

Curvature-guided Graph-to-Hypergraph Structural Lifting Alleviates Over-Squashing in Graph Learning

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Summary

Many real-world systems exhibit complex, higher-order interactions that standard GNNs cannot capture thus motivating Topological Deep Learning and the concept of *lifting*. We propose a structural lifting based on Forman-Ricci curvature, which identifies network backbones, i.e. coarse, structure-preserving geometries, and maps them as hyperedges into a hypergraph \mathcal{H} , virtually shortening distances between relevant nodes and alleviating over-squashing. Using GCN and GAT, lifting improves performance in 75% of cases, while hypergraph models (EDGNN, AllSetTransformer) benefit in 80% of cases.

The challenge: over-squashing in graph learning

Recent research [1–3] shows that certain graph structures are inherently ill-suited for effective message passing. Specifically, MPNNs (e.g. GCN, GAT) [4] struggle in capturing long-range dependencies, where model outputs rely on interactions between distant nodes [5]. When messages from distant nodes must traverse few paths and compress into fixed-size representations, critical signals are lost — a phenomenon known as over-squashing [2, 3, 5] (see figure 1).

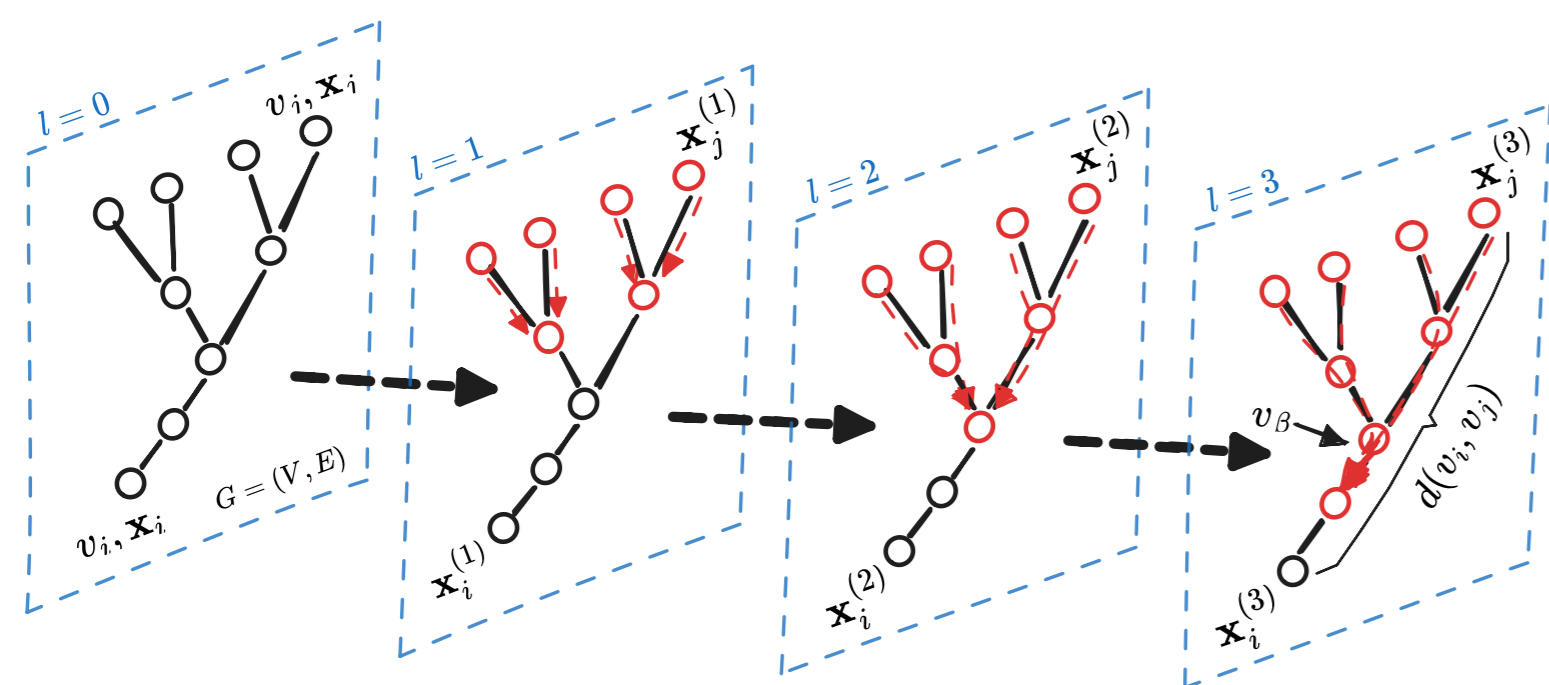


Figure 1: Layer-wise information propagation along edges of G . Due to G 's structure, node v_j forms information bottleneck. In addition, as $d(v_i, v_j) = 4$ but number of layers $l = 3$, information from v_j never reaches v_i .

To this end, over-squashing can be quantified as the lack of sensitivity of an MPNN at a given node to the input features of another remote node [1, 6]. Consider $G = (V, E)$ with node features $\mathbf{x}_i \in \mathbb{R}^m$ for each $v_i \in V$; a general MPNN updates features layer-wise by:

$$\mathbf{x}_i^{(l)} := \mathbf{x}_{v_i}, \quad \mathbf{x}_i^{(l)} = \phi^{(l)} \left(\mathbf{x}_i^{(l-1)}, \bigoplus_{j \in \mathcal{N}(v_i)} \psi^{(l)}(\mathbf{x}_j^{(l-1)}, \mathbf{x}_j^{(l-1)}, \mathbf{e}_{i,j}) \right) \quad (1)$$

