



Proceeding Paper

Existence and Attractivity Results for Fractional Differential Inclusions via Nocompactness Measures [†]

Baghdad Said ^{1,2}

¹ Department of Mathematics, Ibn khaldoun University, Tiaret , Algeria; said.baghdad@univ-tiaret.dz

² Laboratory of Geometry, Analysis, Control and Applications, University of Saida Dr. Moulay Tahar, , Algeria

[†] Presented at the 1st International Online Conference on Mathematics and Applications; Available online: <https://iocma2023.sciforum.net/>.

Abstract: In this paper, we use the concept of measure of nocompactness and fixed point theorems to investigate the existence and stability of solutions of a class of Hadamard-Stieltjes fractional differential inclusion in an appropriate Banach space, these results are proven under sufficient hypotheses. We also give an example to illustrate the obtained results.

Keywords: fractional differential inclusions; nocompactness measures; regulated functions; stability; fixed-point theorems

1. Introduction

In this work, we consider the following differential inclusion with initial condition

$$\begin{cases} \mathcal{D}^\gamma \left(\frac{dw}{d\phi} \right) (z) \in G(z, w(z)); & z \in (1, +\infty) \\ \frac{dw}{d\phi} (1) = w_0; & w(1) = w_1 \end{cases} \quad (1)$$

where $w_0, w_1 \in \mathbb{R}$, $\frac{dw}{d\phi}$ is the Stieltjes derivative of w with respect to ϕ , \mathcal{D}^γ is the Hadamard fractional derivative of order $0 < \gamma < 1$, $G : [1, +\infty) \times \mathbb{R} \rightarrow \mathcal{P}(\mathbb{R})$ is multivalued map and $\mathcal{P}(\mathbb{R})$ is the family of all nonempty subsets of \mathbb{R} .

2. Preliminaries

Assume that $\phi : \mathbb{R} \rightarrow \mathbb{R}$ is monotone, nondecreasing and continuous from the left everywhere. D_ϕ is the set of discontinuity points of ϕ . We denote by $\mathcal{B}(J)$, the Banach space of bounded functions on the interval $J = [1, +\infty)$ equipped with the norm of uniform convergence, and by $\mathcal{B}_\phi(J)$ the subspace of bounded functions which are also ϕ -continuous on J .

Theorem 1. $\mathcal{B}_\phi(J)$ is a Banach space.

Let X and Y be two Banach spaces, we define

$$\mathcal{P}_{cl,cv,cp}(X) = \{\Omega \in \mathcal{P}(X); \Omega \text{ is closed, convex, compact}\}.$$

Theorem 2 ([10]). Let $G : X \rightarrow \mathcal{P}_{cl,cv}(Y)$ be a lower semicontinuous multifunction. Then G admits continuous selection.

Theorem 3 ([10]). Let Ω be a nonempty, bounded, closed and convex subset of the Banach space X with ψ is a measure of nocompactness in it and let $G : \Omega \rightarrow \mathcal{P}_{cl,cv}(\Omega)$ be a closed. Assume that there exists a constant $k \in [0, 1)$ such that $\psi(GA) \leq k\psi(A)$ for any nonempty subset A of Ω . Then G has a fixed point in the set Ω .



Citation: Said, B. Existence and Attractivity Results for Fractional Differential Inclusions via Nocompactness Measures. *Comput. Sci. Math. Forum* **2023**, *1*, 0. <https://doi.org/>

Academic Editor: Firstname
Lastname

Published: 28 April 2023



Copyright: © 2023 by the author. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (<https://creativecommons.org/licenses/by/4.0/>).

Remark 1. Let us denote by $\text{Fix } G$ the set of all fixed points of the operator G which belong to Ω . The set $\text{Fix } G$ belongs to the family $\ker \psi$ see [10].

