Combining COMSOL modelling with different Piezoelectric Materials to design MEMS cantilevers for marine sensing robotic

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Outline

Introduction and objective of work, Approach/Bionic Principle/Application

Designing of Piezoelectric Cantilevers on COMSOL

Simulation and modeling of Cantilevers

Result

Aim of the Work
Novelty

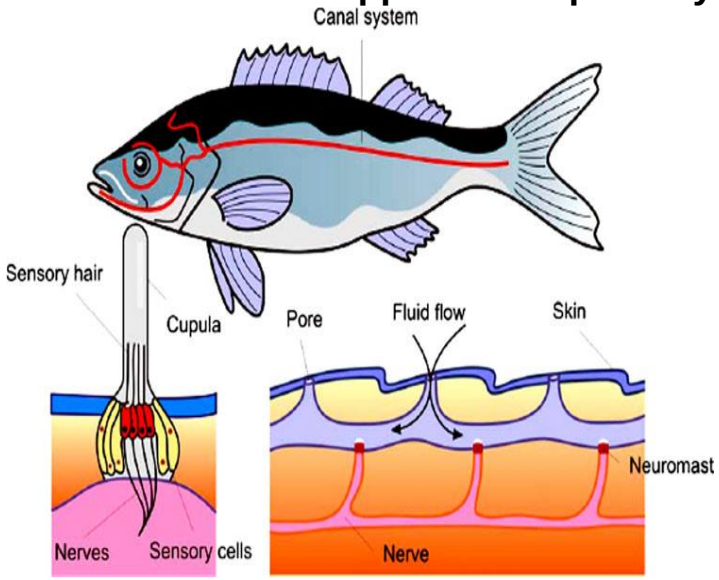
- ✓ **To design an innovative transducer by piezoelectric materials which will sense the intensity and directionality of underwater acoustic pulses.**

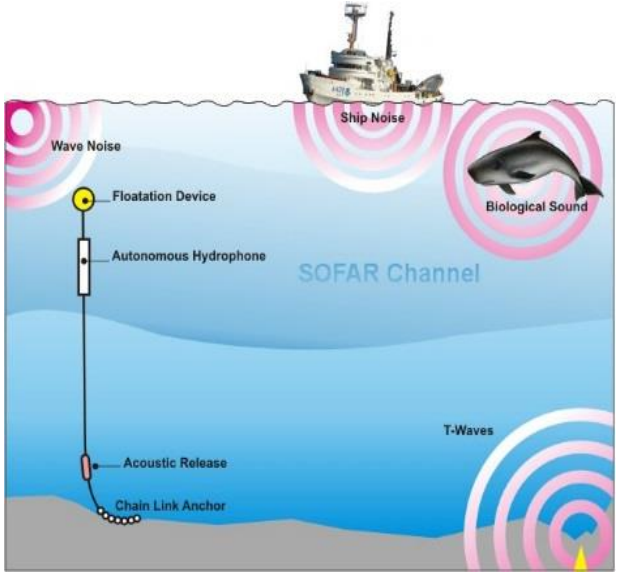
- ✓ **The device will have a wider frequency range. This wider frequency range is necessary for the dynamic range of signals for marine sensing acoustics.**

- ✓ **It will show a good directionality pattern, which helps to detect the acoustics source direction in the water.**

