



1 Proceedings

# 2 Field of view enhancement of dynamic holographic displays 3 using algorithms, devices, and systems: A review

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8 **Abstract:** Holography is a prominent 3D display approach as it offers a realistic 3D display without  
9 the need for special glasses. Due to advancements in computation power and optoelectronic tech-  
10 nology, holographic displays have emerged as widely appreciated technology among other 3D dis-  
11 play technologies and have drawn a lot of research interest in recent years. The core of dynamic  
12 holographic displays is spatial light modulator (SLM) technology. However, owing to the limited  
13 resolution and large pixel size of SLMs, holographic displays suffer from certain bottlenecks such  
14 as limited field of view (FOV) and narrow viewing angle. To develop a holographic display at the  
15 commercial level, it is crucial to solve these problems. A variety of probable solutions to these chal-  
16 lenges may be found in the literature. In this review, we discuss the essence of these approaches.  
17 We study the important milestones of the various methodologies from three primary perspectives:  
18 algorithms, optical systems, and devices employed for FOV extension, and provide useful insights  
19 for future research.

20 **Keywords:** holographic displays; field of view; spatial light modulator

## 22 1. Introduction

23 In order to make their thoughts come to life, people want to visualize them. The  
24 methods through which thoughts and experiences are visualized, have evolved from art  
25 to photography, and more recently to 3-D displays with the advancements of science and  
26 technology. The four main types of 3-D displays are stereoscopic, auto-stereoscopic, vol-  
27 umetric, and holographic displays [1]. Holography has been recognized as the most suit-  
28 able method for displaying 3-D images that seem realistic. It has the ability to control cru-  
29 cial aspects of light, such as phase, which cannot be controlled by other methods [2]. Hol-  
ographic three-dimensional (3-D) displays, which can rebuild 3-D images with complete  
depth cues, have obtained a broad attention in last few decades for their potential appli-  
cations in a variety of industries, including the medical and military sectors [3]. Holo-  
graphic dynamic displays come into picture in order to display information at video rate.  
Since video-enabled holography needs a lot of pixels and data, implementing it is another  
difficult task. However, evolution in parallel computing approaches and inventions of  
optical modulators make the dynamic loading as well as dynamic display of holograms  
possible. To display the calculated digital holograms, spatial light modulators (SLM) are  
one of the widely used methods [4]. But field of view (FOV), space bandwidth product  
(SBP) of the hologram, and the display quality are all constrained by the size and pixel  
pitch of commercially available SLMs. As a result, the SBP of holographic displays utiliz-  
ing SLM is often several hundred times lower than that of static holographic media. It  
implies that for an SLM to display a hologram, either the hologram size or the viewing  
angle must be inadequate. To achieve a large sized, dynamic, full-color, holographic 3-D

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43

1 display, it is important to overcome these problems. So, in the past few years, there have  
2 been various attempts to overcome these barriers for realizing a commercially viable dy-  
3 namic holographic display technology.

4 In this review study, we take a look at some of the prominent methods that are pro-  
5 posed by different researchers to overcome the problems associated with limited FOV of  
6 holographic displays. This study is divided into three sections. In Section I, the FOV ex-  
7 pansion approaches based on algorithms used for CGH generation are discussed. The in-  
8 troduction and principle of various systems and devices employed in optical configura-  
9 tions are explained in Section II and Section III, respectively. The advantages and disad-  
10 vantages regarding each method are also explored from realization/employment perspec-  
11 tive. From this study, we investigate what more is required to have a holographic display  
12 with wide FOV in our hands.

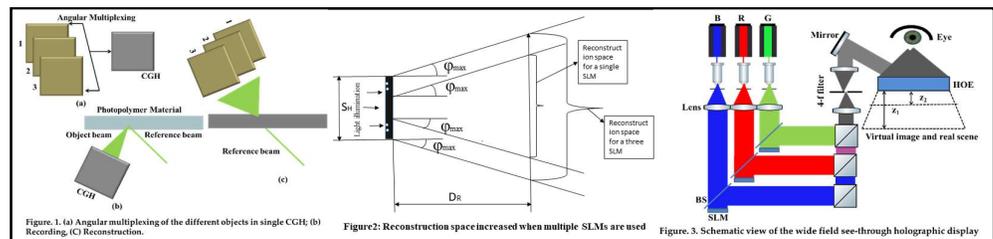
## 13 2. Algorithmic approaches for CGH generation

