



Proceeding Paper

Global Well-Posedness for 3d-Axisymmetric Anisotropic Boussinesq System with Stratification Effects [†]

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Abstract: In this work, we study the Cauchy problem of the 3d-Anisotropic Boussinesq system with Horizontal dissipation and stratification effect for axisymmetric data. This system couples the Navier-stokes equation with a non-homogenous transport-diffusion equation. More precisely, we prove that this kind of system admits a unique global solution belongs to the Anisotropic Sobolev spaces.

Keywords: Anisotropic Sobolev spaces; boussinesq system; global solutions; uniqueness

1. Introduction

The 3d-Boussinesq system with horizontal dissipation and stratification effects describes the convective motion of a viscous or inviscid fluid, which reads as follows:

$$\begin{cases} \partial_t v + v \cdot \nabla v - v_h (\partial_{x_1}^2 v + \partial_{x_2}^2 v) + \nabla p = \varrho \vec{e}_3 & \text{if } (t, x) \in \mathbb{R}_+ \times \mathbb{R}^3, \\ \partial_t \varrho + v \cdot \nabla \varrho - \kappa_h (\partial_{x_1}^2 \varrho + \partial_{x_2}^2 \varrho) = -\mathcal{N}^2(x_3) v_3 & \text{if } (t, x) \in \mathbb{R}_+ \times \mathbb{R}^3, \\ \operatorname{div} v = 0, \\ (v, \varrho)|_{t=0} = (v_0, \varrho_0). \end{cases} \quad (B_{v_h, \kappa_h})$$

where $v = (v_1, v_2, v_3)$ describes the velocity, ϱ is a scalar function represents the density, p is the pressure and v_h, κ_h denotes viscosity and thermal diffusivity of the fluid. On the other hand it deserves to recall that the action of the buoyant forces represented by ϱe_3 , where $e_3 = (0, 0, 1)^t$ induce the motion derived from the gravitational potential energy and the quantity \mathcal{N}^2 is a scalar function called the Brunt-Väisärä frequency or the stratification parameter (see, e.g. [1,2]). One of the interesting situations is to investigate the global existence of the system (B_{v_h, κ_h}) is the case when the velocity is axisymmetric without swirl, which corresponds to the following case: we say that the velocity v is axisymmetric without swirl if we have:

$$v(t, x_1, x_2, x_3) \triangleq v_r(t, r, z) \vec{e}_r + v_z(t, r, z) \vec{e}_z,$$

with $x_1 = r \cos \theta$, $x_2 = r \sin \theta$ and $x_3 = z$, where $r = \sqrt{x_1^2 + x_2^2}$, $0 \leq \theta \leq 2\pi$. The triplet (e_r, e_θ, z) is the cylindrical basis given by

$$\vec{e}_r = \left(\frac{x_1}{r}, \frac{x_2}{r}, 0 \right), \quad \vec{e}_\theta = (-\sin \theta, \cos \theta, 0) \quad \text{and} \quad \vec{e}_z = (0, 0, 1).$$

Lately, there are many papers which study the 3d-axisymmetric Boussinesq system without swirl for different viscosities, we refer the reader to [3–6], see also [7–10] for the axisymmetric Euler equation. In 2012, Miao and Zheng investigated the system (B_{v_h, κ_h}) with axisymmetric data but without stratification effect i.e. $(\mathcal{N} \equiv 0)$, where they have proved the existence and uniqueness of solutions. In this paper we aim to extend the result of [5] to the Boussinesq system with stratification effect, more precisely, the main result of this paper is stated as follows:



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2. Main Result

Theorem 1. Let $v_0 \in H^1$ be an axisymmetric divergence free vector field without swirl such that $\frac{\omega_0}{r} \in L^2, \partial_z \omega_0 \in L^2$ and let $\varrho_0 \in H^{0,1}$ an axisymmetric function. Then the system (B_{v_h, κ_h}) admits a unique global solution such that

$$(v, \varrho) \in (C(\mathbb{R}_+; H^1) \cap L^2_{loc}(\mathbb{R}_+; H^{1,2} \cap H^{2,1}) \cap L^1_{loc}(\mathbb{R}_+; Lip)) \times C(\mathbb{R}_+; H^{0,1} \cap H^{1,1}).$$

Moreover, we have

$$\frac{\omega}{r} \in L^\infty_{loc}(\mathbb{R}_+; L^2) \cap L^2_{loc}(\mathbb{R}_+; H^{1,0}), \quad \partial_z \omega \in C(\mathbb{R}_+; L^2) \cap L^2_{loc}(\mathbb{R}_+; H^{1,0}).$$

Remark 1. Without loss of generality, we assume that $\mathcal{N}^2(x_3) = v_h = \kappa_h = 1$.