Here, $\mathbf{x}_i^{(l)}$ and $\mathbf{x}_i^{(l-1)}$ denote the l -th and $(l-1)$ -th layers' node features representations of v_i , \bigoplus is a differentiable, permutation invariant function, e.g. sum or mean, ψ and ϕ are differentiable message aggregation and node update functions, $\mathcal{N}(v_i)$ is the node neighborhood of v_i and $\mathbf{e}_{i,j}$ denote some (optional) edge features from node v_j to v_i . The receptive field \mathcal{R}^l at the l -th layer is defined as $\mathcal{R}^l = \{v_i, v_j \in V : d(v_i, v_j) \leq l\}$, where

$d(v_i, v_j)$ represents the shortest path distance in G between v_i and v_j . The Jacobian $\partial \mathbf{x}_i^{(l)} / \partial \mathbf{x}_j$ quantifies the sensitivity of representation $\mathbf{x}_i^{(l)}$ at v_i to a specific input feature \mathbf{x}_j at v_j within \mathcal{R}^l . Small absolute values of this Jacobian are indicative of poor information propagation, or over-squashing, i.e. the incapacity of $\mathbf{x}_i^{(l)}$ to be influenced by \mathbf{x}_j at a distance of l . Notably, this Jacobian is upper-bounded by powers of G 's adjacency matrix, so G 's structure directly governs over-squashing [1, 6].

The metric: curvature on graphs

Analyzing the geometric properties of G has been proposed to better understand over-squashing [1]. One such property is curvature, which, in its continuous form, measures how space bends locally. In two dimensions, Gaussian curvature K defines whether a surface is flat (Euclidean), positively curved (e.g. a sphere), or negatively curved (e.g. a saddle) (figure 2).

Such curvature notions extend to graphs [1], linking local geometry to global structure. As an analogy of geodesic dispersion, i.e. whether two parallel geodesics starting from nearby points converge ($K > 0$), remain parallel ($K = 0$), or diverge ($K < 0$), on graphs, consider an edge with two edges starting at its respective endpoints. In a discrete spherical geometry (e.g. a clique graph), the edges would meet at another node to form a triangle. In a discrete Euclidean geometry (e.g. a grid), the edges would stay parallel and form a rectangle or grid, whereas in a discrete hyperbolic geometry (e.g. a tree), the mutual distance of the edge endpoints would increase.

