



Proceeding Paper

Generic Riemannian Maps From Nearly Kaehler Manifold [†]

Richa Agarwal * and Shahid Ali

Department of Mathematics, Faculty of Sciences, Aligarh Muslim University (AMU), Aligarh 202002, India; richa.shahido7@gmail.com

* Correspondence: richa.agarwal262@gmail.com

† Presented at the 1st International Online Conference on Mathematics and Applications; Available online: <https://iocma2023.sciforum.net/>.

Abstract: In order to generalise semi-invariant Riemannian map, B. Sahin [1] first introduced the idea of “Generic Riemannian maps”. We extend the idea of generic Riemannian maps to the case in which the total manifold is nearly Kaehler manifold. We study the integrability conditions for the horizontal distribution although vertical distribution is always integrable. We also study the geometry of foliations of two distributions and obtain the necessary and sufficient condition for generic Riemannian maps to be totally geodesic. Additionally, we study the generic Riemannian map with umbilical fibers.

Keywords: nearly Kaehler manifold; Riemannian maps; generic Riemannian maps; anti-invariant; semi-invariant Riemannian maps and product manifolds

1. Introduction

The idea of a Riemannian map between Riemannian manifolds play a key role in differential geometry and this idea was first introduced by Fischer [2] as a generalization of the notions of an isometric immersion and a Riemannian submersion.

Let us consider the smooth map $F : (\mathcal{M}, g_{\mathcal{M}}) \rightarrow (\mathcal{B}, g_{\mathcal{B}})$ between Riemannian manifolds $(\mathcal{M}, g_{\mathcal{M}})$ and $(\mathcal{B}, g_{\mathcal{B}})$. Then the tangent bundle of \mathcal{M} has the following decomposition

$$T\mathcal{M} = (\ker F_*) \oplus (\ker F_*)^\perp,$$

where the kernel space of F_* is denoted by $\ker F_*$ and its orthogonal complement is denoted by $(\ker F_*)^\perp$. We denote range space of F_* by $\text{rang} F_*$ and its orthogonal complement by $(\text{rang} F_*)^\perp$. Then the tangent bundle $T\mathcal{B}$ of \mathcal{B} has following decomposition

$$T\mathcal{B} = (\text{rang} F_*) \oplus (\text{rang} F_*)^\perp.$$

There are many articles on the geometry of Riemannian map [2,3]. In this paper, we introduce and study generic Riemannian maps from nearly Kaehler manifolds to Riemannian manifolds.

2. Preliminaries

In this section we recall some fundamentals of almost Hermitian manifold, Kaehler manifold, nearly Kaehler manifold and give a brief review of Riemannian maps and generic Riemannian maps.

Let \mathcal{M} be an almost complex manifold with an almost complex structure J and a Riemannian metric $g_{\mathcal{M}}$ satisfying the condition

$$g_{\mathcal{M}}(JX, JY) = g_{\mathcal{M}}(X, Y), \tag{1}$$



Citation: Agarwal, R.; Ali, S. Generic Riemannian Maps From Nearly Kaehler Manifold. *Comput. Sci. Math. Forum* **2023**, *1*, 0. <https://doi.org/>

Academic Editor:

Published: 28 April 2023



Copyright: © 2023 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (<https://creativecommons.org/licenses/by/4.0/>).

for all $X, Y \in \Gamma(TM)$. Then \mathcal{M} is called an almost Hermitian manifold. Let ∇ be the Levi-civita connection on almost Hermitian manifold \mathcal{M} , then \mathcal{M} is called a Kaehler manifold if

$$(\nabla_X J)Y = 0, \tag{2}$$

and \mathcal{M} is called a nearly Kaehler manifold if the tensor field ∇J is skew symmetric, i.e.,

$$(\nabla_X J)Y + (\nabla_Y J)X = 0, \tag{3}$$

for all $X, Y \in \Gamma(TM)$.

Let $F : (\mathcal{M}, g_{\mathcal{M}}) \rightarrow (\mathcal{B}, g_{\mathcal{B}})$ be a Riemannian map between Riemannian manifolds. Then the geometry of Riemannian maps is characterized by the tensor field T and A , which are B.O'Neils fundamental tensor fields defined for the Riemannian submersion. For arbitrary vector fields E and F , the tensor fields T and A is defined as:

$$A_E F = \mathcal{H}\nabla_{\mathcal{H}E}\mathcal{V}F + \mathcal{V}\nabla_{\mathcal{H}E}\mathcal{H}F, \tag{4}$$

$$T_E F = \mathcal{H}\nabla_{\mathcal{V}E}\mathcal{V}F + \mathcal{V}\nabla_{\mathcal{V}E}\mathcal{H}F. \tag{5}$$

Using (4) and (5), we have following Lemma

Lemma 1 ([4]). *Let $X, Y \in \Gamma(\ker F_*)^\perp$ and $U, V \in \Gamma(\ker F_*)$, we have*

$$\nabla_U V = T_U V + \hat{\nabla}_U V, \tag{6}$$

$$\nabla_U X = \mathcal{H}\nabla_U X + T_U X, \tag{7}$$

$$\nabla_X U = A_X U + \mathcal{V}\nabla_X U, \tag{8}$$

$$\nabla_X Y = \mathcal{H}\nabla_X Y + A_X Y, \tag{9}$$

where $\hat{\nabla}_U V = \mathcal{V}\nabla_U V$.