In the spirit of [4,5], by using the hidden structure between the velocity equation and the density equation in the system (B_{v_h, κ_h}) , we can introduce a new quantity which will be called by the coupled function of the system (B_{v_h, κ_h}) , this quantity solves the following equation

$$\partial_t \tilde{\Gamma} + v \cdot \nabla \tilde{\Gamma} - \Delta_h \tilde{\Gamma} + \frac{2}{r} \partial_r \tilde{\Gamma} = -\frac{1}{2} v_z,$$

with $\Delta_h \triangleq \partial_{x_1}^2 + \partial_{x_2}^2$ and $\tilde{\Gamma} \triangleq \zeta - \frac{\varrho}{2}$.

From this observation we start by controlling the L^2 -norm of $\tilde{\Gamma}$, hence we bound the following quantity $\|\frac{\omega \varrho}{r}\|_{L^2}$, then we get the global H^1 -estimate of the velocity, by combining these results, we obtain the Lipschitz norm of the velocity, which leads us to the global existence of solutions.

3. Proof of Theorem 1

Proposition 1. Let (v, ϱ) be a smooth solution of (B_{v_h, κ_h}) . Then we have

$$\|v(t)\|_{L^2}^2 + \|\varrho(t)\|_{L^2}^2 + \int_0^t (\|\nabla_h \varrho(\tau)\|_{L^2}^2 + \|\nabla_h v(\tau)\|_{L^2}^2) d\tau \leq C_0 e^{C_0 t} \tag{1}$$

Proposition 2. Let (ω, ϱ) be a solution for (B_{v_h, κ_h}) and $\partial_z \varrho_0, \partial_z \omega_0 \in L^2$. Then

$$\|\partial_z \varrho(t)\|_{L^2} + \int_0^t \|\nabla_h \partial_z \varrho(\tau)\|_{L^2} d\tau \leq C_0 e^{\exp(C_0 t)}, \tag{2}$$

$$\|\partial_z \omega(t)\|_{L^2} + \int_0^t \|\nabla_h \partial_z \omega(\tau)\|_{L^2} d\tau \leq C_0 e^{\exp(C_0 t)}. \tag{3}$$

Proof. We set $\sigma(t, x) = \partial_z \varrho(t, x)$ and by applying ∂_z to the density equation in (B_{v_h, κ_h}) we find

$$\partial_t \sigma + v \cdot \nabla \sigma - \Delta_h \sigma = \partial_z v_z (1 - \sigma(t, x)) - \partial_z v_r \partial_r \varrho,$$

On the other hand from incompressibility condition, we have $\partial_z v_z = -\partial_r v_r - \frac{v_r}{r}$. Then the classical L^2 -estimates gives

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \|\sigma(t)\|_{L^2}^2 + \|\nabla_h \sigma(t)\|_{L^2}^2 &= - \int_{\mathbb{R}^3} \partial_z v_r \partial_r \varrho \sigma dx + \int_{\mathbb{R}^3} \partial_r v_r \sigma^2 dx + \int_{\mathbb{R}^3} \frac{v_r}{r} \sigma^2 dx \\ &+ \int_{\mathbb{R}^3} \partial_z v_z \sigma dx \\ &= \sum_{i=1}^4 I_i. \end{aligned} \tag{4}$$

