# Quickest Transshipment in an Evacuation Network Topology

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### Outline

- Evacuation optimization
- Earliest arrival transshipment in an integrated network
- Integrated evavcuation network
- Quickest transsipment in an integrated prioritized network References

#### Evacuation planning problems

Auto **Transit** Pedestrian Micro Macro Meso Fluid dynamics **Evacuation** DE/MP planning Simulations problems **Networks** Flow-max Time-min Flow-max/ Time-min Continuous Discrete

#### Bus-based evacuation planning problem

Minimize  $\mathcal{T}_{\mathsf{max}}$ 

such that 
$$\mathcal{T}_{\text{max}} \geq \tau_{di} x_{ij}^{b1} + \sum_{close} \tau_{to}^{br} + \sum_{close} \tau_{back}^{br} \ \forall b \in [B]$$
 (2)

$$\tau_{to}^{br} = \sum_{i \in [Y]} \sum_{j \in [Z]} \tau_{ij} x_{ij}^{br} \, \forall b \in [B], r \in [R]$$

$$(3)$$

$$\tau_{back}^{br} \geq \tau_{ij} \left[ \sum_{k \in [Y]} x_{kj}^{br} + \sum_{l \in [Z]} x_{il}^{b,r+1} - 1 \right], \ \forall b \in [B], r \in [R-1]$$
 (4)

$$\sum_{i \in [Y]} \sum_{j \in [Z]} x_{ij}^{br} \leq 1 \,\forall b \in [B], r \in [R]$$

$$\tag{5}$$

$$\sum_{i \in [Y]} \sum_{j \in [Z]} x_{ij}^{br} \geq \sum_{i \in [Y]} \sum_{j \in [Z]} x_{ij}^{b,r+1} \ \forall b \in [B], r \in [R-1]$$
 (6)

$$\sum_{j \in [Z]} \sum_{b \in [B]} \sum_{r \in [R]} x_{ij}^{br} \geq \alpha_i \ \forall i \in [Y]$$

$$(7)$$

$$\sum_{i \in [Y]} \sum_{b \in [B]} \sum_{r \in [R]} x_{ij}^{br} \leq \beta_j \,\forall j \in [Z]$$
(8)

$$x_{ij}^{br} \in \{0,1\} \ \forall \tau_{to}^{br}, \tau_{back}^{br}, \mathcal{T}_{\mathsf{max}} \in \mathbb{R}$$
 (9)

(1)

## An integrated network topology

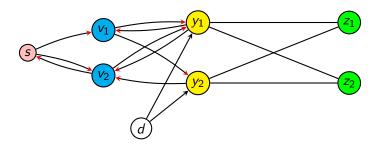


Figure 1: An integrated network topology.

$$\mathcal{N} = \mathcal{N}_1 \cup \mathcal{N}_2$$
  
$$\mathcal{N}_1 = (s, V, A, u_a, \tau_a, Y)$$
  
$$\mathcal{N}_2 = (d, Y, E, \tau_e, Z)$$

#### Earliest arrivals of evacuees

$$\sum_{\sigma=\tau_a}^{T} \sum_{a \in A_i^{in}} f(a, \sigma - \tau_a) - \sum_{\sigma=0}^{T} \sum_{a \in A_i^{out}} f(a, \sigma) = 0, \forall i \notin \{s, y\}$$
 (10)

$$\sum_{\sigma=\tau_{a}}^{\theta} \sum_{a \in \Delta^{in}} f(a, \sigma - \tau_{a}) - \sum_{\sigma=0}^{\theta} \sum_{a \in \Delta^{out}} f(a, \sigma) \geq 0, \forall i \notin \{s, y\}, \theta \in \mathbf{T}$$
 (11)

$$0 \leq f(a,\theta) \leq u_a \qquad \forall a \in A, \ \theta \in \mathbf{T}$$
 (12)

$$(\nu_f, \theta) = \sum_{\sigma=0}^{\theta} \sum_{a \in A_c^{out}} f(a, \sigma) = \sum_{\sigma=\tau_a}^{\theta} \sum_{a \in A_c^{in}} f(a, \sigma - \tau_a)$$
 (13)

The total flow released from s that reached to Y up to  $\theta' \in \mathbb{Z}_+$ , with  $\tau_a = 0$ , is

$$|\nu_f|_{\theta'} = \sum_{\theta=1}^{\theta'} |\nu(Y,\theta)|. \tag{14}$$

For the given time bound T, the value in (14) is denoted by  $|\nu_f| = \sum_{\theta=1}^{T} |\nu(Y, \theta)|$ . See in [3].