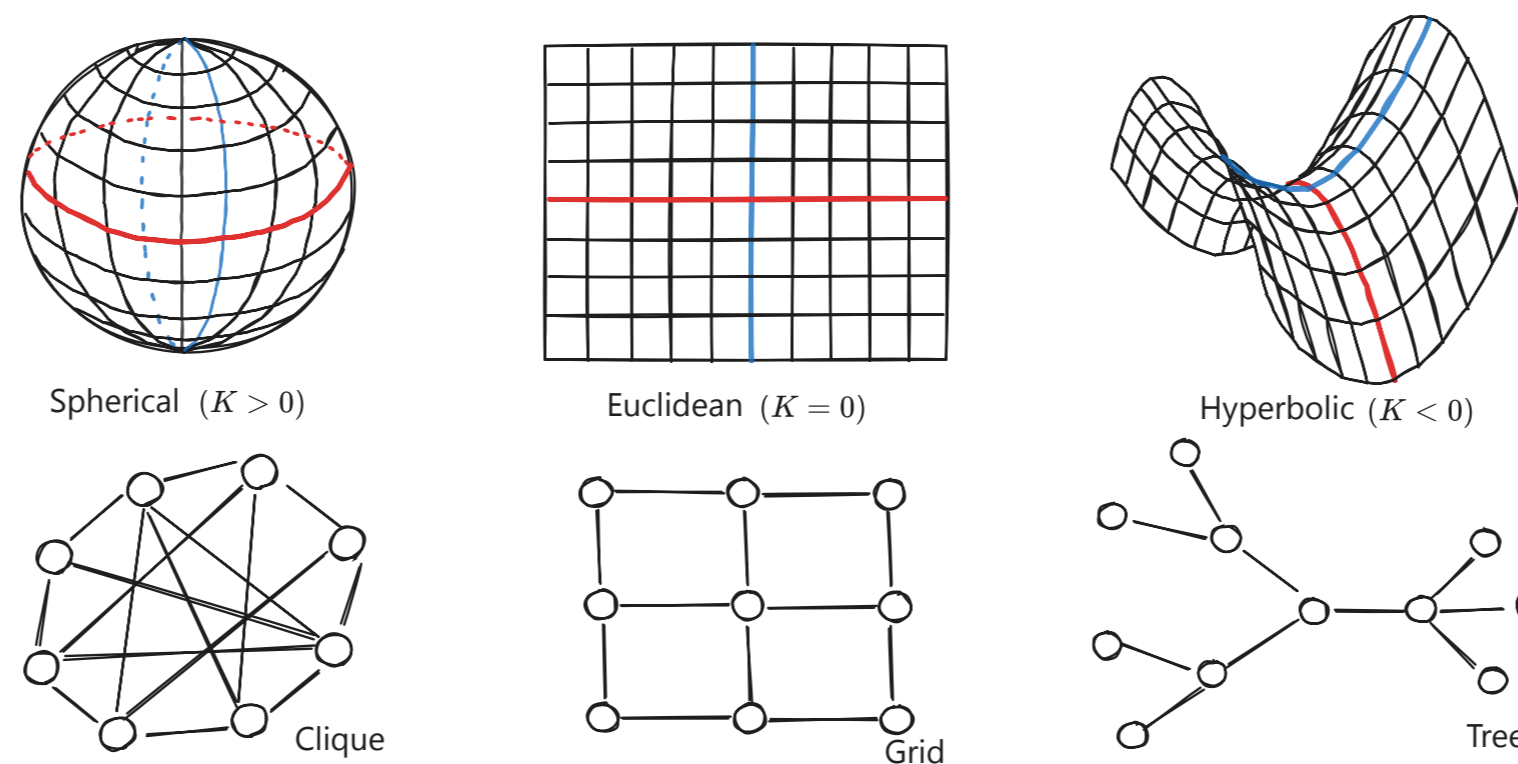


Figure 2: In differential geometry, curvature on manifolds, such as Gaussian curvature K , relates to information propagation. Replacing geodesics for edges, one can find discrete graph analogous for different types of curvature.

To measure curvature on graphs, a variety of metrics have been proposed, predominantly Ollivier-Ricci [7] as well as several variations of Forman-Ricci curvature [1, 2, 8, 9]. In particular, Ollivier-Ricci curvature [10] translates previously described notions of positive and negative curvature directly to the discrete domain [1]. Forman-Ricci correlates with Ollivier-Ricci [9] but scales more efficiently to large networks. However, the purely edge-based Forman-Ricci [8, 9, 11] biases towards negative values, hence lacks the intuition of Ollivier-Ricci curvature. Concretely, highly negative values tend to describe edges within clusters whereas values near zero indicate bridges between clusters.