3. Main Results

Consider the function ψ defined on the family $\mathcal{M}_{\mathcal{B}_\phi(J)}$ by the formula

$$\psi(\Omega) = \max\{\omega_\phi(\Omega), \omega_\phi^+(\Omega)\} + \limsup_{z \rightarrow \infty} \text{diam } \Omega(z). \tag{2}$$

Theorem 4. The mappings ψ is a measure of nocompactness in the space $\mathcal{B}_\phi(J)$.

Consider the following inclusion

$$u(z) \in (Fu)(z); z \in J. \tag{3}$$

Definition 1. The solution $u = u(z)$ of (3) is said to be globally attractive if for each solution $v = v(z)$ of (3) we have that

$$\lim_{z \rightarrow \infty} (u(z) - v(z)) = 0.$$

In the case when this limit is uniform i.e when for each $\epsilon > 0$ there exists $T > 1$ such that

$$|u(z) - v(z)| < \epsilon, \tag{4}$$

for $z \geq T$, we will say that solutions of (3) are uniformly globally attractive.

Remark 2. The kernel $\ker \psi$ consists of nonempty and bounded sets Ω such that functions from Ω are locally equiregulated on J and for each $u, v \in \Omega$, (4) hold.

Let $\frac{dw}{d\phi}(z) = v(z)$ then $w(z) = w_0 + \int_1^z v(t)d\phi(t)$ and (1) can be written as

$$v(z) \in w_1 + \frac{1}{\Gamma(\gamma)} \int_1^z \left(\ln \frac{z}{t}\right)^{\gamma-1} G\left(t, w_0 + \int_1^t v(\tau)d\phi(\tau)\right) \frac{dt}{t}, \tag{5}$$

Denote $|G(z, u)| = \{ |u|; u \in F(z, u) \}$ and $\|G(z, u)\| = H(G(z, u), 0) = \sup\{|u|; u \in G(z, u)\}$. The differential inclusion (1) will be considered under the following assumptions:

(H₁) There exist continuous and bounded functions $p, q : J \rightarrow \mathbb{R}_+$ such that

$$H(G(z, u), G(z, v)) \leq p(z)|u - v|; z \in J,$$

for all $u, v \in \mathbb{R}$, and

$$\|G(z, 0)\| = H(G(z, 0), 0) \leq q(z); z \in J.$$

(H₂) For every (z, w) in $J \times \mathbb{R}$, $G(z, w)$ is a nonempty convex and closed subset of \mathbb{R} .

(H₃) Assume that

$$p^* = \sup_{z \in J} \left| \frac{w_0}{\Gamma(\gamma)} \int_1^z \left(\ln \frac{z}{t}\right)^{\gamma-1} p(t) dt \right| < \infty,$$

$$q^* = \sup_{z \in J} \left| \frac{1}{\Gamma(\gamma)} \int_1^z \left(\ln \frac{z}{t}\right)^{\gamma-1} q(t) dt \right| < \infty,$$

$$p_\phi = \sup_{z \in J} \left| \frac{1}{\Gamma(\gamma)} \int_1^z \left(\ln \frac{z}{t}\right)^{\gamma-1} p(t) [\phi(t) - \phi(1)] dt \right| < 1,$$

Remark 3. As observed there, G is lower semicontinuous, hence G admits continuous selection (Theorem 2).

Theorem 5. Under assumptions $(H_1) - (H_3)$ The differential inclusion (1) has at least one solution $u = u(z)$ in the space $\mathcal{B}_\phi(J)$. Moreover, solutions of the differential inclusion (1) are globally attractive.

