

1 Article

2 **A novel strategy for tall building optimization via combination**
3 **of AGA and machine learning methods**4 **Mohammad Sadegh Es-haghi¹, Mohammad Sarcheshmehpour^{2,*}**5 ¹ Department of Civil Engineering, K. N. Toosi University of Technology, Tehran, Iran.6 ² Department of Civil Engineering, Sharif University of Technology, Tehran, Iran.7 * Correspondence: sarcheshmehpour.m@gmail.com

8

9 **Abstract:** The optimum design of tall buildings, which have a proportionately huge quantity of
10 structural elements and a variety of design code constraints, is a very computationally expensive
11 process. In this paper, a novel strategy, with a combination of evolutionary algorithms and machine
12 learning methods is developed for achieving the optimal design of tall buildings. The most time-
13 consuming part is the analysis of tall buildings and the control of design code constraints requiring
14 long and frequent analyses. The main idea is to use machine learning methods for this purpose. In
15 this study, a practical methodology for the obtaining optimal design of tall building structures, re-
16 garding the constraints imposed by typical building codes, is introduced. The optimization process
17 will be performed by a novel evolutionary algorithm, named asymmetric genetic algorithm (AGA),
18 and in each iteration that requires checking the constraints for a large number of different structural
19 states, machine learning methods, including MLP, GMDH and ANFIS-PSO are facilitators. More
20 specifically, MLP ($R^2 = 0.988$), has performed better than GMDH ($R^2 = 0.961$) and ANFIS-PSO ($R^2 =$
21 0.953). By coupling ETABS and MATLAB software, various combinations of sections for structural
22 elements are assigned and analyzed automatically, thus creating a database for training neural net-
23 works. The applicability of the suggested procedure is described through the determination of the
24 optimal seismic design for a 40-story framed tube building. Results designate that the present
25 method not only supports the precision of the methodology but also remarkably diminishes the
26 computational time and memory needed in comparison with the existing classical methods. More
27 importantly, the optimization process time is also significantly decreased.

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1. Introduction

In recent years, the demand for the optimal candidate of tall building structures has grown significantly due to financial issues. On the other hand, the dependable design of such structures brings many difficulties for an engineer because of the significant number of structural members and also the strict design constraints imposed by codes. This makes the conventional design provided by engineers not necessarily economical. This highlights the significance of optimization tools in the design process of these structures to save on construction costs [1-4]. Many of the studies in the field of tubular structures deal with the modeling of a tall building as a huge cantilever box beam [5-7]. The recent advances in high-performance computers made possible the precise analysis of the whole frame of the high-rise building during the optimization process. Chan et al. [8] introduced an iterative procedure based on drift, strength, and fabrication constraints. The effects of various parameters on the tube action of a reinforced concrete 55-story hotel building



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were investigated by Shin et al [9]. Some researchers proposed techniques for the minimization of the weight of high-rise buildings subject to wind loads [10, 11]. Aldwaik and Adeli [12] conducted a review of the optimization of high-rise buildings with either tubular or other structural systems.

The above-mentioned studies mostly consider fixed patterns of loads; however, another line of thought deals exclusively with the seismic loads which lead to more cumbersome behavior in the structure. In this respect, the design codes prescribe additional strict limitations on the design of structures subject to seismic loads. During the past decades, many researchers focused on the seismic assessment of the structures [13, 14]. More specifically, many studies incorporated seismic considerations into optimization problems [15-17]. Moghaddam and Hajirasouliha [18] introduced an optimization technique to reach the uniform deformation of members in two-dimensional (2D) tall shear buildings subject to seismic excitation. Furthermore, Ganjavi et al. [19] investigated the best distribution of seismic lateral loads to achieve uniform damage distribution in 2D shear buildings considering soil-structure interaction (SSI). Recently, many researchers employed optimization methods to reach the desired seismic performance objectives at various seismic hazard levels in 2D low-rise and mid-rise steel frames [20, 21] and also in 2D reinforced concrete frames [22]. Recently, with the aid of gradient-based optimization algorithms, Sarcheshmehpour et al. proposed practical methodologies for optimal seismic design of steel framed tube tall buildings based on conventional building codes [23] as well as life cycle costs [24].

