



1 Conference Proceedings Paper

2 Radiometric Calibration of RapidScat using GPM

3 Microwave Imager

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8 Published: date

9 Academic Editor: name

10 Abstract: Flying in a non-Sun-synchronous orbit, RapidScat is the first scatterometer capable of 11 measuring ocean vector winds over the full diurnal cycle, instead of observing a given location at a 12 fixed time of day. Non-Sun-synchronous orbit also enables the overlap with other satellite 13 instruments that have been flying in Sun-synchronous orbits. RapidScat covered the latitude range 14 between ± 51.6° and was operated on-board the International Space Station between September 15 2014 and August 2016. This paper describes the process that combines RapidScat's active and 16 passive modes, simultaneously measuring both the radar surface backscatter (active mode), and the 17 microwave emission determining the system noise temperature (passive mode). This work also 18 presents the radiometric (passive mode) cross-calibration using the GPM Microwave Imager (GMI) 19 as a reference to eliminate the measurement biases of brightness temperature between a pair of 20 radiometer channels that are operating at slightly different frequencies and incidence angles. Since 21 the RapidScat operates at 13.4 GHz and the closest GMI channel is 10.65 GHz, GMI brightness 22 temperatures were normalized before the calibration. Normalization was based on the radiative 23 transfer model (RTM) to yield an equivalent brightness temperature prior to direct comparison with 24 RapidScat. The seasonal and systematic biases between two radiometers have been calculated for 25 both polarizations as a function of geometry, atmospheric and ocean brightness temperature 26 models. Calculated biases may be used for measurement correction and for reprocessing of 27 geophysical retrievals.

28 Keywords: RapidScat; GPM Imager; radiometric calibration; brightness temperature.

29 1. Introduction

30 The RapidScat (RS) scatterometer was launched in Sept. 2014 installed on the Columbus module 31 of the International Space Station (ISS). It started making measurements over the Earth's surface in 32 Oct. 2014 and continued until Aug. 2016. The instrument operated in a manner similar to QuikScat, 33 a previous Ku-band scatterometer, as NASA had used the QuikScat's spare engineering unit to build 34 the follow-up RapidScat instrument [1-3]. RapidScat is a dual beam, conical-scanning, long-pulse 35 radar system. It combines active and passive Ku-band microwave measurements in dual receiver 36 channels. The backscatter is measured in a narrowband channel, and the brightness temperature (Tb) 37 in a wider-band channel, both from the ocean surface and through the intervening atmosphere 38 [4].The primary use of scatterometer measurements is wind vector retrieval over sea surface. In the 39 passive mode, the RapidScat measures the linearly polarized microwave emission at 13.4GHz 40 frequency quantified by Tb. The rotating antenna generated vertically (VV) and horizontally (HH) 41 polarized beams directed at the Earth's surface at incidence angles of approximately 56° and 49°, 42 respectively. The ground swath of the outer VV beam is approximately 1100km wide, while the 43 ground swath of the inner HH beam is approximately 900km wide. Regions between ± 58° latitude

44 are sampled uniformly over 24-hour periods, as opposed to previous Sun-synchronous scatterometer 45 orbits with fixed diurnal sampling flying over the same land areas at the same time of day [5-8]. This 46 paper presents the first radiometric calibration work of RapidScat brightness temperature 47 measurements over oceans. To accomplish the calibration, Radiative Transfer Model (RTM), 48 developed at the Central Florida Remote Sensing Laboratory (CRFSL) [9], was used to evaluate the 49 corresponding modeled brightness temperatures. The RTM uses the collocated environmental 50 parameters (surface truth) and given sensor parameters (incidence angle, frequency, and 51 polarization), to produce the simulated Tb. In addition, in comparison with the RTM model, GPM 52 Imager measurements are used for radiometer cross-calibration. To facilitate the cross-calibration, 53 the GMI brightness temperatures are translated to yield an equivalent Tb prior to direct comparison 54 with RapidScat using the RTM. The Tb differences were analyzed seasonally as a function of ocean

55 brightness temperature and atmospheric models.

56 2. Materials and Calibration Method

57 In this work, RapidScat data have been extracted from the Level 2A (L2A) and Level 2B (L2B). 58 The data products were generated by the Physical Oceanography Distributed Active Archive Center 59 (PODAAC) at the Jet Propulsion Laboratory [10]. Data products come in three versions, 1.1, 1.2, and 60 1.3, with 1.2 replacing 1.1 after 8/15/2015; version 1.3 is intended as a replacement and continuation 61 of the Version 1.1 and Version 1.2 data from 02/11/2016 [11]. For the Tb modeling, the surface truth 62 parameters were extracted from the Global Data Assimilation System (GDAS) data product. GDAS 63 global grids are updated every six hours at 0:00, 6:00, 12:00, and 18:00 UTC. Parameters listed in 64 GDAS file include temperature, surface pressure, humidity, cloud liquid water, sea surface 65 temperature, and wind vectors [12].