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### Earliest arrival evacuee problem

Given  $\mathcal{N}_1 = (s, V, A, u_a, \tau_a, Y)$ . The earliest arrival evacuee problem is to find the earliest arrival of evacuees at the pickup locations Y with partial arc reversal capability.

Formulation of the transformed network: Reversal arc for a = (i, j) is a' = (j, i). The transformed network of  $\mathcal{N}_1$  consists of the modified arc capacities and constant transit times as,

$$u_{\tilde{a}} = u_a + u_{a'} \text{ and } \tau_{\tilde{a}} = \begin{cases} \tau_a & \text{if } a \in A \\ \tau_{a'} & \text{otherwise} \end{cases}$$
 (15)

where an edge  $\tilde{a} \in \tilde{A}$  in a transformed network, if  $a \vee a' \in A$  in  $\mathcal{N}_1$ . The remaining graph structure and data are unaltered. In the transformed network  $\mathcal{N}_1$ , we have solved the earliest arrival evacuee problem with  $\tau_a = 0$  on each arc as in [10] and saved all unused arc capacity as in [9].

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### **Algorithm 1:** Earliest arrival evacuee algorithm

- **Input**:  $\mathcal{N}_1 = (s, V, A, u_a, \tau_a, Y)$  with  $\tau_a = 0$  for each  $a \in A$ .
- 1 Construct a transformed network  $\mathcal{N}_1$  as in Equation (15).
- 2 Determine the maximum number of evacuees at every possible time instance at each Y from s as in [10].
- 3 For each  $\theta \in \mathbf{T}$  and reverse  $a' \in A$  up to capacity  $c_a u_a$  if and only if  $c_a > u_a$ ,  $u_a$  replaced by 0 whenever  $a \notin A$ , in  $\mathcal{N}_1$ , where  $c_a$  denotes the static s y flow value in each  $a \in A$  for such sub-network.
- 4 For each  $\theta \in \mathbf{T}$  and  $a \in A$ , if a is reversed,  $\kappa_a = u_{\tilde{a}} c_{a'}$  and  $\kappa_{a'} = 0$ . If neither a nor a' is reversed,  $\kappa_a = u_a c_a$ , where  $\kappa_a$  is saved capacity of a, [8], [9].

**Result:** Earliest arrival of evacuees at Y with  $\tau_a = 0$  for each  $a \in A$ .

#### Theorem 1

The earliest arrival evacue problem with partial arc reversal capability follows the principle of temporally repeated flow at  $\tau_a = 0$  and is polynomial-time solvable.

#### Sketch of proof:

- Steps 1, 3, and 4 of Algorithm 1 are solved in linear time, its time complexity is dominated by the time complexity of Step 2.
- Earliest arrival transshipment computation to Y with  $\tau_a=0$  on each arc is solved in polynomial-time in Step 2, [10].
- It follows the principle of temporally repeated flow at  $\tau_a = 0$ , [7].

## Transit-vehicle assignment problem

Let  $\mathcal{N}=(s,d,V,Y,A,E,u_a,\tau_a,\tau_e,Z)$ , provided with supplies and demands. The transit-vehicle assignment problem is to assign the vehicles for evacuees transshipment with minimum clearance time.

Integrated model for the embedded network: Let  $\omega_i$  be the waiting at  $y_i \in Y$  with the effective waiting,  $\Omega = \max\{\omega_i, \tau_{di}\}$  for  $\mathscr{N}$ , then it can be reformulated as,

minimize 
$$\mathcal{T}_{\text{max}}$$
 (16)

such that 
$$\mathcal{T}_{\text{max}} \geq \Omega + \sum_{r \in [R]} \tau_{to}^{br} + \sum_{r \in [R]} \tau_{back}^{br} \ \forall b \in [B]$$
 (17)

with the constraints 
$$(3-9)$$
 (18)

