

DYNAMICS AND BIFURCATION ANALYSIS OF AN ECO-EPIDEMIOLOGICAL MODEL IN CROWLEY-MARTIN FUNCTIONAL RESPONSE WITH THE IMPACT OF FEAR

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Abstract: This article consists of a three-species food web model that has been developed by considering the interaction between susceptible prey, infected prey, and predator species. It is assumed that susceptible prey species grow logistically in the absence of predators. It is assumed that predators consume susceptible and infected prey and infected prey consumes susceptible prey. Furthermore, the predator consumes its prey in the form of Holling-type and Crowley-Martin-type interactions. Also, infected prey consumes susceptible prey in the form of Holling-type interaction. The positive invariance, positivity, and boundedness of the system are discussed. The conditions of all biologically feasible equilibrium points have been examined. The local stability of the systems around these equilibrium points is investigated and global stability is analyzed by suitable Lyapunov functions around these equilibrium points. Furthermore, the occurrence of Hopf-bifurcation concerning predation rate of the system has been investigated. Finally, we demonstrate some numerical simulation results to illustrate our main analytical findings.

Keywords: Infected prey, Crowley-Martin, Equilibrium point, Stability, Bifurcation

1. Introduction

Eco-epidemiological systems are used to investigate the dynamic connection between predator and prey in one population or a population of susceptible and infected animals. Mathematical models have become significant instruments in examining the flow and manipulation of prevention. Since Kermack-Mckendrick's pioneering work on SIRS [3], epidemiological models have drawn a lot of interest from researchers. Ecology and epidemiology are two distinct essential and significant areas of research. Lotka [4] and Volterra [5] models, The first advance in current mathematical ecology can be examined using the system of dynamical equations. It is referred to as the study of infection spread between interacting organisms. A biological representation in terms of mathematical modelling of communications among the populations density of predators and population density of prey, called "functional response". Modelling in biological systems There are numerous of functional responses namely the Holling type [1,2], type of Beddington-DeAngelis responses, type of Crowley-Martin responses; Arditi and Ginzburg's [7] much more information on predator-prey systems with Crowley-Martin functional responses has become available in recent decades. In the recent era, some renowned authors [6]. They used some functional responses such as type of Crowley-Martin functional response to make the model system, more realistic and controllable in the eco-system. To the best of our knowledge, no one has examined a three-species food web eco-epidemiological model with Holling type I, II, and Crowley-Martin functional responses, along with the disease on prey populations. Motivated by this fact, we explore a three-species food web eco-epidemiological model with Holling type I, Holling type II, and Crowley-Martin functional responses with infection in the prey population. The occurrence of Hopf bifurcation analysis for the proposed

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model in relation to the existence of the infection rate. The rest of the paper is structured as follows: In Section 2, we present the mathematical analysis that has been investigated. Section 3 deals with the point of equilibrium in boundary and their stability. In Sections 4 we determine the existence of the interior point of equilibria $E^*(s^*, i^*, p^*)$ and investigate its local stability. The occurrence of Hopf-bifurcation is shown in Section 5. Numerical simulations are examined for the proposed model in Section 6. Section 7, which concludes the paper.

2. Model formation

The framework demonstrates the relationship between the population density of prey with infection. Which leads to the following structure of non-linear differential equations. The suggested framework was applied to examine the non-linear population density of susceptible, infected prey and predator biological model,

$$\left. \begin{aligned} \frac{dS}{dT} &= r_1 S \left(1 - \frac{S+I}{K}\right) - \lambda I S - \frac{\alpha_1 S P}{(1+\zeta S)(1+\eta P)}, \\ \frac{dI}{dT} &= \lambda I S - d_1 I - \frac{b_1 I P}{a_1 + I}, \\ \frac{dP}{dT} &= -d_2 P + \frac{c b_1 I P}{a_1 + I} + \frac{c \alpha_1 S P}{(1+\zeta S)(1+\eta P)}. \end{aligned} \right\} \tag{1}$$

In the above biological systems the susceptible prey population, infected prey population and population of predator. The table(1) displays specific biological meanings of the parameters.

Table 1. specific biological meanings of the parameters(1).