Proof. Consider the multi-valued operator N defined on the space $\mathcal{B}_\phi(J)$ in the following way:

$$N : \mathcal{B}_\phi(J) \rightarrow \mathcal{P}(\mathcal{B}_\phi(J));$$

such that, for each $u \in \mathcal{B}_\phi(J)$

$$(Nw)(z) = \left\{ u \in \mathcal{B}_\phi(J) \mid u(z) = w_1 + \frac{1}{\Gamma(\gamma)} \int_1^z \left(\ln \frac{z}{t}\right)^{\gamma-1} g\left(t, w_0 + \int_1^t w(\tau) d\phi(\tau)\right) \frac{dt}{t} \right\},$$

where g is a selector of G . For each w in $\mathcal{B}_\phi(J)$, and for each function u in Nw , we have u is ϕ -continuous on J . Next, let us take an arbitrary function $w \in \mathcal{B}_\phi(J)$, $u \in Nu$ and fixed $z \in J$, we get

$$|u(z)| \leq |w_1| + p^* + \|w\| p_\phi + q^*.$$

So, the operator N is well defined. We take

$$\zeta = \frac{|w_1| + \frac{p^*}{\Gamma(\gamma)} + \frac{q^*}{\Gamma(\gamma)}}{1 - p_\phi}.$$

We deduce that the operator $N : B_\zeta \rightarrow \mathcal{P}(B_\zeta)$. Further, the set Nu is closed and convex in B_ζ . Now, we take a nonempty $\Omega \subset B_\zeta$, for $T > 1$, $z_1, z_2 \in [1, T]$ with $z_1 < z_2$ and $|\phi(z_2) - \phi(z_1)| \leq \epsilon$ for each $\epsilon > 0$. Fix arbitrarily $w \in \Omega$ and $u \in Nw$, we obtain

$$\omega_\phi(N\Omega) = 0. \tag{6}$$

For $z_0 \in J \cap D_\phi$, fix $z \in (z_0, z_0 + \epsilon)$, we have

$$\omega_\phi^+(N\Omega) = 0. \tag{7}$$

From (6) and (7), we infer that the set $N\Omega$ is equiregulated on J . Further, for $w, w' \in \Omega$, $u \in Nw$ and $u' \in Nw'$ and an arbitrary fixed $z \in [1, T]$, we get

$$\limsup_{z \rightarrow \infty} \text{diam } N\Omega(z) \leq p_\phi \limsup_{z \rightarrow \infty} \text{diam } \Omega(z). \tag{8}$$

Consequently, in view of (6)–(8), we deduce that

$$\psi(N\Omega) \leq p_\phi \psi(\Omega).$$

Then, by the Theorem 3 the operator N has at least one fixed point in B_ζ which is a solution of differential inclusion (1). Moreover, taking into account the fact that the set $\text{Fix } N \in \ker \psi$ (Remark 1) and the characterization of sets belonging to $\ker \psi$ (Remark 2), we conclude that all solutions of (1) are globally attractive in the sense of Definition 1. \square

4. Example

We consider the following differential inclusion

$$\begin{cases} \mathcal{D}^\gamma \left(\frac{dw}{d\phi} \right) (z) \in \left[\frac{e^{-z}}{|u(z)|+z}, \frac{(z-1)e^{-z}}{|u(z)|+z} \right] \subset \mathbb{R}; z > 1, \\ \frac{dw}{d\phi} (1) = w_0; \quad w(1) = w_1. \end{cases} \tag{9}$$

It is clear that (9) can be written as the differential inclusion (1), where $\phi(\tau) = \arctan([\tau])$ (the symbol $[\tau]$ indicates the integer value of τ). Let us show that conditions $(H_1) - (H_3)$ hold. For $z \in J$ and $u, v \in \mathbb{R}$, we have

$$H(F(z, u), F(z, v)) \leq (z - 1)e^{-z}|u - v|.$$

So $p(z) = (z - 1)e^{-z}$, $F(z, 0) = \left[\inf \left\{ \frac{e^{-z}}{z}, \frac{(z-1)}{z}e^{-z} \right\}, \max \left\{ \frac{e^{-z}}{z}, \frac{(z-1)}{z}e^{-z} \right\} \right]$, hence

$$\|F(z, 0)\| = \max \left\{ \frac{e^{-z}}{z}, \frac{(z-1)}{z}e^{-z} \right\} = q(z).$$

Notice that the functions p, q are continuous and bounded on J . Next, for a fixed $z \in J$, we have $p^* < 1$. This estimate show that p^* and q^* are finite quantities. Consequently from Theorem 5 the differential inclusion (9) has at least solution in the space $\mathcal{B}_\phi(J)$ and solutions of (9) are globally attractive.