3. Generic Riemannian Maps

In this section we define generic Riemannian maps. We investigate the integrability of the leaves of distribution and obtain the necessary and sufficient conditions for such maps to be totally geodesic. For such maps, we also obtain decomposition theorem for total manifold.

First, we recall the following definition [1].

Definition 1. *Let us consider a Riemannian map F from an almost Hermitian manifold $(\mathcal{M}, g_{\mathcal{M}}, J)$ to a Riemannian manifold $(\mathcal{B}, g_{\mathcal{B}})$. If the dimension \mathcal{D}_p is constant along \mathcal{M} and it defines a differentiable distribution on \mathcal{M} , then we say that F is a generic Riemannian map, where \mathcal{D}_p is the complex subspace of the vertical space where $p \in \mathcal{M}$.*

For a generic Riemannian map,

$$\ker F_* = \mathcal{D} \oplus \mathcal{D}^\perp, \tag{10}$$

where \mathcal{D}^\perp is the orthogonal complementary distribution of \mathcal{D} in $\Gamma(\ker F_*)$. For any $U \in \Gamma(\ker F_*)$ by the definition of generic Riemannian map, we write

$$JU = \phi U + \omega U, \tag{11}$$

where $\phi U \in (\ker F_*)$ and $\omega U \in \Gamma(\ker F_*)^\perp$.

We denote the orthogonal complementary distribution of $\omega \mathcal{D}^\perp$ in $\Gamma(\ker F_*)^\perp$ by μ . Thus, for any $X \in \Gamma(\ker F_*)^\perp$, we write

$$JX = BX + CX, \tag{12}$$

where $BX \in \Gamma(\mathcal{D})^\perp$ and $CX \in \Gamma(\mu)$.

Using (10), for $U \in \Gamma(\ker F_*)$, we set

$$JU = P_1U + P_2U + \omega U, \tag{13}$$

where the orthogonal projections from $\ker F_*$ to \mathcal{D} and \mathcal{D}^\perp are P_1 and P_2 respectively.

The covariant derivative of a $(1, 1)$ tensor field J was firstly defined by S. Ali and T. Fatima [5]. For any arbitrary tangent vector fields E and F on \mathcal{M} we set

$$(\nabla_E J)F = P_E F + Q_E F, \tag{14}$$

where $P_E F$ and $Q_E F$ denote the horizontal and the vertical part of $(\nabla_E J)F$ respectively. If \mathcal{M} is nearly Kaehler manifold then

$$P_E F = -P_F E, \quad Q_E F = -Q_F E. \tag{15}$$

Now we investigate the integrability of distribution.

Theorem 1. *Let $F : (\mathcal{M}, g_{\mathcal{M}}, J) \longrightarrow (\mathcal{B}, g_{\mathcal{B}})$ be a generic Riemannian map from nearly Kaehler manifold $(\mathcal{M}, g_{\mathcal{M}}, J)$ to a Riemannian manifold $(\mathcal{B}, g_{\mathcal{B}})$. Then the distribution \mathcal{D}^\perp is integrable if and only if*

$$\hat{\nabla}_V P_2 U - \hat{\nabla}_U P_2 V + T_V \omega U - T_U \omega V + 2Q_V U \in \Gamma(\mathcal{D})^\perp,$$

for any $U, V \in \Gamma(\mathcal{D})^\perp$.

Proof. For any $U, V \in \Gamma(\mathcal{D})^\perp$, on using Lemma 1 and Equations (10), (11) and (13)–(15), we get

$$\begin{aligned} [U, V] = & \phi(\hat{\nabla}_V P_2 U - \hat{\nabla}_U P_2 V + T_V \omega U - T_U \omega V + 2Q_V U) \\ & + \omega(\hat{\nabla}_V P_2 U - \hat{\nabla}_U P_2 V + T_V \omega U - T_U \omega V + 2Q_V U) \\ & + B(T_V P_2 U - T_U P_2 V + \mathcal{H}\nabla_V \omega U - \mathcal{H}\nabla_U \omega V + 2P_V U) \\ & + C(T_V P_2 U - T_U P_2 V + \mathcal{H}\nabla_V \omega U - \mathcal{H}\nabla_U \omega V + 2P_V U). \end{aligned} \tag{16}$$

For any $U, V \in \Gamma(\mathcal{D})^\perp \subset \Gamma(\ker F_*)$. Since $\Gamma(\ker F_*)$ is integrable, therefore $[U, V] \in \Gamma(\ker F_*)$. Comparing the vertical part in (16) we get the result. \square

On similar lines we prove the following.

