

# Uncertainty Relations in Non-Hermitian Systems

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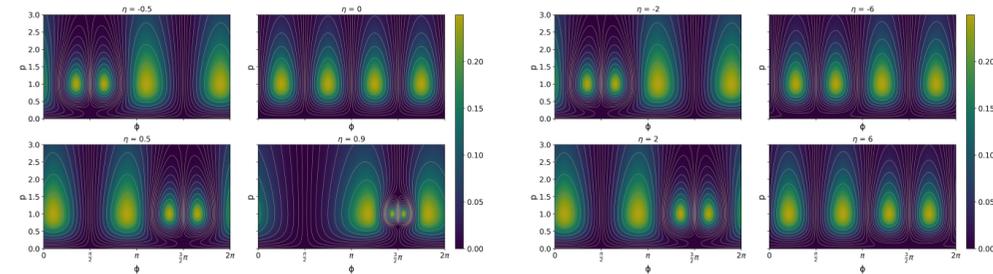
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## INTRODUCTION & GOALS

- ▶ In non-Hermitian dynamics (open systems / gain-loss), standard means and variances can be inconsistent if the usual inner product is not physically appropriate.
- ▶ For pseudo-Hermitian Hamiltonians (including PT symmetry), a metric  $S$  is required to define expectation values, variances, and uncertainty relations consistently.
- ▶ **Main challenge:**  $S$  can become indefinite (broken phase) or singular (exceptional points), motivating a unified framework.
- ▶ **Goal:** Construct suitable metrics in each spectral regime (exact phase, broken phase, EPs) within a **Krein-space approach**, and derive a Heisenberg-Robertson-type inequality valid across all regimes.
- ▶ **Key:** changing the inner product forces a consistent change of representation: the adjoint changes, and with it the effective form of operators and the representation of states, if physical matrix elements are to remain invariant.

## RESULTS & DISCUSSION

Initial state  $|\varphi_0\rangle = (1 + p^2)^{-1/2}(|0\rangle + pe^{i\phi}|1\rangle)$



Contour plots of  $UR(\sigma_x, \sigma_y)$  in the  $(\phi, p)$  plane at  $t = 0$  for different  $\eta$ : left, PT-symmetric region  $\eta^2 < 1$ ; right, broken-symmetry region  $\eta^2 > 1$ .

## Framework: positive metric, observables, and evolution

**Pseudo-Hermiticity:**  $H^\dagger S = SH$ ,  $S = S^\dagger$   
Indefinite form:  $[x, y]_S := \langle x|S|y\rangle$ ,  $A^\# := S^{-1}A^\dagger S$

**Positive metric from  $S$  ("flip signs"):**

$$S = PDP^{-1}, \quad D = \text{diag}(\mu_j), \quad \mu_j \in \mathbb{R}, \quad S_K := P|D|P^{-1} = |S| > 0, \\ \langle x|y\rangle_{S_K} := \langle x|S_K|y\rangle$$

**Factorization & operator transport:**

$$S_K = \gamma^\dagger \gamma \Rightarrow \langle x|y\rangle_{S_K} := \langle x|S_K|y\rangle = \langle \gamma x|\gamma y\rangle$$

For canonical  $\hat{\delta} = \hat{\delta}^\dagger$ , let  $\hat{O} := \gamma^{-1}\hat{\delta}\gamma$

$$\langle \cdot | \hat{O} | \cdot \rangle_S = \langle \cdot | S \hat{O} | \cdot \rangle = \langle \cdot | \gamma^\dagger \gamma \hat{O} | \cdot \rangle = \langle \cdot | \gamma^\dagger \hat{\delta} \gamma | \cdot \rangle = \langle \gamma \cdot | \hat{\delta} | \gamma \cdot \rangle$$

**Time evolution (normalized in  $S_K$ ):**

$$|I(t)\rangle = \mathcal{N}(t)e^{-iHt/\hbar}|I(0)\rangle, \quad \langle I(t)|I(t)\rangle_{S_K} = 1 \\ \langle \hat{\delta}(t) \rangle = \langle I(t) | \hat{O} | I(t) \rangle_S = \langle \gamma I(t) | \hat{\delta} | \gamma I(t) \rangle$$

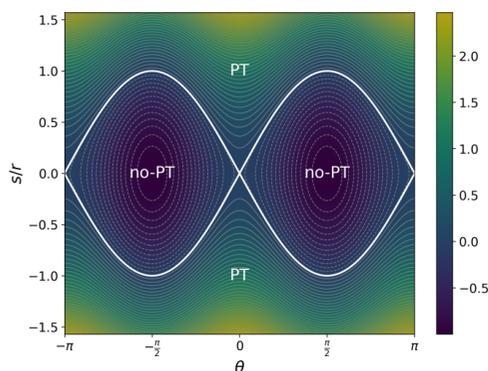
## Unified prescription across regimes (overview)

Regime	Spectrum	Metric / inner product
Exact (unbroken)	Real, diagonalizable	$S > 0$ (pseudo-Hermitian metric)
Broken	Complex-conjugate pairs	Krein construction $S_K$ from indefinite $S$
Exceptional points (EP)	Jordan blocks	Jordan-metric $S_J$ + positive structure

- ▶ **The metric is not optional:** it fixes physical means/variances/uncertainty bounds.

