqrt{(\Sigma F_L)^2 + (\Sigma F_S)^2}}{2} < I$ 

### CONCLUSION

With this, drivers and passengers should be aware that driving at high speeds during cornering, most especially on roads with high bank angles could lead to accidents. They should consider driving at speeds less than 12 km/h and on inclines less than 6° to avoid accidents.

### REFERENCES

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