Theorem 2. *Let $F : (\mathcal{M}, g_{\mathcal{M}}, J) \longrightarrow (\mathcal{B}, g_{\mathcal{B}})$ be a proper generic Riemannian map from a nearly Kaehler manifold $(\mathcal{M}, g_{\mathcal{M}}, J)$ to a Riemannian manifold $(\mathcal{B}, g_{\mathcal{B}})$. Then the distribution \mathcal{D} is integrable if and only if*

$$\begin{aligned} & \hat{\nabla}_U P_1 V - \hat{\nabla}_V P_1 U - 2Q_U V \in \Gamma(\mathcal{D}), \\ \text{and } & T_U P_1 V - T_V P_1 U - 2P_U V \in \Gamma(\mu), \end{aligned}$$

for $U, V \in \Gamma(\mathcal{D})$.

We now study the geometry of the leaves of distributions \mathcal{D} and \mathcal{D}^\perp , we have following propositions.

Proposition 1. Let $F : (\mathcal{M}, g_{\mathcal{M}}, J) \longrightarrow (\mathcal{B}, g_{\mathcal{B}})$ be a generic Riemannian map from a nearly Kaehler manifold $(\mathcal{M}, g_{\mathcal{M}}, J)$ to a Riemannian manifold $(\mathcal{B}, g_{\mathcal{B}})$. Then the distribution \mathcal{D} defines a totally geodesic foliation in \mathcal{M} if and only if

- (i) $\hat{\nabla}_X P_2 Z + T_X \omega Z - Q_X Z$ has no component in \mathcal{D} for $X \in \Gamma(\mathcal{D})$ and $Z \in \Gamma(\mathcal{D})^\perp$.
- (ii) $\hat{\nabla}_X B W + T_X C W - Q_X Z$ has no component in \mathcal{D} for $X \in \Gamma(\mathcal{D})$ and $W \in \Gamma(\ker F_*)^\perp$.

Proof. For $X, Y \in \Gamma(\mathcal{D}), Z \in \Gamma(\mathcal{D})^\perp$, using Equations (1) and (13)–(15) and Lemma 1 we get

$$g_{\mathcal{M}}(\nabla_X Y, Z) = -g_{\mathcal{M}}(\hat{\nabla}_X P_1 Z + T_X \omega Z - Q_X Z, JY). \tag{17}$$

Now, for $X, Y \in \Gamma(\mathcal{D})$ and $W \in \Gamma(\ker F_*)^\perp$, using again Equations (1) and (13)–(15) and Lemma 1 we get

$$g_{\mathcal{M}}(\nabla_X Y, W) = -g_{\mathcal{M}}(\hat{\nabla}_X B W + T_X C W - Q_X W, JY). \tag{18}$$

From Equations (17) and (18) we get the required result. \square

Proposition 2. Let $F : (\mathcal{M}, g_{\mathcal{M}}, J) \longrightarrow (\mathcal{B}, g_{\mathcal{B}})$ be a generic Riemannian map from a nearly Kaehler $(\mathcal{M}, g_{\mathcal{M}}, J)$ to a Riemannian manifold $(\mathcal{B}, g_{\mathcal{B}})$. Then the distribution \mathcal{D}^\perp defines a totally geodesic foliation if and only if

- (i) $\hat{\nabla}_U P_2 V + T_U \omega V - Q_U V = 0$,
- (ii) $CT_U P_2 V + CH \nabla_U \omega V - CP_U V$ has no components in μ , for $U, V \in \Gamma(\mathcal{D})^\perp$.

From Propositions 1 and 2 we have the following decomposition theorem.

Theorem 3. Let $F : (\mathcal{M}, g_{\mathcal{M}}, J) \longrightarrow (\mathcal{B}, g_{\mathcal{B}})$ be a generic Riemannian map from nearly Kaehler manifold $(\mathcal{M}, g_{\mathcal{M}}, J)$ to a Riemannian manifold $(\mathcal{B}, g_{\mathcal{B}})$. Then the fibers are locally product Riemannian manifold of the form $\mathcal{M}_{\mathcal{D}} \times \mathcal{M}_{\mathcal{D}^\perp}$ if and only if,

- (i) $\hat{\nabla}_Y P_2 U + T_Y \omega U - Q_Y U = 0$ for $Y \in \Gamma(\ker F_*)$ and $U \in \Gamma(\mathcal{D})^\perp$.
- (ii) $CT_U P_2 V + CH \nabla_U \omega V - CP_U V$ has no component in μ , $V \in \Gamma(\mathcal{D})^\perp$.
- (iii) $\hat{\nabla}_X B W + T_X C W - Q_X Z$ has no component in \mathcal{D} for $X \in \Gamma(\mathcal{D})$ and $W \in \Gamma(\ker F_*)^\perp$.
- (iv) $\hat{\nabla}_X P_2 Z + T_X \omega Z - Q_X Z$ has no component in \mathcal{D} for $X \in \mathcal{D}$ and $Z \in \mathcal{D}^\perp$.