14 One of the most important aspects of holographic displays is computer generated  
15 hologram (CGH) generation. The objective of CGH is to model, calculate, and encode hol-  
16 ograms from 3D scenes. Algorithms are often separated into three paths from a computa-  
17 tional perspective, depending on the various solutions to the wave equation. The ap-  
18 proaches mentioned in literature include point source, polygon, spherical, and cylindrical  
19 [5]. The main objective of these algorithms is the real-time computation of complex holo-  
20 graphic patterns with huge information capacities for multi-color, wide-angle, and large-  
21 image systems. However, the spatial frequency and physical size of the CGH affect its  
22 information capacity and FOV. As a result, a significant amount of study on overcoming  
23 these limitations is reported. Generally, curved holograms such as computer-generated  
24 cylindrical holograms (CCGH) are thought to be the best for enlarging FOV as they offer  
25 the ability to view an image from any angle, enabling the reconstruction and 360° horizon-  
26 tal viewing of the object [6]. For a large compensation distance, it is impossible to correctly  
27 perform the point-to-point phase compensation between wavefront recording plane and  
28 CCGH. The approximate phase compensation (APC) technique has also this restriction  
29 condition. As a result, a full CCGH cannot be produced, and the FOV extension is con-  
30 strained, making it impossible to fully use the 360° FOV of the CCGH. This issue has been  
31 resolved by gapless splicing of multi-segment cylindrical holograms (mSCH) [7]. In this  
32 suggested approach, the limited condition of APC technique was initially examined. Fur-  
33 ther, the crucial compensation distance requirement was also mentioned. Three SCHs  
34 were taken into account as a group in this method and two by two were spliced together  
35 at a time. To obtain wide FOV display with above discussed method, curved display  
36 screen and flexible display materials are required. It is often convenient to employ LCoS  
37 SLMs with inclined illumination since they operate in reflection. The inclination geometry  
38 changes the FOV of the holographic display. Modifying an object wavefront obtained  
39 from recorded digital holograms for reconstruction at the tilted SLM display is a major  
40 challenge with this technology. Kozacki [8] developed a digital hologram processing tech-  
41 nique that uses just the required paraxial holographic field by rigorously propagating par-  
42 axial fields between inclined planes. Other significant considerations in this method are  
43 pixel response and wavefront aberration calibration, SLM calibration based on tilt value,  
44 and characterization of tilt-dependent imaging space. Unconventional angular multiplex-  
45 ing techniques [9] are also utilized to multiplex the whole object information in single  
46 CGH according to the SLM parameters. This approach results in angle multiplexed CGHs  
47 as shown in Fig.1. Although this method only requires one SLM, the FOV it produces is  
48 insufficient for binocular vision. Another CGH generation approach [10] is developed  
49 based on angular multiplexing but it utilizes three SLMs in a planar configuration to re-  
50 construct the image. So, it is economically inefficient and optical configuration also be-  
51 comes complex due to use of three SLMs. Two step Fresnel diffraction method [11] for  
52 CGH calculation is formulated for expansion of FOV without any physical change in the

optical set-up. The virtual image size is increased, resulting in enhanced FOV, by decreasing the sampling interval on the intermediate plane. However, the proposed approach shows promise for the construction of holographic AR near-eye displays with wide FOV. Thus, it is clear from the literature that the algorithms used for CGH generation play a vital role in FOV expansion for a particular holographic display.

### 3. Configuration of display systems

SLMs are used in holographic displays to replicate wavefronts of an object. Due to employment of SLMs as display systems, FOV of reconstructed images is relatively constrained because small size of available SLMs. It is difficult for the viewer to move around while watching the reconstructions since viewing angle is also small due to large pixel pitch of SLMs. Thus, the depth cue provided by motion parallax is insufficient. Additionally, the size of the reconstructed object is rather modest due to the restricted FOV [12]. To increase the field of view for holographic displays, several techniques are reviewed in this section. As the SLMs can work in reflection mode, so it is easy to illuminate them by tilted plane wave. The FOV of the display increases asymmetrically with respect to the tilt angle [8]. The performance of SLM is impacted by incidence angle. In this approach, the limitation is that digital holograms cannot be directly reconstructed due to the geometry and large tilt angles affect the quality of the reconstructed images. Another display system reported by Maeno, K. et. al. [13], in which five transmission type liquid crystal SLMs are placed horizontally side by side. Consequently, there is an expansion of the horizontal FOV. In addition, this technique has limited vertical parallax. To answer this problem, one more method is proposed to enhance the FOV of the reconstructed images. The field of view significantly grows along with the number of SLMs [14] as shown in Fig.2. In the reported geometry six phase-only SLMs are used in a holographic display system that creates holographic reconstructions from a point cloud that is taken from a three-dimensional object [5]. These SLMs are tiled in a three by two pattern. But this method is very expensive because the field of view relies on the number of modulators being employed. Further, J. Hahn et. al. explained another unique strategy [15], in which the display system is made up of a curved array of SLMs. The spatial bandwidth of SLMs is reduced by the curved arrays, which produce more data points. The local angular spectra of the object wave are shown by individually modifying each SLM in the curved array. This configuration has a significant impact on optically reconstructed holographic images.