Parameters	Units	Physiological representation
S	Components per unit area (tons)	Population density of susceptible Prey
I	Components per unit area (tons)	Population density of prey with infection
P	Components per unit area (tons)	Population density of Predator
r_1	Per day (T^{-1})	Prey population densities growth rate
K	Components per unit area (tons)	The carrying
λ	Per day (T^{-1})	Infection rate
a	Per day (T^{-1})	Constant of Half-saturation
α_1	Per day (T^{-1})	Susceptible prey to predator consumption
b_1	Per day (T^{-1})	Capture rate by predator
c	Per day (T^{-1})	Conversion rate of prey to predator
d_1, d_2	Per day (T^{-1})	Diseased prey and predator death rate
ζ, η	Per day (T^{-1})	Constant of feeding rate

In system(1) has many parameters with different units its inconvenient to solve the systems (1), so in our convenient we reduce the system in to non-dimensional equations using the following transformations Here, $s = \frac{S}{K}, i = \frac{I}{K}, p = \frac{P}{K}$, with non-dimensional time $t = \lambda K T$ Now the (1) becomes,

$$\left. \begin{aligned} \frac{ds}{dt} &= r s (1 - s - i) - i s - \frac{s a p}{(1+\zeta s)(1+\eta p)} \\ \frac{di}{dt} &= i s - d i - \frac{\theta i p}{a+i} \\ \frac{dp}{dt} &= -\delta p + \frac{c \theta i p}{a+i} + \frac{c \alpha s p}{(1+\zeta s)(1+\eta p)}. \end{aligned} \right\} \tag{2}$$

here the conditions are, $r = \frac{r_1}{\lambda K}, \alpha = \frac{\alpha_1}{\lambda K}, d = \frac{d_1}{\lambda K}, \theta = \frac{b_1}{\lambda K}, \delta = \frac{d_2}{\lambda K}$. According to the preliminary criteria $\{s(0), i(0), p(0)\} \geq 0$. The described over are in \mathbb{R}_+^3 .

3. The existence point of equilibrium

The system (2) has three points of equilibrium and one endemic point of equilibrium .

- The $E_0(0, 0, 0)$ is the point of equilibrium, which is trivial,

- $E_1(1, 0, 0)$ be the free of infection and free of predator point of equilibrium . 61
- The absence of predator point of equilibrium is $E_2(\hat{s}, \hat{i}, 0)$, 62
 where, $\hat{s} = d, \hat{i} = \frac{r(1-d)}{r+1}$, its exists for $r(1-d) > 1$ 63
- endemic equilibrium is $E^*(s^*, i^*, p^*)$, where, $i^* = \frac{a(a\delta + (\delta - c\alpha)s^*)}{(c\alpha s^* + (c\theta - \delta)(1 + \zeta s^*)(1 + \eta p^*))}$, 64
 $p^* = \frac{ac(s^* - d)(1 + \zeta s^*)}{(c\alpha s^* + (c\theta - \delta)(1 + \zeta s^*))}$, and the s^* is the quadratic equation's one and only positive 65
 root, $AS^2 + BS + C = 0$, where, 66

$$A = r(\alpha c + \theta c - \delta), B = (\theta c - \delta)(ar - r) + \alpha c(-r) + a(\delta + (\delta - c\alpha)r),$$

$$C = -a(r)(c\theta - \delta) + (c\alpha(d) - a\delta(+r)).$$

If endemic equilibrium exist for $\delta > \alpha c, r > 1, s^* - d > \frac{(1+r)a\delta}{a\alpha}$, and $a\delta + s^*(\delta - \alpha c)$. 67

4. local stability analysis 68

I. We begin by determining the system's (2) Jacobian matrix. $J(E) = \begin{pmatrix} n_{11} & n_{12} & n_{13} \\ n_{21} & n_{22} & n_{23} \\ n_{31} & n_{32} & n_{33} \end{pmatrix}$. 69

Where, 70

$$n_{11} = r(1 - 2s) - i(r + 1) - \frac{\alpha p}{(1 + \zeta s)^2(1 + \eta p)}, n_{12} = -s(r + 1),$$

$$n_{13} = prs(1 - s - i) - \frac{\alpha s}{(1 + \zeta s)(1 + \eta p)^2}, n_{21} = i, n_{22} = s - d - \frac{a\theta p}{(a + i)^2},$$

$$n_{23} = -\frac{\theta i}{(a + i)}, n_{31} = \frac{c\alpha p}{(1 + \zeta s)^2(1 + \eta p)}, n_{32} = \frac{ac\theta p}{(a + i)^2}, n_{33} = -\delta + \frac{c\theta i}{a + i} + \frac{\alpha cs}{(1 + \zeta s)(1 + \eta p)^2}.$$