Notwithstanding ample researches on the optimization problems of tall buildings, using soft computing methods in optimal seismic design of tall buildings has been scarce in the literature. In the current research, a practical methodology with logical computational demand to achieve the most beneficial possible design within the constructional aspects, by the combination of machine learning methods and evolutionary algorithms, has been proposed. First, the optimization problem considering all constraints is described. Then, by establishing the connection between MATLAB and ETABS software, a huge database, which has been used for training ANNs, is created. The methods of MLP, GMDH, and ANFIS-PSO have been investigated and the best one is selected for evaluating the constraints in the optimization process, which are based on the AGA algorithm. Finally, the result for a sample 40-story building has been presented. The structural analysis procedure for creating the database is conveyed based on the Iranian National Building Code (INBC) which is almost identical to ANSI/AISC 360-10 LRFD design guide [25].

2. Formulation of the optimization problem

In this section, the general formulation for seismic design optimization of high-rise buildings is presented. The structural design is performed according to the conventional load and resistance factor design (LRFD) approach:

Design for serviceability: Based on the Iranian Code of Practice for Seismic Resistant Design of Buildings (Standard No. 2800), the inter-story drift ratio (Δ_i) of different stories of the buildings more than five stories high, the following constraint shall be satisfied under design seismic forces:

$$C_d \Delta_i \leq 0.02, \quad (1)$$

In which C_d indicates the amplification factor accounting for the expected inelastic response.

- Design for Strength

According to the building code, the demand-capacity ratio defined in Eq. 2 shall be equal to or less than one for all load combinations, i.e.,

$$\frac{R_u}{\phi R_n} \leq 1, \quad (2)$$

where R_u represents the required strength under all LRFD load combinations and ϕR_n indicates the design strength of each structural element.

- Strong-column/weak-beam (SC/WB): For design of Special Moment Frames (SMFs), the moment ratio shall satisfy the following constraint at each beam-to-column connection:

$$\frac{\sum M_{pb}^*}{\sum M_{pc}^*} < 1, \quad (3)$$

Where $\sum M_{pb}^*$ represents the total flexural strength of all beams attached to the connection and $\sum M_{pc}^*$ indicates the total flexural strength of the columns with a reduction for the axial force.

- Practical limitations: from a practical perspective, the dimensions of columns in each story shall not be less than those in the upper stories. This constraint can be formulated as:

$$d_{j,i}^{col} \geq d_{j+1,i}^{col}, \quad b_{j,i}^{col} \geq b_{j+1,i}^{col}, \quad j = 1, 2, \dots, NS - 1; \quad i = 1, 2, \dots, NC, \quad (4)$$

In Eq. 4, $d_{j,i}^{col}$ and $b_{j,i}^{col}$ represent the depth and the width of the section of the i th column in the j th story, respectively. Furthermore, NC denotes the number of columns in each story and NS is the total number of stories.

In the current design optimization problem, the total weight of all beams and columns in the 3D steel tall building indicates the objective function and all the above-mentioned inequalities behave as the optimization constraints. In addition, the section properties of the structural elements are considered as the design variables. The resulting nonlinear constrained optimization problem is attacked by two basic approaches, in the current study. The first one is the metaheuristic optimization method, named AGA. The second one is using machine learning techniques for determining nonlinear inequality constraints instead of time-consuming analytical approaches. For the sake of convenience, the proposed procedure of the optimal seismic design is illustrated in Figure 1. A full description of the parameters available in Figure 1 can be found in [23].

3. Structural model

In this study, a 40-story framed tube building is considered as the case study to demonstrate the applicability of the proposed strategy. The 3D view and the typical floor plan of this building are shown in Figure 2. As seen, in both directions, the plan consists of nine bays, each with a length of 3 m. The gravitational columns (GC) and the corner columns (CC) of the perimeter tube have box sections. The sections of the rest of the columns (P1C and P2C) are I-shaped sections. As shown in Figure 2, there are two types of non-corner perimeter columns: P1C columns which are only connected to the perimeter beams from both sides, and P2C columns which are also connected to the pin-ended gravitational beams (GB). The spandrel beams (PB) are fixed-ended and have a length of 3 m. Moreover, both types of gravitational beams (GB and IGB) are pin-ended with a length of 9 m. As seen in Figure 2, IGB beams connect the gravitational columns together and GB beams connect the gravitational columns to the perimeter tube.