### 4. Development of optical devices

In holographic display systems, after CGH generation and display systems, optical configurations are realized for spatial filtering of higher diffraction orders and magnification/demagnification, and propagation the reconstructed image to the desired distance at the observation plane. The optical devices used in the optical configurations also have a significant contribution in enhancement of FOV. To increase the FOV by time division and space division multiplexing of SLMs, multiple projection systems, and CGH

1 generation at high frame rate are required. Due to the use of number of SLMs, there are  
2 gaps observed in the reconstructed image that degrades its quality. A holographic  
3 function screen [16] is developed to remove these gaps and further expand the FOV of  
4 display systems. This screen has a specific diffusion angle related with the diffraction  
5 angle of SLM and it is placed at the image plane. Three SLMs are used and the FOV is  
6 increased by 38 times as compare to single SLM with gapless splicing using this functional  
7 screen. The system becomes complex and the functional screen reduced the intensity of  
8 light reached at the observation plane. Holographic optical elements (HOE) [17] are  
9 suggested to achieve the 80° FOV for round view. CGH is uploaded using a phase-only  
10 SLM, and noise produced by the dead zone of the SLM is blocked using a 4f optical system  
11 and spatial filtering at the Fourier plane. The HOE serves as an eyepiece and, as illustrated  
12 in Fig. 3, converges a highly off-axis beam into an on-axis beam in front of the human eye.  
13 The FOV expansion is dependent upon the photopolymer material used for recording as  
14 well as the grating structure of HOE. G. Yuchen et. al.[18], obtained a diagonal FOV about  
15 55° using polarized volume holographic grating (PVG). The angular bandwidth and  
16 refractive index modulation of recorded gratings are the responsible factors for the limited  
17 FOV. In spite of the fact that PVG has a wider angular bandwidth than volume  
18 holographic grating (VHG), a single PVG is unable to accommodate a broad field of  
19 view. Thus, the laminated composite PVGs are proposed in this work. The lens array 4f  
20 system [19] is adopted to increase the FOV from 1.9° to 7.6° and optimized the SLM phase  
21 profile to improve the reconstructed image quality. K. Dongyeon et. al. suggested a FOV  
22 expansion technique for the holographic near-eye display without additional mechanical  
23 device and micro structured mask. The original intensity is divided into pieces, and each  
24 serves as a target profile for each depth plane. The placement of beam splitter array and  
25 eyepiece lens with high numerical aperture allows realization of the enlarged FOV. Three  
26 times enlarged FOV is achieved by the mentioned approach. Based on the above research  
27 studies, it is observed that the development of such devices are helpful in realization of  
28 holographic displays with wide FOV.

## 29 5. Conclusion

30 This paper reviews the current state-of-the-art of the FOV expansion for the holographic  
31 displays. CGH generation algorithms, configuration of display systems, and the optical  
32 devices are identified as the three most promising candidates for the above purpose. The  
33 combination of different primitive methods into an optimized algorithm is a good solution  
34 to enhance the FOV. In addition, with the development of computer, the combination of  
35 fast calculation algorithms and high-performance computing equipment is also an  
36 effective means to speed up the calculation and helpful in spatio-temporal multiplexing  
37 of SLMs. A path for limited FOV is opened up at the same time by the development of  
38 new optical devices. From the perspective of display for practical uses, more system  
39 parameters need to be taken into account, such as cost, image quality, uniform intensity  
40 distribution, and simplicity of overall system etc. Holographic displays are anticipated to  
41 enter the market and become a part of daily life in the near future as a result of  
42 advancements in CGH algorithms, devices, and systems.

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