66 The goal of the radiatiative transfer model (RTM) is to calculate the brightness temperature at 67 the defined operating frequency and incidence angle. The RTM is used in this work to generate Tb at 68 13.4 GHz; then, global measured and modeled RapidScat Tb's can be compared for both 69 polarizations. The environmental parameters of the ocean and atmosphere were prepared for the 70 input to the RTM. The most important characteristic of the RTM is that it accurately captures the 71 dynamics of the ocean Tb and environmental parameters. The three main RTM components that 72 contribute to the Tb captured by a space-borne sensor are the apparent brightness temperature from 73 radiometer measurements, the ocean surface brightness temperature, and the ocean surface which 74 reflects the sky brightness with some loss. This is an incoherent summation from the atmosphere and 75 surface [4, 9].

Examples of RapidScat and GMI orbits mapped over the globe are illustrated in Fig. 1. It shows a wide RapidScat swath in red, and the GMI orbit in blue. The wide RapidScat swath in Sunasynchronous orbit allows collocation at different latitudes. For each collocated (RapidScat / GMI) data, there must be corresponding GDAS parameters within a ± 60 minute window. This temporal criterion eliminates about 2/3 or all data for which GDAS reference may not be valid (4 GDAS daily files spanning total 8-hour window to collocate with satellites).

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Figure 1. RapidScat / GPM Imager collocations.

85 The collocated (RS/GMI) brightness temperatures over a two-year period have a wide 86 geographic coverage for ascending and descending passes. To ensure high quality 87 calibration/validation, this data set was spatially selected within 1° latitude x longitude boxes, using 88 a conservative land, rain, and a heavy cloud mask. These boxes were quality controlled and edited 89 to remove non-homogenous ocean scenes and/or transient environmental conditions. Rain flag and 90 rain impact from L2B were used to remove any 1° box with a rain rate higher than zero, and when 91 the GDAS indicated high water vapor (> 60 mm). The final valid data set now consists of the 92 environmental parameters (GDAS) with incidence angle and measured vertical and horizontal Tbs 93 (from L2A). Next, the RapidScat brightness temperature has been compared to the GMI. The purpose 94 of this technique was to find a radiometric calibration bias from one radiometer to another, and thus 95 to reduce the relative biases among the sensors [13].

96 The GMI is a non-sun-synchronous, dual-polarization, conical-scanning, multi-channel (ranging 97 from 10 to 183 GHz) radiometer, and it makes calibrated measurements at different wavelengths and 98 polarizations [14]. For the Imager, the two lowest frequency channels at 10.65 GHz and 18.7 GHz 99 bracket the RapidScat at 13.4 GHz; however, the incidence angles do not match. The GMI incidence 100 angle is 52.8° for all channels; however, for RapidScat, the inner (H-pol) beam is 46°, and the outer 101 (V-pol) beam is 54°. Thus, GMI Tbs are translated to yield an equivalent Tb prior to direct comparison 102 with RapidScat [15, 16]. The radiative transfer model is used to calculate the equivalent RS Tbs from 103 GMI channels (10.65 and 18.7 GHz), to produce the equivalent 13.4 GHz at the corresponding 104 RapidScat incidence angles. This process involved using a spectral ratio (S_r) parameter for both 105 polarizations calculated as a function of water vapor, cloud liquid water, and sea surface 106 temperature, which is defined by Equation 1:

107 108

$$S_r(wv, clw, sst) = \frac{RS_{rtm} 13.4 - GMI_{rtm} 10.65}{GMI_{rtm} 18.7 - GMI_{rtm} 10.65} ,$$
(1)

109

110Where RS_{rtm} 13.4, GMI_{rtm} 10.65, and GMI_{rtm} 18.7 are the modeled brightness temperatures for RS and111GMI, respectively [17, 18]. Using this ratio, the GMI brightness temperatures (10.65 and 18.7 GHz)112were translated to the RapidScat equivalent Tb (13.4 GHz) as shown in Equation 2:

113 114

115

(3)

116 Where $Tb \, \text{GMI}_{10.65}$, and $Tb \, \text{GMI}_{18.7}$ are the observed brightness temperatures. By having the 117 equivalent 13.4 GHz Tb's (TB GMI eqv), the difference between the observed RapidScat and the 118 equivalent GMI Tb's can be calculated by the Equation 3. Figure 2 summarizes the calibration 119 procedure in a block diagram.