We start by I_1 , we use the anisotropic inequality [5, Lemma F.3] and Hölder inequality, we obtain

$$\begin{aligned} (I_1)^2 &\lesssim \|\partial_z v_r\|_{L^2} \|\nabla_h \partial_z v_r\|_{L^2} \|\partial_r \varrho\|_{L^2} \|\partial_z \partial_r \varrho\|_{L^2} \|\sigma\|_{L^2} \|\nabla_h \sigma\|_{L^2} \\ &\lesssim \|\partial_z v_r\|_{L^2} \|\nabla_h \partial_z v_r\|_{L^2} \|\partial_r \varrho\|_{L^2} \|\sigma\|_{L^2} \|\nabla_h \sigma\|_{L^2}^2. \end{aligned}$$

Young’s inequality and Biot savart law ensures that

$$I_1 \lesssim \|\nabla_h \partial_z v_r\|_{L^2}^2 + \|\omega\|_{L^2}^2 \|\partial_r \varrho\|_{L^2}^2 \|\sigma\|_{L^2}^2 + \frac{1}{4} \|\nabla_h \sigma\|_{L^2}^2.$$

For I_2 , from the anisotropic inequality [5, Lemma F.3] and Young inequality, we obtain

$$\begin{aligned} I_2 &\lesssim \left\| \frac{v_r}{r} \right\|_{L^6}^{\frac{3}{4}} \|\partial_z \left(\frac{v_r}{r} \right)\|_{L^2}^{\frac{1}{4}} \|\sigma\|_{L^2}^{\frac{3}{2}} \|\nabla_h \sigma\|_{L^2}^{\frac{1}{2}} \\ &\lesssim \left\| \frac{\omega_\theta}{r} \right\|_{L^2}^{\frac{4}{3}} \|\sigma\|_{L^2}^2 + \frac{1}{4} \|\nabla_h \sigma\|_{L^2}^2 \end{aligned} \tag{5}$$

Analogously, we find out

$$\begin{aligned} I_3 &\lesssim \|\partial_r v_r\|_{L^6}^{\frac{3}{4}} \|\partial_z \partial_r v_r\|_{L^2}^{\frac{1}{4}} \|\sigma\|_{L^2}^{\frac{3}{2}} \|\nabla_h \sigma\|_{L^2}^{\frac{1}{2}} \\ &\lesssim \|\nabla_h \omega\|_{L^2} \|\sigma\|_{L^2}^2 + \frac{1}{4} \|\nabla_h \sigma\|_{L^2}^2 \end{aligned} \tag{6}$$

For the last term I_4 , we use Hölder’s and Young’s inequalities to get:

$$\begin{aligned} I_4 &\lesssim \|\partial_z v_z\|_{L^2} \|\sigma\|_{L^2} \\ &\lesssim \|\nabla v\|_{L^2}^2 + \|\sigma\|_{L^2}^2 \\ &\lesssim \|\omega\|_{L^2}^2 + \|\sigma\|_{L^2}^2. \end{aligned} \tag{7}$$

Then by Integrating (4) with respect to time and using Grönwall’s inequality to obtain the required result. In order to prove (3), we apply the partial derivative ∂_z to the vorticity equation, to obtain

$$\partial_t \tilde{\omega} + v \cdot \nabla \tilde{\omega} - \Delta_h \tilde{\omega} = \partial_z \partial_r \varrho e_\theta + \frac{\partial_z}{r} \omega - \partial_z v_r \partial_r \omega + \tilde{\omega} \left(\frac{v_r}{r} - \partial_z v_z \right),$$

with $\tilde{\omega} = \partial_z \omega$. We have

$$\partial_t \tilde{\omega} + v \cdot \nabla \tilde{\omega} - \Delta_h \tilde{\omega} = -\partial_z \partial_r \varrho e_\theta + \frac{\partial_z v_r}{r} \omega - \partial_z v_r \partial_r \omega + \tilde{\omega} \left(2 \frac{v_r}{r} + \partial_r v_r \right).$$

The classical L^2 -estimate leads to

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \|\tilde{\omega}(t)\|_{L^2}^2 + \|\nabla_h \tilde{\omega}(t)\|_{L^2}^2 &= - \int_{\mathbb{R}^3} \partial_z \partial_r \varrho e_\theta \tilde{\omega} dx + \int_{\mathbb{R}^3} \frac{\partial_z v_r}{r} \omega \tilde{\omega} dx \\ &\quad - \int_{\mathbb{R}^3} \partial_z v_r \partial_r \omega \tilde{\omega} dx + \int_{\mathbb{R}^3} 2 \frac{v_r}{r} \tilde{\omega} \omega dx + \int_{\mathbb{R}^3} \partial_r v_r \tilde{\omega} \omega dx \\ &= \sum_{i=1}^5 J_i. \end{aligned} \tag{8}$$