## MODEL

$$H = \begin{pmatrix} re^{i\theta} & s \\ s & re^{-i\theta} \end{pmatrix}, \quad d = (s/r)^2(1 - \eta^2), \quad \eta = \frac{r}{s} \sin \theta$$



Phase map from  $d(s/r, \theta)$ : unbroken ( $\eta^2 < 1$ ), broken ( $\eta^2 > 1$ ), EP ( $\eta^2 = 1$ ).

## Main inequality (metric form, all regimes)

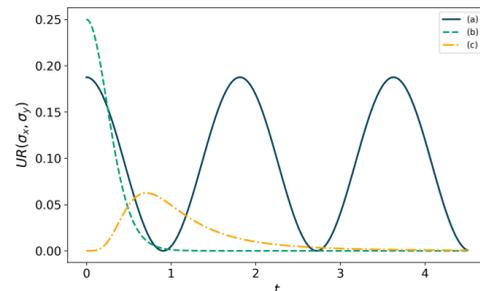
For two non-commuting observables  $A, B$ ,

$$UR(A, B) := \Delta_{S_K}^2 A \Delta_{S_K}^2 B - \frac{1}{4} |\langle [A, B] \rangle_{S_K}|^2 \geq 0$$

- ▶ **Same inequality, same look:** the regime-dependence is only in the choice of metric (unbroken:  $S > 0$ ; broken: Krein metric  $S_K$ ; EP: Jordan-based  $S_J$ ).

## Dynamics of uncertainty

- ▶ **Unbroken phase:**  $UR(t)$  oscillates as a function of time  $t$ .
- ▶ **Broken phase & EP:**  $UR(t)$  relaxes to a **minimum-uncertainty** steady state.

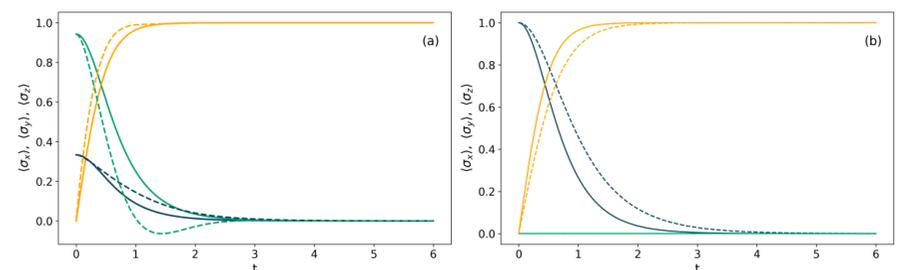


Time evolution of  $UR(\sigma_x, \sigma_y)$ : (a) exact PT phase ( $\eta = 1/2$ ,  $s = 1$ ), (b) broken PT phase ( $\eta = \sqrt{2}$ ,  $s = 1$ ), (c) EP ( $\eta = 1$ ,  $s = 1$ ). Initial state  $(\phi, p) = (\pi, 1)$ .

Steady-state predictions match the Lindblad master-equation description (differences only at early times: jumps / postselection).

$$\frac{d\rho}{dt} = -\frac{i}{\hbar}[h, \rho] + \sum_k \gamma_k \left( L_k \rho L_k^\dagger - \frac{1}{2} \{L_k^\dagger L_k, \rho\} \right).$$

- ▶ Hamiltonian:  $h = r \cos \theta \mathbb{I} + s \sigma_x$ .
- ▶ Collapse operators:  $L_\pm = (\sigma_x \pm i\sigma_y)/2$ ,  $\gamma_k = \sqrt{|r \sin \theta|}$ .
- ▶ Non-Hermitian evolution  $\sim$  effective/no-jump (postselected) trajectory.
- ▶ Lindblad includes *quantum jumps*  $\Rightarrow$  short-time deviations.



Behavior of the mean values of the components of spin,  $\langle \sigma_i \rangle_{S_K}$ , as a function of time (blue, green and yellow dashed lines correspond to  $\langle \sigma_x \rangle_{S_K}$ ,  $\langle \sigma_y \rangle_{S_K}$ ,  $\langle \sigma_z \rangle_{S_K}$  respectively). Solid lines show the effective (no-jump) evolution.

## CONCLUSION

- ▶ The metric determines physically meaningful expectation values, variances and uncertainty relations in exact, broken and EP regimes within a single prescription.
- ▶ In pseudo-hermitian dynamics, Krein-space tools show oscillations in the exact phase; relaxation to stationary minimum-uncertainty states in the broken phase and at EPs.
- ▶ Lindblad benchmarking supports the steady-state predictions. At early stages of time evolution, the differences support the role of postselection.

## OUTLOOK & REFERENCES

Establish a constructive equivalence between the broken-PT Krein-space formulation and the metric-operator canonical-inner-product approach, including an explicit dictionary for metrics, adjoints, observables, and states.

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