136 3. Results

137 This section presents RapidScat/GMI Tb differences in arbitrary selected periods between 138 January 2015 and August 2016. To assess the Tb difference affected by each parameter, geometry and 139 environmental factors were precisely examined. In each of the processed data sets overall agreement 140 between both polarizations is observed. Figure 3 summarizes the Tb differences as a function of wind 141 speed in July 2015, relative wind direction in Feb. 2015, water vapor in June 2015, and cloud liquid 142 water in Sept. 2015. In addition to the atmospheric and ocean brightness temperature models, latitude 143 dependency was also investigated, as shown for July 2015. The horizontal axis represents the latitude 144 over the oceans from 55° latitude-south to 55° north (collocation region). The second and bottom 145 windows present the average RapidScat/GMI Tb differences separated in horizontal (blue line) and vertical (red line) polarizations.

146 147







Figure 3. Tb differences/biases as a function of latitude (top), Tb differences as a function of wind speed, relative wind direction (middle), and water vapor, and cloud liquid water (bottom).

153 4. Discussion

To present latitude dependency, averages over longitude, known as *zonal averages*, were performed to form a latitude series (to reduce the Tb measurement standard deviation). The top panel shows the averaged Tb differences of RapidScat/GMI (left), while the right panel presents the RapidScat Tb biases for both beams (Single Difference (SD): Tb measured – Tb modeled). It is noticeable that the highest differences were recorded in the same region between -20° to 20° latitude for both polarizations, as shown in the shaded area.

160 To evaluate RapidScat/GMI differences as a function of latitude, Tb difference dependence on 161 wind speed (left) and relative wind direction (right) was investigated for both beams and presented 162 in the second row. The difference variation changes in most circumstances are within ± 3K; however, 163 there is an exception, especially for wind speeds above 10 m/s where the Tb difference became higher. 164 Moreover, the right panel captures the average Tb differences as a function of the relative wind 165 direction. Differences at both polarizations follow the same pattern, and all the radiometric measured 166 data in 2015 shows good overall average agreement in both inner and outer beams, with the red and 167 blue lines presenting the averaged Tb differences in inner and outer beam, respectively.

The other environmental factor that was examined is the water vapor. The presence of water vapor in the atmosphere causes an increase in the brightness temperatures measured by microwave instruments. The bottom panel (left) illustrates an example for June 2015. The examined periods show a good agreement between the inner and the outer beam, but the Tb difference changes behavior from positive to negative when the water vapor exceeds 25 mm in both polarizations. Additionally, an analysis of the Tb differences versus the cloud liquid water (CLW) was examined. The plot on the

174 right shows the Tb differences mostly within \pm 2K, except for the CLW higher than 0.05 mm for both 175 beams.

176 5. Conclusions

177 This paper describes the RapidScat's passive mode with radiometer measurements to obtain the 178 brightness temperature simultaneously with primary active mode collecting normalized radar cross 179 section measurements. This work presents differences between RapidScat and the GPM Imager 180 measured Tbs as a function of the main RTM environmental inputs. Wind Speed, relative wind 181 direction, water vapor, and cloud liquid water are four major factors that affect microwave apparent 182 brightness temperatures. To understand their contribution to the RapidScat Tb bias, those 183 environmental factors were examined. The trends of the Tb deviation could be studied by this method 184 to assess the Tb bias affected by each parameter.

Results obtained from two years of observations indicate that most of the measured data in 2015 show good overall average agreement. Also, it can be concluded that RapidScat brightness temperature is a reliable source of data and it satisfies the accuracy requirements, despite Tb not being RapidScat's primary data product. Data used in the validation were collected from the entire RapidScat's mission. Further analysis of the RapidScat measurement set may help estimate relative validity and stability of other scatterometers/radiometers.

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Acknowledgments: This research was performed under the grant NNX15AT70G from the NASA Headquarters.
 Both L2A and L2B RapidScat data sets were provided by the NASA Physical Oceanography Distributed Active
 Archive Center (PODAAC) at the Jet Propulsion Laboratory (https://podaac.jpl.nasa.gov/). The authors also wish
 to acknowledge the collaboration with Prof. W. Linwood Jones at Central Florida Remote Sensing Laboratory,
 University of Central Florida.

Author Contributions: This research was designed and guided by Dr. Josko Zec. Ali Al-Sabbagh and Ruaa
 Alsabah performed, analyzed, and discussed the research data. All authors helped in improving this paper.

199 Conflicts of Interest: The authors declare no conflict of interest.

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