Combining Cauchy-Schwartz’s inequality with Young’s inequality we obtain

$$\begin{aligned} J_1 &\leq \|\partial_z \partial_r \varrho\|_{L^2} \|\tilde{\omega}\|_{L^2} \\ &\leq \|\partial_z \partial_r \varrho\|_{L^2}^2 + \|\tilde{\omega}\|_{L^2}^2 \leq \|\nabla_h \partial_z \varrho\|_{L^2}^2 + \|\tilde{\omega}\|_{L^2}^2. \end{aligned} \tag{9}$$

To control J_2 we make use the anisotropic inequality [5, Lemma F.5] to obtain

$$\begin{aligned} J_2 &\lesssim \|\partial_z \frac{v_r}{r}\|_{L^2} \|\omega\|_{L^6}^{\frac{3}{4}} \|\tilde{\omega}\|_{L^2}^{\frac{1}{4}} \|\tilde{\omega}\|_{L^2}^{\frac{1}{2}} \|\nabla_h \tilde{\omega}\|_{L^2}^{\frac{1}{2}} \\ &\lesssim \|\frac{\omega_\theta}{r}\|_{L^2}^{\frac{3}{4}} \|\nabla_h \omega\|_{L^2}^2 + \|\frac{\omega_\theta}{r}\|_{L^2}^{\frac{3}{4}} \|\tilde{\omega}\|_{L^2}^2 + \frac{1}{8} \|\nabla_h \tilde{\omega}\|_{L^2}^2. \end{aligned}$$

From ([5], Lemma F.2), we find

$$\begin{aligned} J_3 &\lesssim 2\|\frac{v_r}{r}\|_{L^2} \|\partial_z \frac{v_r}{r}\|_{L^2}^{\frac{1}{4}} \|\tilde{\omega}\|_{L^2}^{\frac{3}{2}} \|\nabla_h \tilde{\omega}\|_{L^2} \\ &\lesssim \|\frac{\omega}{r}\|_{L^2}^{\frac{3}{4}} \|\tilde{\omega}\|_{L^2}^2 + \frac{1}{8} \|\nabla_h \tilde{\omega}\|_{L^2}^2. \end{aligned} \tag{10}$$

Similarly, we obtain

$$\begin{aligned} J_4 &\lesssim \|\partial_r \omega\|_{L^2}^{\frac{1}{2}} \|\partial_r \tilde{\omega}\|_{L^2}^{\frac{1}{2}} \|\partial_z v_r\|_{L^2}^{\frac{1}{2}} \|\nabla_h \partial_z v_r\|_{L^2}^{\frac{1}{2}} \|\tilde{\omega}\|_{L^2}^{\frac{1}{2}} \|\nabla_h \tilde{\omega}\|_{L^2}^{\frac{1}{2}} \\ &\lesssim \|\nabla_h \omega\|_{L^2}^2 \|\omega\|_{L^2}^2 \|\tilde{\omega}\|_{L^2}^2 + \|\nabla_h \partial_z v_r\|_{L^2}^2 + \frac{1}{8} \|\nabla_h \tilde{\omega}\|_{L^2}^2 \end{aligned}$$

For the last term, we get

$$\begin{aligned} J_5 &\lesssim \|\partial_r v_r\|_{L^6}^{\frac{3}{4}} \|\partial_z \partial_r v_r\|_{L^2}^{\frac{1}{4}} \|\tilde{\omega}\|_{L^2}^{\frac{3}{2}} \|\nabla_h \tilde{\omega}\|_{L^2}^{\frac{1}{2}} \\ &\lesssim \|\nabla_h \omega\|_{L^2} \|\tilde{\omega}\|_{L^2}^2 + \frac{1}{8} \|\nabla_h \tilde{\omega}\|_{L^2}^2. \end{aligned} \tag{11}$$