The remedy: graph-to-hypergraph structural lifting

While curvature-guided local graph rewiring has been proposed to address bottlenecks [1, 2], one fundamental restriction of graphs is their limitation to pairwise relations. Topological Deep Learning instead encodes higher-order relationships beyond pairwise constraints [12].

We propose a remedy that uses Forman-Ricci curvature to identify network backbones, i.e. structure-preserving, coarse geometries connecting major communities. We then perform a structural lifting [13, 14] $\gamma : G \rightarrow \mathcal{H}$, treating backbones as hyperedges to virtually shorten distances between relevant nodes.

$$\text{Ric}_F(e) = \omega(e) \left(\frac{\omega(v_i) + \omega(v_j)}{\omega(e)} - \sum_{e_{v_i} \sim e} \left[\frac{\omega(v_i)}{\sqrt{\omega(e)\omega(e_{v_i})}} + \frac{\omega(v_j)}{\sqrt{\omega(e)\omega(e_{v_j})}} \right] \right) \quad (2)$$

where e_{v_i}, e_{v_j} are the edges connected to nodes v_i and v_j . For an unweighted network graph, i.e. all edge weights $w = 1$, equation 2 reduces to $\text{Ric}_F(e) = 4 - \deg(v_i) - \deg(v_j)$. Thus $\text{Ric}_F(e) < 0$ if both v_i and v_j have high degrees. In particular,

edges with high negative curvature, i.e. $\text{Ric}_F(e) \ll 0$, should play a special role for the spreading out and hence for, e.g. information dispersal in a network, whereas edges with $\text{Ric}_F(e) \approx 0$ rather constitute long-range interactions, bottlenecks, interfaces or boundaries (see figure 3).