The case study is a residential building in which the first four stories are considered as parking lots. The gravitational beams (GB or IGB) are divided into two groups based on their position in either residential floors or parking lots. For practical design purposes, all spandrel beams and all columns are grouped every four stories. This leads to a considerable reduction in the number of design variables. It is worth mentioning that the index i in Figure 2 represents the group number of each structural section.

The building is considered to be located in Tehran with a very high level of seismicity. Furthermore, the soil beneath the building is consistent with Soil Type 2 of Iranian seismic code (in a depth of 30 m, the average shear wave velocity is between 375 m/s and 750 m/s). A fixed base is assumed at the ground level and all supports are fixed in the structural model.

By coupling ETABS [26] and MATLAB software, 7800 combinations of sections for structural elements are assigned and analyzed automatically, thus creating a database for training neural networks.

3.1. Sections decision variables

In this research, the sections properties indicating the decision variables are considered to be continuous. The number of design variables reduces appreciably by relating all dimensions of the section to its depth through rational equations. In this study, linear equations relating the dimensions of the sections to their depths are determined according to Euro-standard sections. For more details refer to [23, 24].

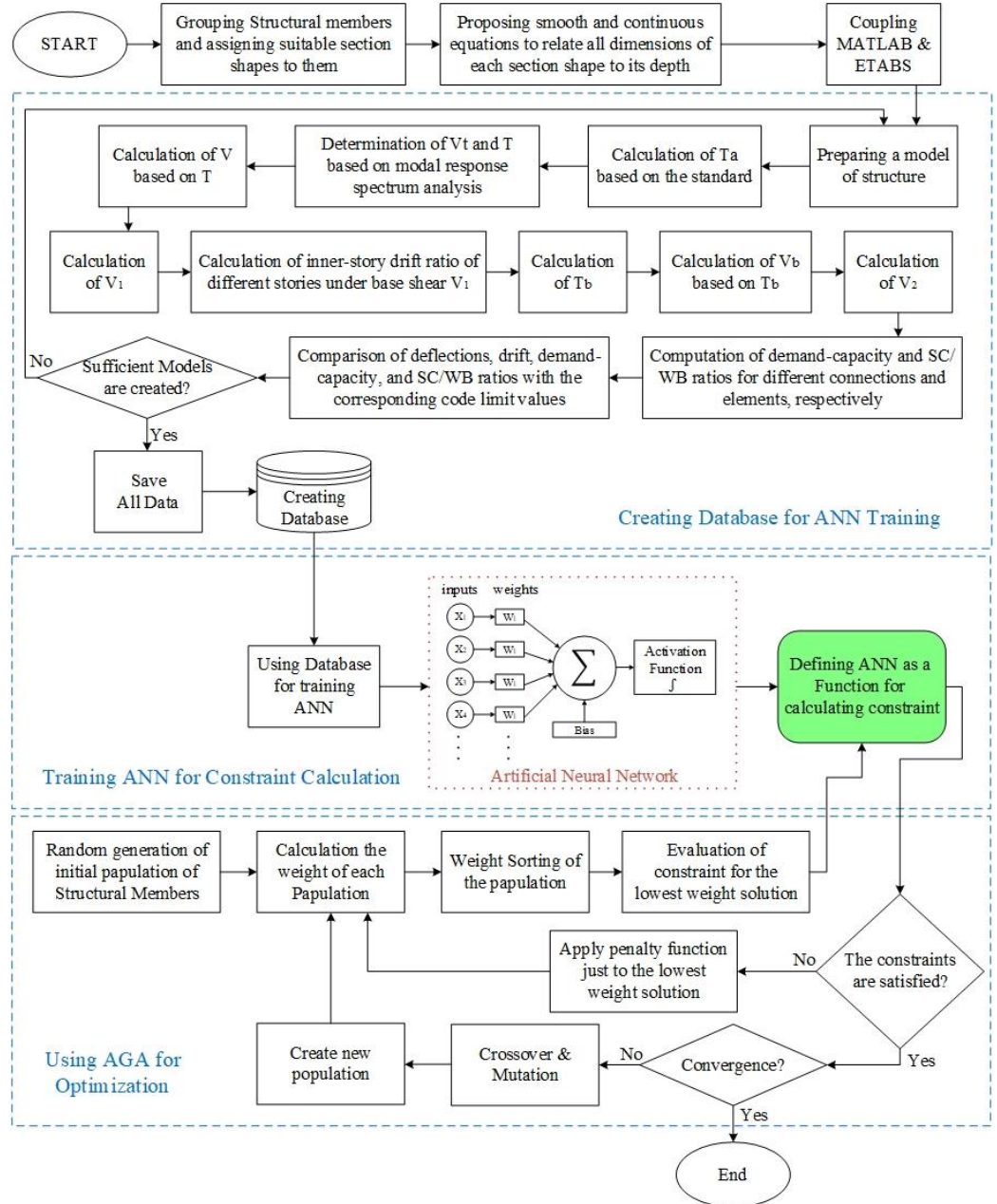


Fig. 1 The iterative procedure for the optimal structural seismic design