Putting the above inequalities together and using Grönwall’s inequality we get the desired result. \square

Proposition 3. Assume that $v_0 \in L^2$, with $\frac{\omega^\theta}{r} \in L^2$ and $q_0 \in L^2$. Let be a smooth axisymmetric solution of (B_{v_h, κ_h}) without swirl, then we have

$$\|\frac{\omega_\theta}{r}(t)\|_{L^2}^2 + \int_0^t \|\nabla_h \frac{\omega_\theta}{r}(\tau)\|_{L^2}^2 d\tau \leq 2(\|v_0\|_{L^2} + \|q_0\|_{L^2})^2 \left(\|\frac{\omega_\theta}{r}(0)\|_{L^2} + \|q_0\|_{L^2} + 2\right)^2 e^{Ct}.$$

Proof. According to (3) the coupled function $\tilde{\Gamma} \triangleq \frac{\omega^\theta}{r} - \frac{q}{2}$ satisfies the following equation

$$\left(\partial_t + v \cdot \nabla - (\Delta_h + \frac{2}{r} \partial_r)\right) \tilde{\Gamma} = -\frac{v^z}{2}.$$

On one hand, from the classical L^2 -estimate, we obtain

$$\|\tilde{\Gamma}(t)\|_{L^2}^2 + \|\nabla_h \tilde{\Gamma}\|_{L^2_t L^2}^2 \leq (\|v_0\|_{L^2} + \|q_0\|_{L^2})^2 \left(\|\tilde{\Gamma}_0\|_{L^2} + 1\right)^2 e^{Ct}. \tag{12}$$

On the other hand, we have

$$\begin{aligned} \|\frac{\omega_\theta}{r}(t)\|_{L^2}^2 + \int_0^t \|\nabla_h \frac{\omega_\theta}{r}(\tau)\|_{L^2}^2 d\tau &\leq (\|\tilde{\Gamma}(t)\|_{L^2} + \|q(t)\|_{L^2})^2 (\|\nabla_h \tilde{\Gamma}(t)\|_{L^2} + \|\nabla_h q(t)\|_{L^2_t L^2})^2 \\ &\leq 2(\|v_0\|_{L^2} + \|q_0\|_{L^2})^2 \left(\|\tilde{\Gamma}_0\|_{L^2} + 2\right)^2 e^{Ct}. \end{aligned}$$

This gives the first estimate. For the second one, we have

$$\frac{1}{2} \frac{d}{dt} \|\omega_\theta(t)\|_{L^2}^2 + \|\nabla_h \omega_\theta(t)\|_{L^2}^2 + \|\frac{\omega_\theta}{r}(t)\|_{L^2}^2 = \int_{\mathbb{R}^3} \frac{v_r}{r} \omega_\theta \omega_\theta dx - \int_{\mathbb{R}^3} \partial_r q \omega_\theta.$$

By an integration by parts, we find out

$$\begin{aligned} \int_{\mathbb{R}^3} \partial_r \varrho \omega_\theta dx &= 2\pi \int \varrho \omega_\theta r dr dz = 2\pi \int \varrho \partial_r \omega_\theta r dr dz + 2\pi \int \varrho \omega_\theta dr dz \\ &= \int_{\mathbb{R}^3} \varrho \partial_r \omega_\theta dx + \int_{\mathbb{R}^3} \varrho \frac{\omega_\theta}{r} dx. \end{aligned}$$

By combining with Hölder and Young’s inequality, we infer

$$\begin{aligned} \left| \int_{\mathbb{R}^3} \partial_r \varrho \omega_\theta dx \right| &\leq \| \varrho(t) \|_{L^2} (\| \nabla_h \omega_\theta(t) \|_{L^2} + \| \omega_\theta / r(t) \|_{L^2}) \\ &\leq 2(\| v_0 \|_{L^2} + \| \varrho_0 \|_{L^2})^2 e^{Ct} + \frac{1}{4} (\| \nabla_h \omega_\theta(t) \|_{L^2}^2 + \| \omega_\theta / r(t) \|_{L^2}^2). \end{aligned}$$

