

# A Robust Adaptive Hybrid Nonlinear Conjugate Gradient Method Ensuring Global Convergence

Chibi Mouhamed Amine<sup>1,\*</sup> Nouredine Benrabia<sup>2</sup>

<sup>1</sup> Department of Mathematics, University of souk ahra, Algeria

<sup>2</sup> Department of Mathematics, University of souk ahra, Algeria

\*1 Correspondence: m.chibi@univ-soukahras.dz \*2 Correspondence: n.benrabia@univ-soukahras.dz

## INTRODUCTION & AIM

**Context.** Nonlinear conjugate gradient (NCG) methods solve  $\min_{x \in \mathbb{R}^n} f(x)$  with  $O(n)$  storage and one gradient evaluation per iteration. The update rule is:

$$x_{k+1} = x_k + \alpha_k d_k, \quad d_{k+1} = -g_{k+1} + \beta_k d_k$$

**Classical  $\beta_k$  formulas** ( $y_k = g_{k+1} - g_k$ ):

$$\beta^{\text{FR}} = \frac{\|g_{k+1}\|^2}{\|g_k\|^2}, \quad \beta^{\text{PRP}} = \frac{g_{k+1}^\top y_k}{\|g_k\|^2}, \quad \beta^{\text{HS}} = \frac{g_{k+1}^\top y_k}{d_k^\top y_k}$$

**FR:** strong theory, slow convergence. **PRP/HS:** faster but may lack global convergence without safeguards.

**Aim.** Propose **AHNCG**, a hybrid that:

- Continuously combines FR, PRP, HS via a geometry-driven weight  $\theta_k$
- Guarantees *uniform* sufficient descent for all  $k$
- Proves strong convergence  $\lim_{k \rightarrow \infty} \|g_k\| = 0$

## RESULTS & DISCUSSION

**Test bench.** 96 CUTEst problems,  $n \in \{50, \dots, 10000\}$ , strong Wolfe line search ( $c_1=10^{-4}$ ,  $c_2=0.4$ ),  $\varepsilon = 10^{-6}$ .

Method	NF	NI	CPU(s)	SR(%)
FR	1247	843	1.82	76.0
PRP <sup>+</sup>	938	614	1.41	84.4
HS <sup>+</sup>	902	591	1.37	85.4
DY	1053	702	1.58	81.2
CG_DESCENT	741	481	1.12	90.6
<b>AHNCG</b>	<b>683</b>	<b>441</b>	<b>1.03</b>	<b>93.7</b>

NF: gradient evaluations; NI: iterations; SR: success rate.

**Key findings:**

- AHNCG reduces gradient evaluations by **45%** vs. FR and **8%** vs. CG\_DESCENT
- Success rate improved by **+3.1 pp** over the next-best method
- Gains most pronounced on ill-conditioned problems ( $\kappa > 10^4$ ), where  $\theta_k$  correctly favours the PRP component

## METHOD

**Adaptive hybrid parameter:**

$$\beta_k^{\text{adaptive}} = \theta_k \beta_k^{\text{PRP}} + (1 - \theta_k) \min\{\beta_k^{\text{FR}}, \beta_k^{\text{HS}}\}$$

**Cosine-similarity weight:**

$$\theta_k = \frac{|g_{k+1}^\top g_k|}{\|g_{k+1}\| \|g_k\|} \in [0, 1]$$

$\theta_k \approx 0$ : gradients orthogonal  $\Rightarrow$  conservative FR–HS blend.

$\theta_k \approx 1$ : gradients aligned  $\Rightarrow$  aggressive PRP.

**Reinforced safeguard (novel):**

$$S_k = \begin{cases} \frac{(1 - c_2) \|g_{k+1}\|^2}{|g_{k+1}^\top d_k|} & g_{k+1}^\top d_k \neq 0, \\ +\infty & \text{otherwise.} \end{cases}$$

$$\beta_k \leftarrow \max\{0, \min(\beta_k^{\text{adaptive}}, \tau, S_k)\}$$

Directly bounds  $\beta_k |g_{k+1}^\top d_k| \leq (1 - c_2) \|g_{k+1}\|^2$ , guaranteeing the *exact* descent constant  $c_2$ .

## CONCLUSION

**Theoretical contributions:**

1. **Uniform sufficient descent** (Lemma 1):  $g_k^\top d_k \leq -c_2 \|g_k\|^2$  for all  $k \geq 0$ , proved by induction covering the degenerate case  $g_{k+1}^\top d_k = 0$ .
2. **Bounded directions** (Lemma 2):  $\|d_k\| \leq \gamma/(1 - \tau)$  for all  $k \geq 0$ .
3. **Strong global convergence** (Theorem 1):  $\lim_{k \rightarrow \infty} \|g_k\| = 0$  (stronger than the classical  $\liminf = 0$  from Zoutendijk alone).

**Proof sketch of Theorem 1:**

1. Zoutendijk condition:  $\sum_k \frac{(g_k^\top d_k)^2}{\|d_k\|^2} < \infty$
2. Lemma 1  $\Rightarrow (g_k^\top d_k)^2 \geq c_2^2 \|g_k\|^4$
3. Lemma 2  $\Rightarrow \sum_k \|g_k\|^4 < \infty$
4. Non-negative series convergence  $\Rightarrow \|g_k\|^4 \rightarrow 0 \Rightarrow \|g_k\| \rightarrow 0$   $\square$

**Future work:**

- Quasi-Newton corrections to  $\beta_k$
- Extension to constrained optimization
- Stochastic variants for large-scale machine learning

**Key references:**

- [1] Fletcher & Reeves, *Comput. J.*, 1964.
- [2] Polak & Ribière, *Rev. fr. inform.*, 1969.
- [3] Hestenes & Stiefel, *J. Res. NBS*, 1952.
- [4] Dai & Yuan, *SIAM J. Optim.*, 1999.
- [5] Hager & Zhang, *SIAM J. Optim.*, 2005.
- [6] Nocedal & Wright, *Numerical Optimization*, 2006.
- [7] Dolan & Moré, *Math. Program.*, 2002.