Theorem 1. *The trivial equilibrium point $E_0(0, 0, 0)$ is unstable.* 71

Proof. The Jacobian matrix for $E_0(0, 0, 0)$ is $J(E_0) = \begin{pmatrix} r & 0 & 0 \\ 0 & -d & 0 \\ 0 & 0 & -\delta \end{pmatrix}$, 72

where, the characteristic equation of the above Jacobian matrix is, 73

$$(\lambda_{01} - r)(\lambda_{02} - (-d))(\lambda_{03} + \delta) = 0, \quad \text{74}$$

$$\lambda_{01} = r, \lambda_{02} = -d, \lambda_{03} = -\delta, \quad \text{75}$$

here, $\lambda_{01} > 0$ then the equilibrium point E_0 is unstable. \square 76

Theorem 2. *The infected prey and predator free equilibrium point $E_1(1, 0, 0)$ is unstable due to table value of numerical simulation .* 77

Proof. The Jacobian matrix for E_1 is 79

$$J(E_1) = \begin{pmatrix} -r & -(r + 1) & \frac{-\alpha}{(a+1)} \\ 0 & 1 - d & 0 \\ 0 & 0 & \frac{c\alpha}{a+1} - \delta \end{pmatrix}, \quad \text{80}$$

where, the characteristic equation of the above Jacobian matrix is, 81

$$(\lambda_{11} - (-r))(\lambda_{12} - (1 - d))(\lambda_{13} - (\frac{\alpha c}{a + 1} - \delta)) = 0,$$

$$\lambda_{11} = -r, \lambda_{12} = 1 - d, \lambda_{13} = \frac{-c\alpha}{a + 1} - \delta,$$

here, The infected free and predator free equilibrium point $E_1(1, 0, 0)$ is unstable because $1 - d$ is never negative due to the table () value of numerical simulation. \square 82

Theorem 3. *The equilibrium $E_2(\hat{s}, \hat{i}, 0)$ which absence of predator is asymptotically stable if $\delta > c(\theta + \alpha)$* 84

Proof. The matrix in the form of Jacobian at E_2 is $J(E_2) = \begin{pmatrix} o_{11} & o_{12} & o_{13} \\ o_{21} & o_{22} & o_{23} \\ o_{31} & o_{32} & o_{33} \end{pmatrix}$,

where,

$$o_{11} = r(1 - 2\hat{s}) + i(r + 1), o_{12} = (-1 - r)\hat{s}, o_{13} = -\frac{\alpha\hat{s}}{(1 + \zeta\hat{s})}, o_{21} = \hat{i}, o_{22} = s - d - 2,$$

$$o_{23} = -\frac{\theta\hat{i}}{a + \hat{i}}, o_{31} = 0, o_{32} = 0, o_{33} = \frac{c\alpha\hat{s}}{1 + \zeta\hat{s}} - \delta + \frac{c\theta\hat{i}}{a + \hat{i}}.$$

The E_2 characteristic equation is, $\lambda^3 + \mathcal{T}\lambda^2 + \mathcal{U}\lambda + \mathcal{V} = 0$. Here,

$$\mathcal{T} = -o_{11} - o_{33}, \mathcal{U} = -o_{21}o_{12} + o_{33}o_{11}, \mathcal{V} = o_{12}o_{21}o_{33}.$$

According to the Routh-Hurwitz criterion, if and only if \mathcal{T}, \mathcal{V} and $\mathcal{T}\mathcal{U} - \mathcal{V}$ are non-negative, then the real parts are non-positive roots of the above characteristic equation. Now $\mathcal{T}\mathcal{U} - \mathcal{V} = -o_{11}(-o_{12}o_{21} + o_{33}(o_{33} + o_{11}))$. Now, the necessary criteria for o_{33} to be non-positive is $\delta > c(\alpha + \theta)$. If the above condition in the Theorem is satisfied, the E_2 is locally asymptotically stable. \square

Theorem 4. *The endemic or positive point of equilibrium E^* is asymptotically stable.*

Proof. The matrix in the form of Jacobian at E^* is $J(E^*) = \begin{pmatrix} r_{11} & r_{12} & r_{13} \\ r_{21} & r_{22} & r_{23} \\ r_{31} & r_{32} & r_{33} \end{pmatrix}$, where,

$$r_{11} = -\frac{s^*(1 - r + ar + (1 + r)i^* + 2rs^*)}{(1 + \zeta s^*)^2(1 + \eta p^*)}, r_{12} = -s^*(r + 1),$$

$$r_{13} = p^*rs^*(1 - s^* - i^*) - \frac{\alpha s^*}{(1 + \zeta s^*)(1 + \eta p^*)}, r_{21} = i^*,$$

$$r_{22} = \frac{a\theta p^* i^*}{(a + i^*)^2}, r_{23} = \frac{\theta i^*}{(a + i^*)}, r_{31} = \frac{c\alpha p^*}{((1 + \zeta s^*)^2(1 + \eta p^*))}, r_{32} = \frac{ac\theta p^*}{(a + i^*)^2}, r_{33} = 0.$$