On other hand, we get

$$\begin{aligned} \left| \int_{\mathbb{R}^3} \varrho \frac{\omega_\theta}{r} dx \right| &\leq \| v^r \|_{L^\infty} \left\| \frac{\omega_\theta}{r} \right\|_{L^2} \| \omega_\theta \|_{L^2} \\ &\leq C \left\| \frac{\omega_\theta}{r} \right\|_{L^2}^{\frac{4}{3}} \| \omega_\theta \|_{L^2}^2 + \frac{1}{4} \| \nabla_h \omega_\theta \|_{L^2}^2. \end{aligned}$$

Thus,

$$\frac{1}{2} \frac{d}{dt} \| \omega_\theta(t) \|_{L^2}^2 + \| \nabla_h \omega_\theta(t) \|_{L^2}^2 + \left\| \frac{\omega_\theta}{r}(t) \right\|_{L^2}^2 \lesssim (\| v_0 \|_{L^2} + \| \varrho_0 \|_{L^2})^2 e^{Ct} + \left\| \frac{\omega_\theta}{r} \right\|_{L^2}^{\frac{4}{3}} \| \omega_\theta \|_{L^2}^2.$$

Integrating the above inequality with respect to time, we get

$$\begin{aligned} \| \omega_\theta(t) \|_{L^2}^2 + \int_0^t (\| \nabla_h \omega_\theta(\tau) \|_{L^2}^2 + \left\| \frac{\omega_\theta}{r}(\tau) \right\|_{L^2}^2) d\tau &\lesssim \| \omega_\theta(0) \|_{L^2}^2 + (\| v_0 \|_{L^2} + \| \varrho_0 \|_{L^2})^2 e^{Ct} \\ &\quad + \int_0^t \left\| \frac{\omega_\theta}{r}(\tau) \right\|_{L^2}^{\frac{4}{3}} \| \omega_\theta(\tau) \|_{L^2}^2 d\tau. \end{aligned}$$

Since $\| \omega \|_{L^2} = \| \omega_\theta \|_{L^2}$ and $\| \nabla_h \omega(t) \|_{L^2}^2 = \| \nabla_h \omega_\theta \|_{L^2}^2 + \left\| \frac{\omega_\theta}{r} \right\|_{L^2}^2$, then

$$\| \omega(t) \|_{L^2}^2 + \int_0^t \| \nabla_h \omega(\tau) \|_{L^2}^2 \leq C_0 e^{C_0 t}. \tag{13}$$

□

Proposition 4. Let (v, ϱ) be a smooth solution of (B_{v_h, κ_h}) such that $v_0 \in H^1$ be divergence free axisymmetric without swirl vector field, with $\frac{\omega^\theta}{r} \in L^2, \partial_z \omega^0 \in L^2$ and $\varrho_0 \in H^{0,1}$ be an axisymmetric function. Then we have

$$\| \nabla v \|_{L_t^1 L^\infty} \leq C_0 e^{\exp(C_0 t)}.$$

Proof. By using the fact $\operatorname{div} v = \partial_r v^r + \frac{v^r}{r} + \partial_z v^z = 0$ and $\omega^\theta = \partial_z v^r - \partial_r v^z$, we obtain

$$\begin{aligned} \| \nabla v \|_{L_t^1 L^\infty} &\leq \| \partial_r v^r \|_{L_t^1 L^\infty} + \left\| \frac{v^r}{r} \right\|_{L_t^1 L^\infty} + \| \partial_z v^z \|_{L_t^1 L^\infty} \\ &\lesssim \left\| \frac{v^r}{r} \right\|_{L_t^1 L^\infty} + \| \partial_r v^r \|_{L_t^1 L^\infty} + \| \partial_z v^r \|_{L_t^1 L^\infty} + \| \partial_r v^z \|_{L_t^1 L^\infty}. \end{aligned}$$

We have:

$$\left\| \frac{v^r}{r} \right\|_{L_t^1 L^\infty} \lesssim \left\| \frac{\omega_\theta}{r} \right\|_{L_t^1 L^\infty}^{\frac{1}{2}} \| \nabla_h \left(\frac{\omega_\theta}{r} \right) \|_{L_t^1 L^\infty}^{\frac{1}{2}} \lesssim C_0 e^{(C_0 t)}.$$