The above-mentioned relations for I-shape sections pertinent to the non-corner columns of the perimeter tube and beams are presented in Eq. 5 and 6, respectively.

$$b_f = d, \quad t_f = 0.055d + 0.35 \quad t_w = 0.015d + 0.6 \quad (5)$$

$$b_f = 0.35d + 3.3, \quad t_f = 0.026d + 0.33 \quad t_w = 0.016d + 0.25 \quad (6)$$

In Eqs. 5 and 6, d is the section depth, b_f denotes the flange width, t_f is the flange thickness, and t_w represents the web thickness.

As mentioned before, all the corner and gravitational columns have box shape sections. The equation relating the thickness (t) of the box section to its depth (d) is given as:

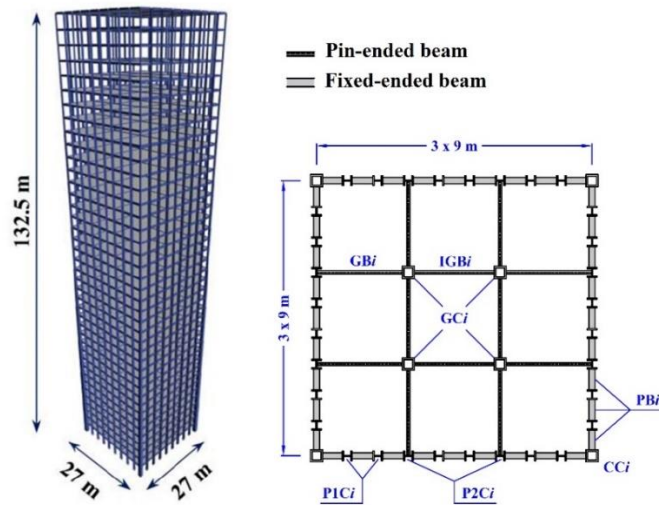
$$t = 0.06d \tag{7}$$


Fig. 2 The 3D and plan view of the 40-story framed tube building

4. Machine learning techniques for constraint evaluation

Recently, machine learning has become very popular in engineering application [27, 28]. In this study, three non-linear machine learning models, namely multi-layer perceptron (MLP) [29], group method of data handling (GMDH) [30], and combining adaptive-network-based fuzzy inference system and particle swarm optimization (ANFIS-PSO)[31] were employed to estimate structural constraints. These methods are examined and the best one is selected in optimization process as the function of constraint evaluation. For training ANNs, 7800 models were created. For instance, the effect of dataset size for estimation of one of constraints, design ratio of CC1, by MLP method, has been shown in Figure 3. As shown in this figure, the number of 6000 is sufficient for dataset size. Therefore, creating 7800 model is appropriate. By trying several different models for neural networks, their final structures are presented in Table 1.