**Algorithm 2:** Transit-vehicle assignment algorithm for minimum clearance time.

**Input**: An embedded network  $\mathcal{N} = (s, d, V, Y, A, E, u_a, \tau_a, \tau_e, Z)$ .

- 1 In  $\mathcal{N}_1 = (s, V, A, u_a, \tau_a, Y)$ , determine the earliest arrival of evacuees for  $\tau_a = 0$  at different Y from s, by using Algorithm 1.
- 2 Assign the transit-vehicles from d as guided by the dominant assignment approach as in [1] to  $\mathcal{N}_2 = (d, Y, E, \tau_e, Z)$  for the supplies provided by Step 1, [4].
- 3 Stop, if all the supplies at each of Y are fulfilled, respecting the capacity constraints of Z.
- 4 Otherwise, return to Step 2.
  - **Result:** Transit-vehicle assignment with minimum clearance time:  $s \rightarrow Z$ .

#### Example 2

#### Integrated approach in ${\mathscr N}$

- |s| = +12,  $|y_1| = \mp 8$ ,  $|y_2| = \mp 4$ ,  $|z_1| = -6$ ,  $|z_2| = -10$ .
- $\begin{array}{ccc} \bullet & s \rightarrow v_1 \rightarrow y_1, \\ s \rightarrow v_2 \rightarrow y_1, \\ s \rightarrow v_1 \rightarrow v_2. \end{array}$
- |v(f)| = 1, initially, temporally repeated.
- $|v_f|_{(y_1,y_2)} = (8,4), T=4.$
- If arc reversal, the same is at T=2.
- For |B| = 1,  $\mathcal{T}_{max} = 41$  and 39, respectively.
- For  $|B| \ge 12$ ,  $\mathcal{T}_{max} = 7$  and 5, respectively.

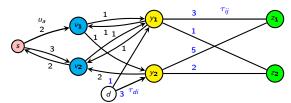


Figure 2: An instance of an integrated network  ${\mathscr N}$ 

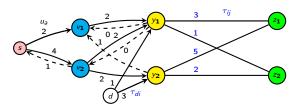


Figure 3:  $\mathcal N$  with partial arc reversal

## An integrated prioritized evacuation network

- A flow value is said to be lexicographic if it is compared according to the rank of the terminals for a prioritized network.
- Let  $\mathcal{N} = (S, V, A, u_a, \tau_a, Z)$  be a prioritized network with priority  $t_1, t_2, \dots, t_n$ ;  $t_i \in S \cup Z$ . Let

$$|f|_t := \left\{ egin{array}{ll} \sum_{a \in A_t^+} f_a, & t \in S ext{ is a source} \\ \sum_{a \in A_t^-} f_a, & t \in Z ext{ is a sink} \end{array} 
ight.$$

be the out/in flow value from/in the source/sink, respectively.

- For  $f^1$ ,  $f^2$  be the terminal respecting flows, then  $f^1 \ge_L f^2$  if  $\exists I \in \{0, 1, \cdots, k-1\} : \forall i \in \{1, 2, \cdots, l\} : |f^1|_{t_i} = |f^2|_{t_i} \land |f^1|_{t_{l+1}} > |f^2|_{t_{l+1}}$  or  $\forall i \in \{1, 2, \cdots, k\} : |f^1|_{t_i} = |f^2|_{t_i}$ .
- The maximum flow respecting the rank of the terminals is the lex-max.

# Quickest partial arc reversal transshipment problem

Given  $\mathcal{N}_1 = (S, V, A, u_a, \tau_a, Y)$  with supplies at S, demands at Y. The quickest partial arc reversal transshipment problem is to find the quickest arrival of evacuees at Y with partial arc reversals capability.

Algorithm 3: Quickest partial arc reversal transshipment algorithm.

**Input**: Let  $\mathcal{N}_1 = (S, V, A, u_a, \tau_a, Y)$ , with the supply and demand.

- 1 Construct a transformed dynamic sub-network  $\overline{\mathcal{N}}_1$  as in Equation (15).
- 2 Solve the quickest transshipment problem in  $\overline{\mathcal{N}}_1$  of Step 1, [5].
- 3 For each  $\theta \in \mathbf{T}$  and reverse  $a' \in A$  up to capacity  $c_a u_a$  iff  $c_a > u_a$ ,  $u_a$  replaced by 0 whenever  $a \notin A$ , in  $\mathcal{N}_1$ , where  $c_a$  denotes the static s y flow value in each  $a \in A$  for such sub-network.
- 4 For each  $\theta \in \mathbf{T}$  and  $a \in A$ , if a is reversed,  $\kappa_a = u_{\overline{a}} c_{a'}$  and  $\kappa_{a'} = 0$ . If neither a nor a' is reversed,  $\kappa_a = u_a c_a$ , where  $\kappa_a$  is the saved capacity of a, [8].