The E^* characteristic equation is

$$\lambda^3 + \mathcal{F}\lambda^2 + \mathcal{G}\lambda + \mathcal{H} = 0, \quad (3)$$

here, $\mathcal{F} = -r_{11} - r_{33}, \mathcal{G} = -r_{21}r_{12} + r_{22}r_{11} - r_{13}r_{31} + r_{23}r_{32},$
 $\mathcal{H} = r_{13}(-r_{22}r_{31} + r_{21}r_{32}) + r_{23}(r_{12}r_{31} - r_{11}r_{32})$. If $\mathcal{F} > 0, \mathcal{H} > 0, \mathcal{F}\mathcal{G} - \mathcal{H} > 0$. According to the Routh-Hurwitz criterion, if and only if $\mathcal{F}, \mathcal{H}, \mathcal{F}\mathcal{G} - \mathcal{H}$ are non-negative, then the real parts are non-positive roots of the above characteristic equation. The E^* is locally asymptotically stable. \square

5. Hopf-Bifurcation Analysis

The periodic solutions arise or depart due to changes in system parameters, which is called Hopf-bifurcation. The eigenvalues of the Jacobian matrix have a negative real part with a complex conjugate, which means bifurcation can occur.

Theorem 5. *If the bifurcation parameter α exceeds a critical point, the model (2) approaches Hopf-bifurcation. At $\alpha = \alpha^*$, the following Hopf-bifurcation conditions arise:*

1. $\mathcal{A}_1(\alpha^*)\mathcal{A}(\alpha^*) - \mathcal{A}_3(\alpha^*) = 0$.
2. $\frac{d}{d\alpha}(\text{Re}(\lambda(\alpha)))|_{\alpha=\alpha^*} \neq 0$ Here λ is the root of the parametric solution correlated with the equilibrium interior point.

Proof. For $\alpha = \alpha^*$, the characteristic (3) is in the form

$$(\lambda^2(\alpha^*) + \mathcal{A}_2(\alpha^*))(\lambda(\alpha^*) + \mathcal{A}_1(\alpha^*)) = 0. \quad (4)$$

This indicates that the roots of the preceding equation are $\pm i\sqrt{\mathcal{A}_2(\alpha^*)}$ and $-\mathcal{A}_1(\alpha^*)$. To achieve the Hopf-bifurcation at $\alpha = \alpha^*$ the following transversality criterion must be fulfilled.

$$\frac{d}{d\alpha^*}(\operatorname{Re}(\lambda(\alpha^*))) \neq 0.$$

For α , the above equation (4) has general roots

$$\lambda_1 = r(\alpha) + is(\alpha), \lambda_2 = r(\alpha) - is(\alpha), \lambda_3 = -\mathcal{A}_1(\alpha).$$

Weather check the criteria $\frac{d}{d\alpha^*}(\operatorname{Re}(\lambda(\alpha^*))) \neq 0$. Let $\lambda_1 = r(\alpha) + is(\alpha)$ in the (4), we get $\mathcal{C}(\alpha) + i\mathcal{D}(\alpha) = 0$. Where,

$$\begin{aligned} \mathcal{C}(\alpha) &= r^3(\alpha) + r^2(\alpha)\mathcal{A}_1(\alpha) - 3r(\alpha)s^2(\alpha) - s^2(\alpha)\mathcal{A}_1(\alpha) + \mathcal{A}_2(\alpha)r(\alpha) + \mathcal{A}_1(\alpha)\mathcal{A}_2(\alpha), \\ \mathcal{D}(\alpha) &= \mathcal{A}_2(\alpha)s(\alpha) + 2r(\alpha)s(\alpha)\mathcal{A}_1(\alpha) + 3r^2(\alpha)s(\alpha) + s^3(\alpha). \end{aligned}$$

In order to satisfy the (4) we must have the variables $\mathcal{C}(\alpha) = 0$ and $\mathcal{D}(\alpha) = 0$, then calculating \mathcal{C} and \mathcal{D} with regard to α .