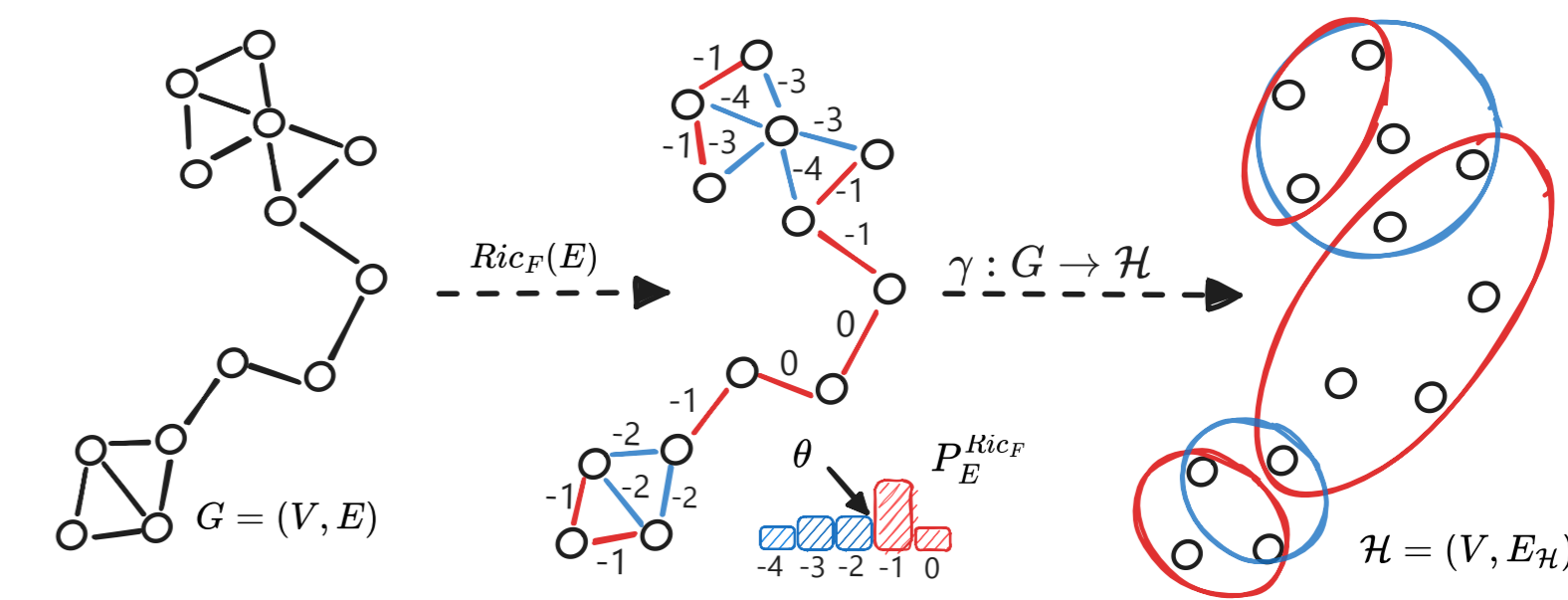


Figure 3: Forman-Ricci curvature based structural lifting $\gamma : G \rightarrow \mathcal{H}$ given $\theta = -1$ for an unweighted graph G . Red and blue hyper-edges correspond to $\text{Ric}_F(e) \geq \theta$ and $\text{Ric}_F(e) < \theta$, respectively.

Subsequently, we use $\text{Ric}_F(e)$ values per each e to define a structural lifting $\gamma : G \rightarrow \mathcal{H}$, mapping $G = (V, E)$ to $\mathcal{H} = (V, \mathcal{E}_{\mathcal{H}})$, where \mathcal{H} generalizes G by allowing hyperedges to connect any number of nodes [13, 14].

Hyperparameter θ separates two hyperedge types: cluster edges ($\text{Ric}_F(e) < \theta$) and long-range/bottleneck edges ($\text{Ric}_F(e) \geq \theta$); θ can be set as a quantile of the empirical curvature distribution (figure 3).

We then define a hyperedge $e_{S,\theta} \in \mathcal{E}_{\mathcal{H}}$ in \mathcal{H} where S denotes a subset of V in G . For each node $v_i \in S$, v_i is an endpoint to an edge e in G with $\text{Ric}_F(e) < \theta$ (or $\text{Ric}_F(e) \geq \theta$ respectively), and $\exists v_j \in S$, with $v_j \in \mathcal{N}_1(v_i)$, i.e. v_i, v_j are connected via e in G . Figure 3 illustrates $\gamma : G \rightarrow \mathcal{H}$ given $\theta = -1$.

Experiments

We evaluate on graph classification benchmarks and a molecular property prediction dataset (table 1). Results are averaged across four metrics (precision, recall, AUROC, accuracy). GCN and GAT consistently improve on lifted vs. non-lifted data in 75% (6/8) of cases. Hypergraph models (EDGNN, AllSetTransformer, UniGNN2) also benefit, improving in 80% (10/12) of cases.

Dataset / Method	GCN	GAT	AST	EDGNN	UniGNN2
NC11	0.71 ± 0.03	0.73 ± 0.04	0.65 ± 0.07	0.70 ± 0.06	0.63 ± 0.08
NC11 _{Ric_F}	0.72 ± 0.03	0.73 ± 0.04	0.68 ± 0.05	0.71 ± 0.04	0.72 ± 0.03
NC1109	0.70 ± 0.03	0.71 ± 0.04	0.70 ± 0.06	0.68 ± 0.09	0.67 ± 0.09
NC1109 _{Ric_F}	0.71 ± 0.03	0.72 ± 0.04	0.69 ± 0.07	0.69 ± 0.07	0.70 ± 0.05
OGB Molhiv	0.78 ± 0.14	0.77 ± 0.17	0.78 ± 0.20	0.76 ± 0.17	0.78 ± 0.15
OGB Molhiv _{Ric_F}	0.79 ± 0.13	0.77 ± 0.17	0.79 ± 0.19	0.78 ± 0.16	0.78 ± 0.16
PROTEINS	0.69 ± 0.04	0.69 ± 0.04	0.66 ± 0.08	0.67 ± 0.07	0.69 ± 0.06
PROTEINS _{Ric_F}	0.70 ± 0.02	0.70 ± 0.04	0.70 ± 0.07	0.73 ± 0.04	0.70 ± 0.09

Table 1: Performance comparison on original and lifted datasets across several graph and hypergraph neural network architectures.

Implementation

An earlier version of our curvature-based structural lifting has been made available as part of TopoBench [15] a modular Python library designed to standardize benchmarking and accelerate research in Topological Deep Learning.

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