**Output:** The quickest arrival of evacuees at Y in  $\mathcal{N}_1$  with partial arc reversal capability.

#### Theorem 3

The quickest partial arc reversal transshipment problem can be computed in polynomial-time complexity via  $\delta$  minimum cost flow (MCF) computations in  $O(\delta m \log n(m + n \log n))$  on the network with n nodes and m arcs.

#### Sketch of proof:

- Steps 1, 3, and 4 related to the arc reversal capability as in Algorithm 3 are solved in linear time.
- The time complexity is dominated by the time complexity of the computation of the quickest evacuee arrival at Y in  $\mathcal{N}_1$  and is solved in polynomial-time with  $\delta$  MCF computations in  $O(\delta$ MCF(m,n), where MCF $(m,n) = O(m \log n(m+n \log n))$  on a network having n nodes and m arcs as in [6].

# Assignment of vehicles in an embedding

- Let  $\alpha_1$  be the No. of evacuees arrived at the highest pickup demand.
- Assignment begins only after  $\alpha_1 \geq Q$ , for uniform bus capacity Q.
- Adjusted demands  $\alpha'(y_k)$  to be the integral multiple of busloads by using the following demand adjustment principle, [2],

$$\alpha'(y_k) = \left\lfloor \frac{\alpha(y_k) + \sum_{q=1}^{k-1} [\alpha(y_q) - \alpha'(y_q)]}{Q} \right\rfloor . Q \ \forall k \in 1, 2, \dots, n-1 \quad (19)$$

$$\alpha'(y_k) = \alpha(y_k) + \sum_{q=1}^{k-1} [\alpha(y_q) - \alpha'(y_q)], \text{ for the last pickup location}$$
 (20)

# Assignment of transit-vehicles in a prioritized embedding

### Integrated evacuation planning problem in a prioritized embedding

Given a prioritized network  $\mathcal{N}=(s,d,V,Y,A,E,u_a,\tau_a,\tau_e,Z)$ , having supplies and demands at s and Z, respectively. The integrated evacuation planning problem in a prioritized embedding is to assign the vehicles for evacuees transshipment with minimum clearance time.

Integrated model for the prioritized embedding: For  $\Psi$  be the effective waiting in such embedding, it can be reformulated as:

minimize 
$$\mathcal{T}_{\text{max}}$$
 (21)

such that 
$$\mathcal{T}_{\text{max}} \geq \Psi + \sum_{r \in [B]} \tau_{to}^{br} + \sum_{r \in [B]} \tau_{back}^{br} \ \forall b \in [B]$$
 (22)

with the constraints 
$$(3-9)$$
 (23)

Constraint (22) needs  $\mathcal{T}_{max}$  to be greater than or equal to the maximal travel cost incurred by all buses and is to be minimized in (21). Other constraints are the same as in Equations (3-9).

Quickest Transshipment

**Algorithm 4:** Integrated evacuation planning algorithm in a prioritized embedding.

**Input** :  $\mathcal{N} = (S, V, A, u_a, \tau_a, Y, d, u_e, \tau_e, Z)$ , with given supply, demand.

- 1 Consider  $\mathcal{N}_1 = (G, u_a, S, \tau_a, Y)$ , having their pickup locations be Y.
- 2 Construct a priority ordering of Y, the highest priority to the nearest.
- 3 Determine the arrival of evacuees at Y of  $\mathcal{N}_1$  from S using Algorithm 3.
- 4 Assign transit-buses from d to Y in  $\mathcal{N}_2 = (d, Y, u_e, \tau_e, Z)$  for the supplies of Step 3, as guided by the dominant assignment approach, on the first-come-first-serve basis, provided by [4].
- 5 Begin the assignment with  $\alpha_1 \geq Q$ ,  $\forall \alpha'(y_k)$  provided by Equation (19).
- **6** Stop, if all  $\alpha'(y_k)$  be fulfilled, respecting Equation (20) the  $\nu(Z)$ .
- 7 Otherwise, return to Step 4.

**Output:** Transshipment of evacuees to Z in minimum clearance time.

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## Suggestions are welcome



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