$$\frac{d\mathcal{A}}{d\alpha} = \zeta_1(\alpha)r'(\alpha) - \zeta_2(\alpha)s'(\alpha) + \zeta_3(\alpha) = 0, \quad (5)$$

$$\frac{d\mathcal{B}}{d\alpha} = \zeta_2(\alpha)r'(\alpha) + \zeta_1(\alpha)s'(\alpha) + \zeta_4(\alpha) = 0, \quad (6)$$

where, $\zeta_1 = 3r^2(\alpha) + 2r(\alpha)\mathcal{A}_1(\alpha) - 3s^2(\alpha) + \mathcal{A}_2(\alpha)$, $\zeta_2 = 6r(\alpha)s(\alpha) + 2s(\alpha)\mathcal{A}_1(\alpha)$, $\zeta_3 = r^2(\alpha)\mathcal{A}_1'(\alpha) + s^2(\alpha)\mathcal{A}_1'(\alpha) + \mathcal{A}_2'(\alpha)r(\alpha)$, $\zeta_4 = \mathcal{A}_2'(\alpha)s(\alpha) + 2r(\alpha)s(\alpha)\mathcal{A}_1'(\alpha)$.

On multiplying (5) by $\zeta_1(\alpha)$ and (6) by $\zeta_2(\alpha)$ respectively

$$r(\alpha)' = -\frac{\zeta_1(\alpha)\zeta_3(\alpha) + \zeta_2(\alpha)\zeta_4(\alpha)}{\zeta_1^2(\alpha) + \zeta_2^2(\alpha)}. \quad (7)$$

Substituting $r(\alpha) = 0$ and $s(\alpha) = \sqrt{\mathcal{A}_2(\alpha)}$ at $\alpha = \alpha^*$ on $\zeta_1(\alpha)$, $\zeta_2(\alpha)$, $\zeta_3(\alpha)$, and $\zeta_4(\alpha)$, we obtain $\zeta_1(\alpha^*) = -2\mathcal{A}_2(\alpha^*)$, $\zeta_2(\alpha^*) = 2\mathcal{A}_1(\alpha^*)\sqrt{\mathcal{A}_2(\alpha^*)}$

$\zeta_3(\alpha^*) = \mathcal{A}_3'(\alpha^*) - \mathcal{A}_2(\alpha^*)\mathcal{A}_1'(\alpha^*)$, $\zeta_4(\alpha^*) = \mathcal{A}_2'(\alpha^*)\sqrt{\mathcal{A}_2(\alpha^*)}$. The equation (7), implies

$$r'(\alpha^*) = \frac{\mathcal{A}_3'(\alpha^*) - (\mathcal{A}_1(\alpha^*)\mathcal{A}_2(\alpha^*))'}{2(\mathcal{A}_2(\alpha^*) + \mathcal{A}_1^2(\alpha^*))}, \quad (8)$$

if $\mathcal{A}_3'(\alpha^*) - (\mathcal{A}_1(\alpha^*)\mathcal{A}_2(\alpha^*))' \neq 0$ which implies that $\frac{d}{d\alpha^*}(\operatorname{Re}(\lambda(\alpha^*))) \neq 0$, and $\lambda_3(\alpha^*) = -\mathcal{A}_1(\alpha^*) \neq 0$. Therefore the condition $\mathcal{A}_3'(\alpha^*) - (\mathcal{A}_1(\alpha^*)\mathcal{A}_2(\alpha^*))' \neq 0$ It has been guaranteed that the transversality criterion is satisfied, hence the model (2) has attained the Hopf-bifurcation at $\alpha = \alpha^*$. \square

6. Numerical Simulations

In this section, several numerical experiments on the system (2) are carried out to verify the mathematical findings. The rate of fear ρ is used as a control parameter. For the specified fixed parameter values, the numerical simulation is carried out using the MATLAB/MATHEMATICA software packages. With Runge-Kutta's numerical scheme. Here $r = 0.2$, $\theta = .25$, $d = 0.1$, $\delta = 0.1$, $\zeta = 0.15$, $\eta = 0.15$, $\alpha = \text{variable}$