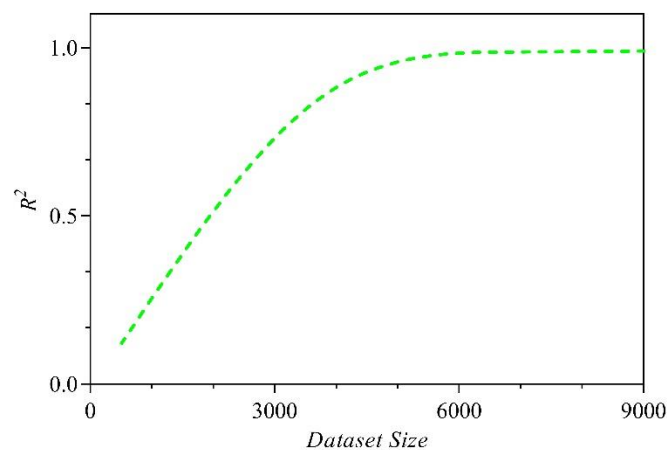


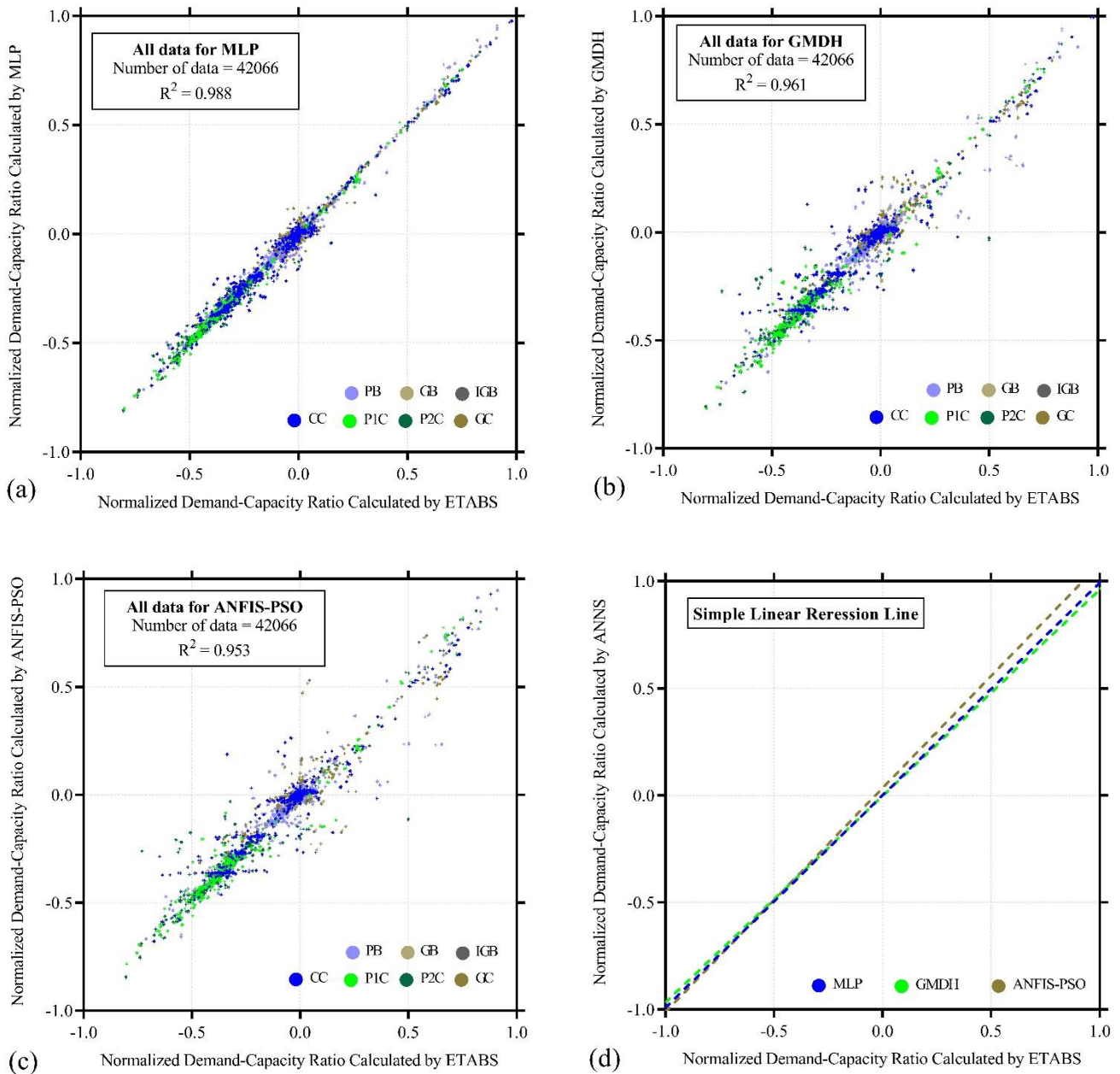
Fig. 3 The effect of dataset size of the performance of machine learning (MLP) method