Proposition 3. Let $F : (\mathcal{M}, g_{\mathcal{M}}, J) \longrightarrow (\mathcal{B}, g_{\mathcal{B}})$ be a generic Riemannian map from a nearly Kaehler manifold $(\mathcal{M}, g_{\mathcal{M}}, J)$ to a Riemannian manifold $(\mathcal{B}, g_{\mathcal{B}})$. Then the distribution $(\ker F_*)^\perp$ defines a totally geodesic foliation in \mathcal{M} if and only if,

$$T_V \phi W + H \nabla_V \omega W + P_W V \in \Gamma(\omega \mathcal{D}^\perp),$$

$$\text{and } \hat{\nabla}_V \phi W + T_V \omega W + Q_W V \in \Gamma(\mathcal{D}),$$

for any $V, W \in \Gamma(\ker F_*)$.

Proposition 4. Let $F : (\mathcal{M}, g_{\mathcal{M}}, J) \longrightarrow (\mathcal{B}, g_{\mathcal{B}})$ be a generic Riemannian map from a nearly Kaehler manifold $(\mathcal{M}, g_{\mathcal{M}}, J)$ to a Riemannian manifold $(\mathcal{B}, g_{\mathcal{B}})$. Then the distribution $(\ker F_*)^\perp$ defines a totally geodesic foliation in \mathcal{M} if and only if

$$BA_X B Y + BH \nabla_X C Y + B P_Y X = -\phi \hat{\nabla}_X B Y - \phi A_X C Y - \phi Q_Y X,$$

for $X, Y \in (\ker F_*)^\perp$.

Proof. Let $X, Y \in (\ker F_*)^\perp$. Using Equations (11), (12), (14) and (15) and Lemma 1 we get

$$\begin{aligned}\nabla_X Y = & -B(A_X B Y + \mathcal{H} \nabla_X C Y + P_Y X) \\ & -C(A_X B Y + \mathcal{H} \nabla_X C Y + P_Y X) \\ & -\phi(\hat{\nabla}_X B Y + A_X C Y + Q_Y X) \\ & -\omega(\hat{\nabla}_X B Y + A_X C Y + Q_Y X).\end{aligned}\quad (19)$$

From Equation (19) we get the result. \square

We recall a Riemannian map with totally umbilical fibers if

$$T_U V = g_{\mathcal{M}}(U, V)H,$$

for all $U, V \in \Gamma(\ker F_*)$, where H is the mean curvature vector of the fibers.

We have

Theorem 4. Let $F : (\mathcal{M}, g_{\mathcal{M}}, J) \rightarrow (\mathcal{B}, g_{\mathcal{B}})$ be a generic Riemannian map with totally umbilical fibers from a nearly Kaehler manifold $(\mathcal{M}, g_{\mathcal{M}}, J)$ onto a Riemannian manifold $(\mathcal{B}, g_{\mathcal{B}})$. Then $H \in \Gamma(\omega \mathcal{D})^\perp$.

Author Contributions:

Funding:

Institutional Review Board Statement:

Informed Consent Statement:

Data Availability Statement:

Conflicts of Interest: The authors declare no conflict of interest.

References

1. Sahin, B. Generic Riemannian maps. *Miskole Math. Notes* **2017**, *18*, 453–467.
2. Fischer, A.E. Riemannian maps between Riemannian manifolds. *Contemp. Math.* **1992**, *132*, 331–336.
3. Sahin, B. Conformal Riemannian maps between Riemannian manifolds, their harmonicity and decomposition theorem. *Acta Appl.* **2010**, *109*, 829–847.
4. O’Neill, B. The fundamental equations of submersion. *Mich. Math. J.* **1966**, *13*, 458–469.
5. Ali, S.; Fatima, T. Anti-invariant Riemannian submersion from Nearly Kaehler manifolds. *Filomat* **2013**, *27*, 1219–1235.

Disclaimer/Publisher’s Note: The statements, opinions and data contained in all publications are solely those of the individual author(s) and contributor(s) and not of MDPI and/or the editor(s). MDPI and/or the editor(s) disclaim responsibility for any injury to people or property resulting from any ideas, methods, instructions or products referred to in the content.