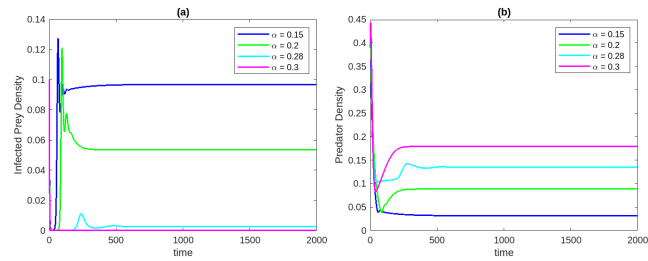


Figure 1. The population concentrations of infected prey, and predators are as follows for the parametric values . Where $\alpha = 0.15, 0.2, 0.28, 0.3$

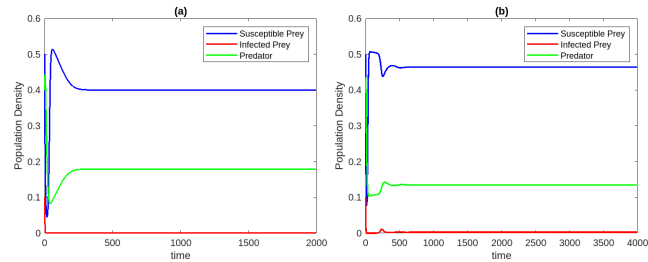


Figure 2. $\alpha = 0.3$, the system's time series solution (2) revolves around the equilibrium point E_2 with the parametric values are given . with the exception of $\alpha = 0.28$, the following time series will be centered on the equilibrium point E^* and will have the same parametric values as in the table().

6.1. Effect of varying the predation rate α

Fix the parameters in above , For the specified parameters, without infection equilibrium point E_2 and the endemic equilibrium point E^* exists for $0.1 < \alpha < 0.35$, respectively, for the given parametric values. The stability of for $\alpha = 0.3$ and $\alpha = 0.28$.

Figure (1) demonstrates an increase in the predation rate α and a decrease in the population of infected prey when the predator population increases .Figure (1) demonstrates an increase in the predation rate α and a decrease in the population of infected prey when the predator population increases . For a predation on susceptible prey of value $\alpha = 0.3$ the model (1) is locally asymptotically stable at $E^*(0.0526548, 0.0395862, 0.04271033)$, in Figure (3). By increasing the value of refuge $\alpha = 0.5$, the model (1) losses its stability and oscillates around $E^*(0.0471160, 0.0260163, 0.0353871)$, arising a limit cycle in figure (4).

To fix the rate of refuge value $\alpha = 0.3$ the model, then the model (1) satisfy the values of transversality conditions for a non-delayed model is $(Re(\lambda(\alpha)))|_{\alpha=\alpha^*} = 0.001528 \neq 0$.

7. Conclusion

We researched an eco-epidemiological system that included infection in the population density of prey and fear in the susceptible prey population density as a result of predator attacks on susceptible and diseased prey. In addition, each biologically possible point of equilibrium can be represented (2). Furthermore, we investigated the suggested model's local stability (2) and observed the occurrence of Hopf-bifurcation, and we determined that modifying the cost of predation rate α has an instantaneous effect on the model's stability (2). As a result, Hopf-bifurcation constrained the developed analytical arguments around

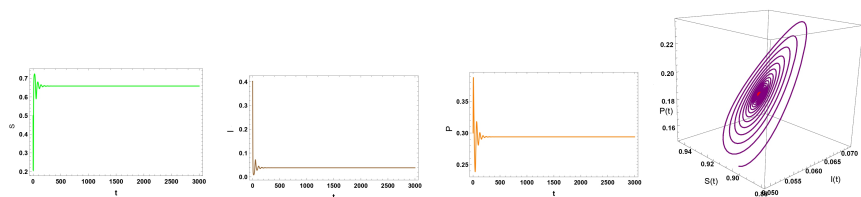


Figure 3. The time analysis of model(2) and phase portrait for the model (2) when $\alpha = 0.3$.

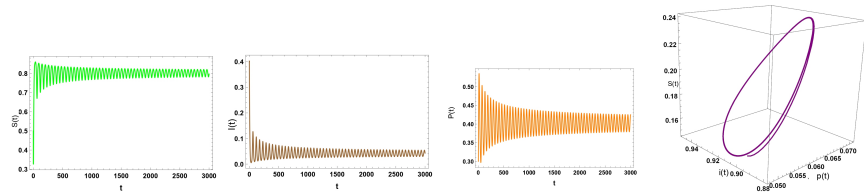


Figure 4. The time analysis of model(2) and phase portrait for the model (2) when $\alpha = 0.6$.

the E^* simulation findings. In the proposed models, we deduce that the existence of dread has a higher impact on stability shifts via the Hopf bifurcation.

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