In Figure 4, the performances of the three selected ML tools are compared. It can be seen that MLP is more accurate than GMDH and ANFIS-PSO in calculating the constraints and catching the structural response. Output provided by MLP is shown to be much less scattered than the others, and the linear interpolation of all the pairs of results is well

aligned with the (perfect fit) bisector of the quadrant. Therefore, for optimization process, MLP method is selected.

Table 1- The parameters of Machine Learning methods

ML Methods	Parametrs		
MLP	Number of Layers:	1	Training Percentage: 65 %
	Number of neurons:	20	Testing Percentage: 30 %
	Structure:	54-20-1 ANN	Validation Percentage: 5 %
GMDH	Maximum number of neurons in a layer: 30		
	Maximum number of layers:	6	Training percentage: 50 %
	Selection pressure:	0.2	Testing percentage: 50 %
ANFIS-PSO	Number of the iterations:	5000	Cognitive acceleration: 1
	Number of particles:	65	Social acceleration: 1.5
	Initial inertia weight:	0.8	Training percentage: 70 %
	Final inertia weight:	0.2	Testing percentage: 50 %



1
2 **Fig. 4** Performances of the ML algorithms: parity plots showing the ML output against the corresponding targets for: (a) MLP re-
3 garding all data; (b) GMDH regarding all data; (c) ANFIS-PSO regarding all data; (d) linear regression line for ML al algorithms.

4 **5. Results**

5 In this part, the details of the optimal designs and the seismic behavior of the 40-story
6 framed tube are presented. For optimization process the algorithms of AGA, which are
7 depicted in [2] is used. The AGA algorithm has some differences from the GA, the most
8 important of which are in the constraints evaluation strategy. In AGA, initial population
9 members are sorted by goal function, and, despite GA, just the constraints of the best
10 member are evaluated. If the best member satisfies the constraints, AGA does not evaluate
11 other members' constraints. If else, the penalty function is applied to the best one, and
12 then the population is sorted again, and the new best solution is evaluated by the con-
13 straints again. This procedure proceeds to achieve the lowest weight member that is sat-
14 isfied by whole constraints. After reaching this goal, AGA goes to the next level, as is

shown in the related part in Figure 1. As a result, evaluation of constraints is not done for whole members of the population in AGA. See [2] for more information. The hyperparameters of AGA were selected by trying different values of the number of generations, the population size, the crossover probability, and the mutation probability, which amount of them are 200, 50, 60, and 5 respectively.

The optimization of the 40-story building consists 54 decision variables. The sections' depths of the optimal designs associated with the 40-story building with both systems are given in Table 2. The inter-story drift ratios of different stories, SC/WB ratios, and demand-capacity ratios relevant to the optimal design of 40-story building as well as the corresponding code limits are depicted in Figure 5.

Table 2- The depth of columns sections in the optimal design of the building in (mm)

Element Name	Group Number									
	1	2	3	4	5	6	7	8	9	10
CC	1210	1118	983	853	724	598	475	401	340	273
P1C	593	593	581	569	553	533	511	480	433	357
P2C	605	599	583	566	544	517	493	468	428	358
GC	994	829	779	728	674	616	550	476	391	281
PB	577	635	637	631	615	585	563	539	495	423
GB	598	552
IGB	590	554

6. Conclusion

In the current work, the optimal seismic design of high-rise buildings, which is a large-scale optimization problem, drives to a time-consuming process, and needs huge computational demands, has been investigated. These problems are cast into the context of optimization with the combination of evolutionary algorithms and machine learning methods. AGA, as a novel evolutionary algorithm, has been employed for the optimization process. The algorithm converged to optimal design, whose specifications have been presented, with an initial population of 50 after 200 iterations. For constraint evaluation, three machine learning methods including MLP, GMDH, and ANFIS-PSO have been investigated and the best one, MLP with a coefficient of determination of 0.988, is selected. Therefore, the strategy mentioned in this paper can be used to achieve the minimum weight of the tall buildings along with meeting all practical and design code constraints. This strategy donates a methodical procedure for the reasonable comparison of different tall building designs.