Funding:

Institutional Review Board Statement:

Informed Consent Statement:

Data Availability Statement:

Conflicts of Interest:

References

1. Abbas, S.A.İ.D.; Benchohra, M.O.U.F.F.A.K.; Henderson, J.O.H.N.N.Y. Ulam stability for partial fractional integral inclusions via Picard operators. *J. Frac. Calc. Appl.* **2014**, *5*, 133–144.
2. Appell, J.; Pascale, E.D.; Thai, N.H.; Zabreiko, P.P. *Multi-Valued Superpositions*; Instytut Matematyczny Polskiej Akademi Nauk: Warszawa, Poland, 1995.
3. Aubin, J.P.; Cellina, A. *Differential Inclusions Set-Valued Maps and Viability Theory*; Springer: Berlin/Heidelberg, Germany, 1984.
4. Bressan, A. On the qualitative theory of lower semicontinuous differential inclusions. *J. Differ. Equ.* **1989**, *77*, 379–391.
5. Cichoń, M.; Cichoń, K.; Satco, B. Measure differential inclusions through selection principles in the space of regulated functions. *Mediterr. J. Math.* **2018**, *15*, 148.
6. Couchouron, J.-F.; Precup, R. Existence principles for inclusions of Hammerstein type involving noncompact acyclic multivalued maps. *Electron. J. Differ. Equ.* **2002**, *2002*, 1–21.
7. Dudek, S.; Olszowy, L. Measures of noncompactness and superposition operator in the space of regulated functions on an unbounded interval. *Rev. R. Acad. Cienc. Exactas Fís. Nat. Ser. A Mat. RACSAM* **2020**, *114*, 168.
8. Frigon, M.; FAdrián, F.T. Stieltjes differential systems with nonmonotonic derivators. *Bound. Value Probl.* **2020**, *2020*, 41.
9. Frigon, M.; Pouso, R.L. Theory and applications of first-order systems of Stieltjes differential equations. *Adv. Nonlinear Anal.* **2017**, *6*, 13–36.
10. Kamenskii, M.; Obukhovskii, V.; Zecca, P. *Condensing Multivalued Maps and Semilinear Differential Inclusions in Banach Spaces*; Walter de Gruyter: Berlin, Germany; New York, NY, USA, 2001.
11. López, P.R.; Márquez, A.I.; Rodríguez, L.J. Solvability of non-semicontinuous systems of Stieltjes differential inclusions and equations. *Adv. Differ. Equ.* **2020**, *2020*, 227.
12. Marraffa, V.; Satco, B. Stieltjes Differential Inclusions with Periodic Boundary Conditions without Upper Semicontinuity. *Mathematics* **2022**, *10*, 55.
13. Monteiro, G.A.; Satco, B. Extremal solutions for measure differential inclusions via Stieltjes derivatives. *Adv. Differ. Equ.* **2019**, *2019*, 239.
14. O'Regan, D.; Precup, R. Fixed point theorems for set-valued maps and existence principles for integral inclusions. *J. Math. Anal. Appl.* **2000**, *245*, 594–612.
15. Samko, S.; Kilbas, A.; Marichev, O.I. *Fractional Integrals and Derivatives (Theorie and Applications)*; Gordon and Breach Science Publishers: Yverdon, Switzerland, 1993.

Disclaimer/Publisher's Note: The statements, opinions and data contained in all publications are solely those of the individual author(s) and contributor(s) and not of MDPI and/or the editor(s). MDPI and/or the editor(s) disclaim responsibility for any injury to people or property resulting from any ideas, methods, instructions or products referred to in the content.