Approach/Bionic Principle/Application

- ➢ **A biomimetic approach inspired by Fish lateral line system**





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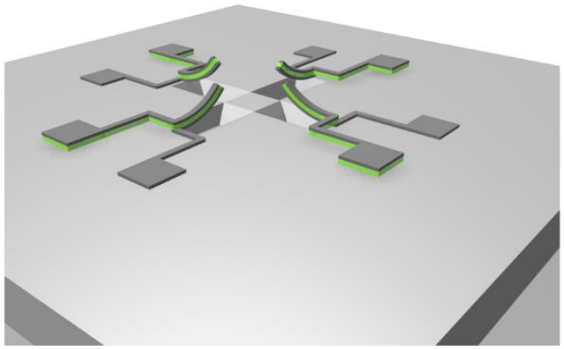
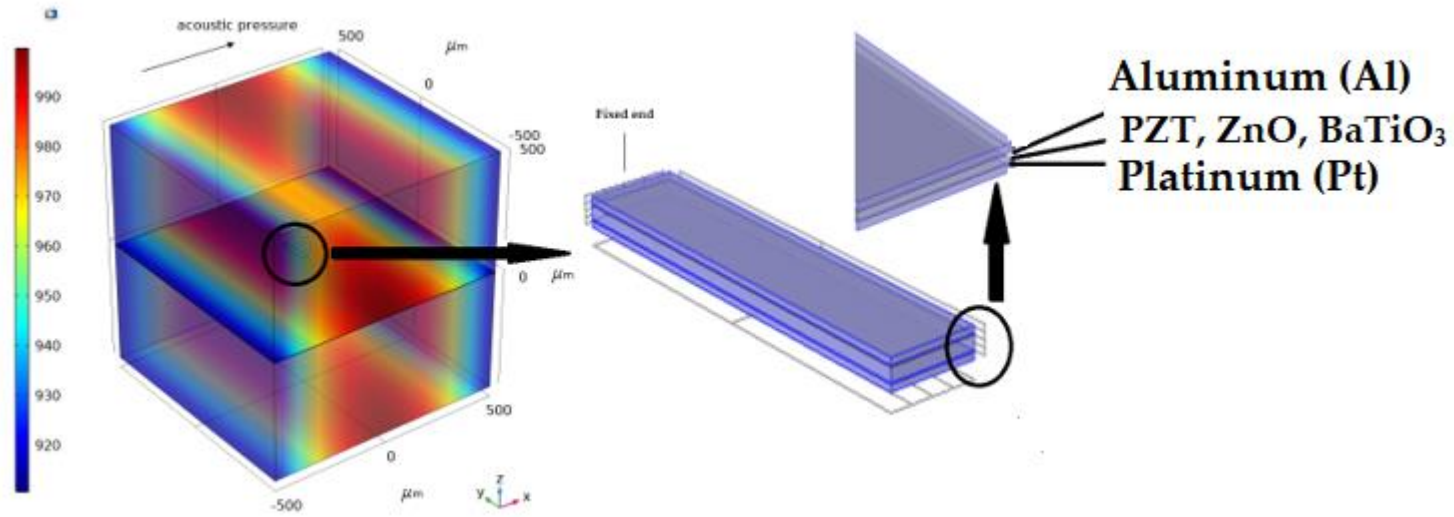


Materials Properties

Materials	Thickness
Platinum (Pt)	200 nm
Aluminum (Al)	200 nm
PZT, ZnO, BaTiO3	1 µm

Dimension

Length (µm)	Width (µm)
100,200,300,40,500,600,700,800900,1000	50



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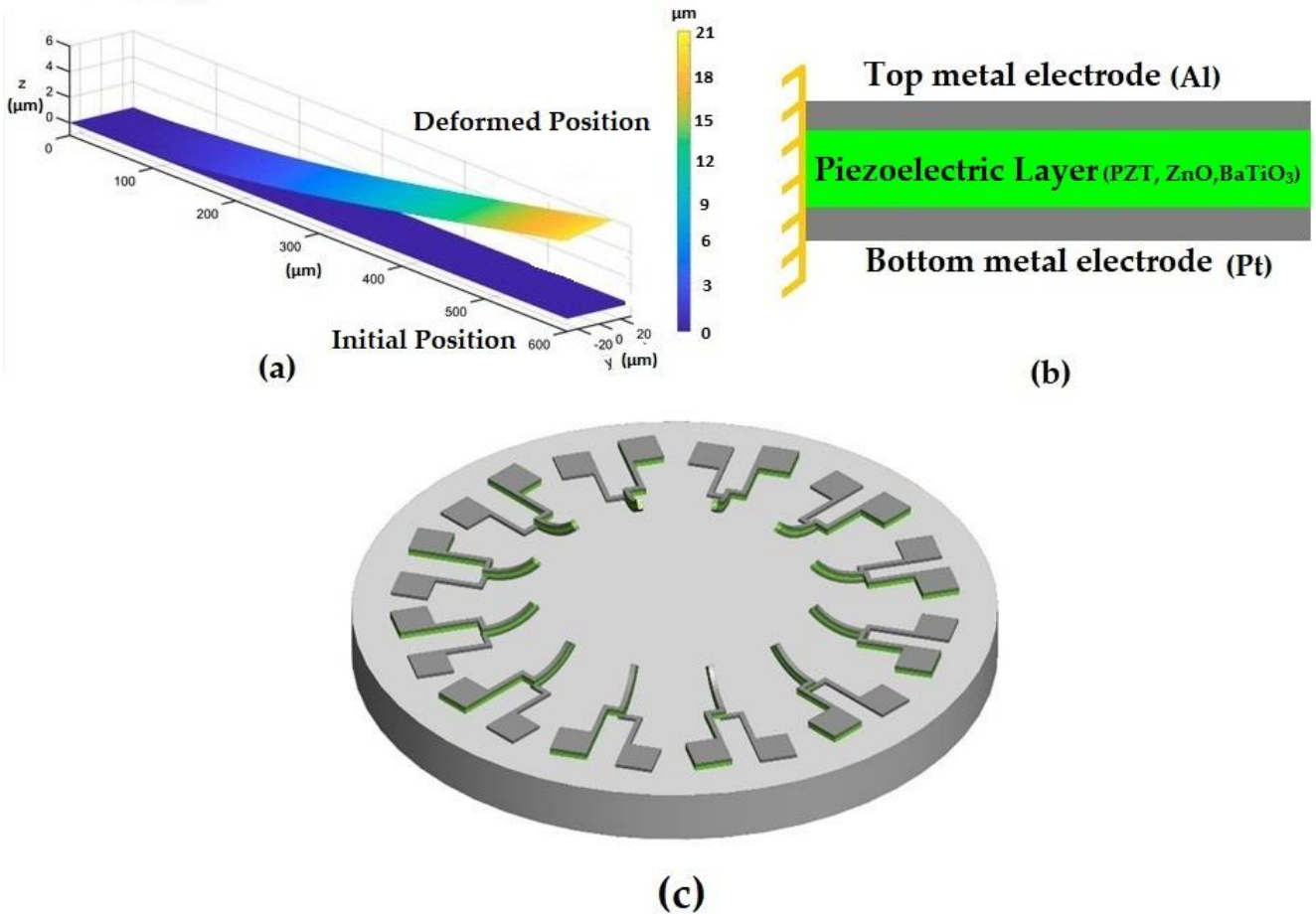