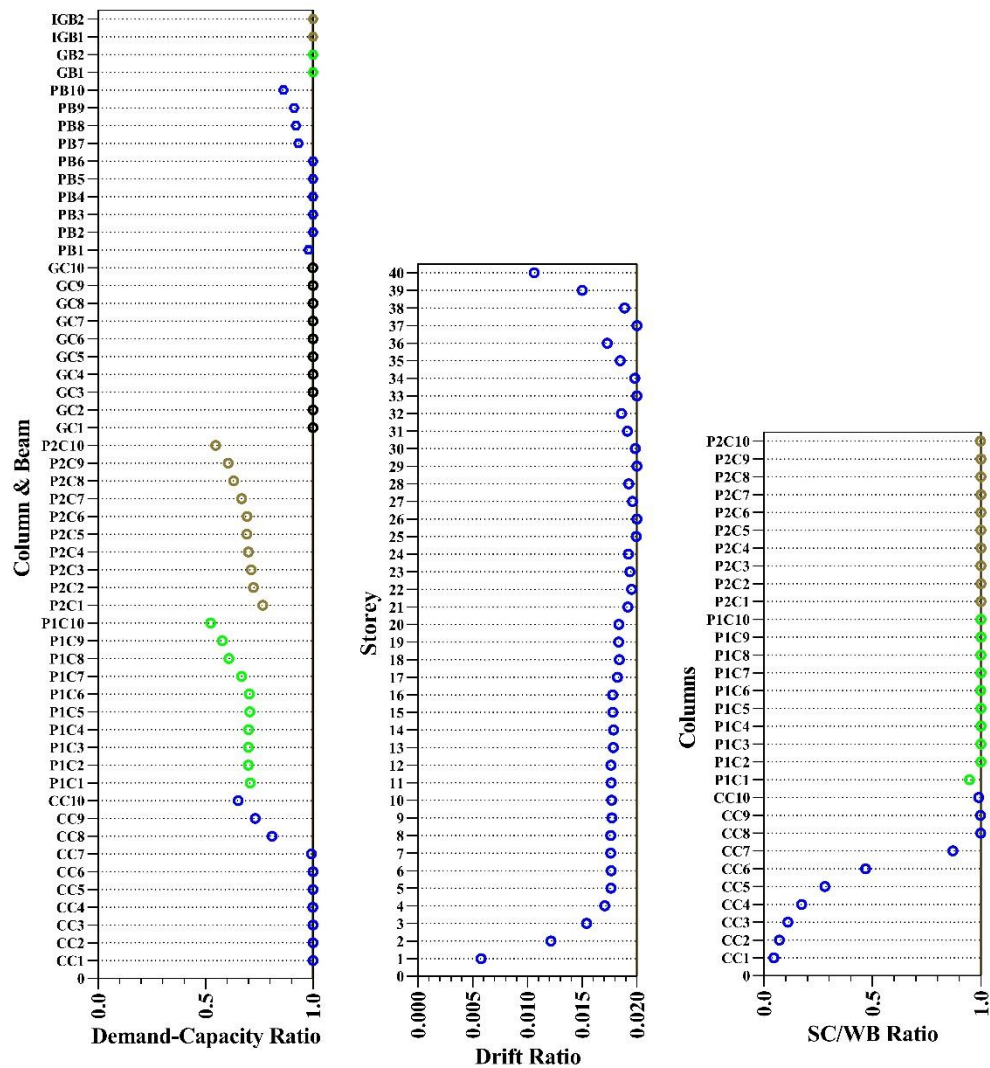


Fig. 5 Demand-capacity ratio, SC/WB ratio, and drift ratio for optimal candidate in 40-storey building

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