Also

$$\| \partial_z v^r \|_{L_t^1 L^\infty} \lesssim \int_0^t \| \nabla \partial_z v^r \|_{L^2}^{\frac{1}{2}} \| \nabla_h \partial_z v^r \|_{L^2}^{\frac{1}{2}} d\tau \lesssim t^{\frac{1}{2}} \| \partial_z \omega \|_{L_t^\infty L^2}^{\frac{1}{2}} \| \nabla_h \partial_z \omega \|_{L_t^1 L^2}^{\frac{1}{2}}.$$

For the last quantities, we have

$$\|\partial_r v^z\|_{L^1_t L^\infty} + \|\partial_r v^r\|_{L^1_t L^\infty} \lesssim \|v\|_{L^1_t B^{1, \frac{1}{2}}_{2,1}}.$$

Therefore,

$$\begin{aligned} \|v\|_{L^1_t B^{1, \frac{1}{2}}_{2,1}} &\lesssim \|v_0\|_{B^{0, \frac{1}{2}}_{2,1}} + \|v\|_{L^1_t B^{0, \frac{1}{2}}_{2,1}} + \|v \otimes v\|_{L^1_t B^{1, \frac{1}{2}}_{2,1}} + \|v \otimes v\|_{L^1_t B^{0, \frac{3}{2}}_{2,1}} + \|q\|_{L^1_t B^{0, \frac{1}{2}}_{2,1}} \\ &\lesssim \|v_0\|_{H^{1,1}} + \|v\|_{L^1_t H^{1,1}} + \|v \otimes v\|_{L^1_t H^{2,1}} + \|v \otimes v\|_{L^1_t H^{\frac{5}{4}, \frac{7}{4}}} + \|q\|_{L^1_t H^{1,1}} \\ &\lesssim \|v_0\|_{H^{1,1}} + \|v\|_{L^2_t H^{1,1}} + \|v\|_{L^2_t H^{2,1}}^2 + \|v\|_{L^2_t H^{\frac{5}{4}, \frac{7}{4}}}^2 + \|q\|_{L^1_t H^{1,1}}, \end{aligned}$$

for the definition of Besov spaces and Anisotropic Besov spaces, we refer the reader to ([5], Definition.2.2). Hence

$$\|v\|_{L^2_t H^{2,1}} \lesssim \|v\|_{L^2_t L^2} + \|\partial_z v\|_{L^2_t L^2} + \|\nabla_h^2 v\|_{L^2_t L^2} + \|\nabla_h^2 \partial_z v\|_{L^2_t L^2}$$

and

$$\begin{aligned} \|v\|_{L^2_t H^{\frac{5}{4}, \frac{7}{4}}} &\lesssim \|v\|_{L^2_t L^2} + \|\Lambda_h^{\frac{5}{4}} v\|_{L^2_t L^2} + \|\Lambda_\theta^{\frac{7}{4}} v\|_{L^2_t L^2} + \|\Lambda_h^{\frac{5}{4}} \Lambda_\theta^{\frac{7}{4}} v\|_{L^2_t L^2} \\ &\lesssim \|v\|_{L^2_t L^2} + \|\nabla_h v\|_{L^2_t L^2} + \|\nabla_h^2 v\|_{L^2_t L^2} + \|\partial_z v\|_{L^2_t L^2} + \|\partial_z^2 v\|_{L^2_t L^2} + \|\nabla_h \partial_z v\|_{L^2_t L^2}. \end{aligned}$$

For the term $\|q\|_{L^1_t H^{1,1}}$, we have

$$\|q\|_{L^1_t H^{1,1}} \lesssim \|q\|_{L^1_t L^2} + \|\partial_z q\|_{L^1_t L^2} + \|\nabla_h q\|_{L^1_t L^2} + \|\nabla_h \partial_z q\|_{L^1_t L^2} \leq C_0 e^{exp(C_0 t)},$$

then we get the desired result. \square

4. Conclusions

In this paper, we were able to obtain the global well posedness for the anisotropic Boussinesq system with horizontal dissipation.

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