Figure 2. (a) Simulated microcantilever with deformed position. (b) Side view of micro cantilevers (C) Face to face configuration of microcantilever.

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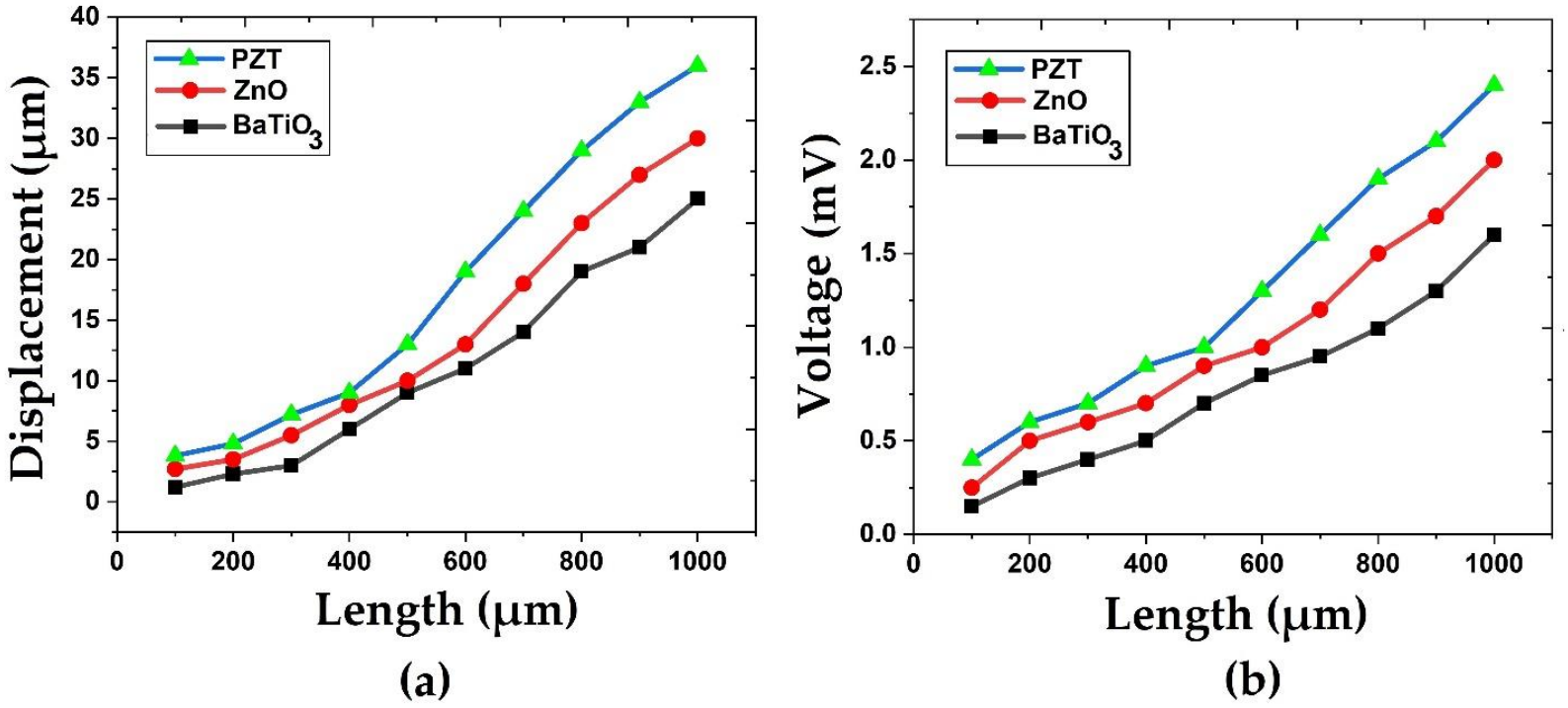

Figure 2. (a) Microcantilevers displacement vs Length with different piezoelectric materials (b) Microcantilever Voltage response vs Length with different piezoelectric materials