



A multiscale approach to the smart deployment of micro-sensors over flexible plates

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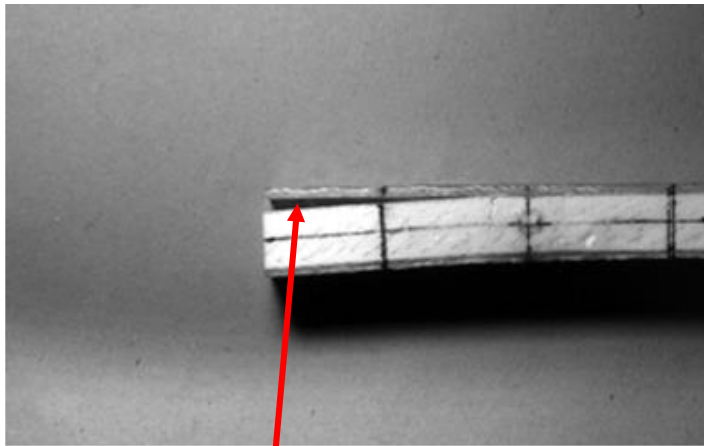
15-30 November 2016, online

Chairs:

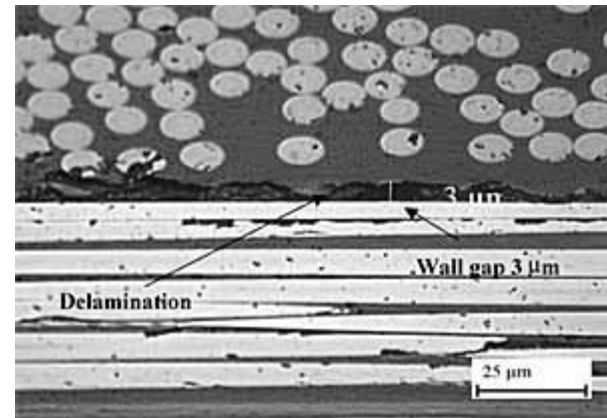
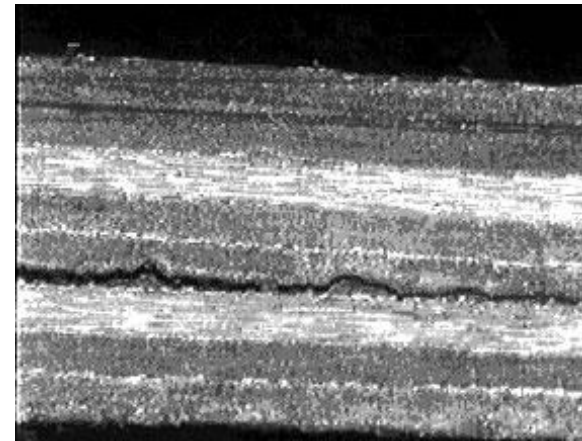
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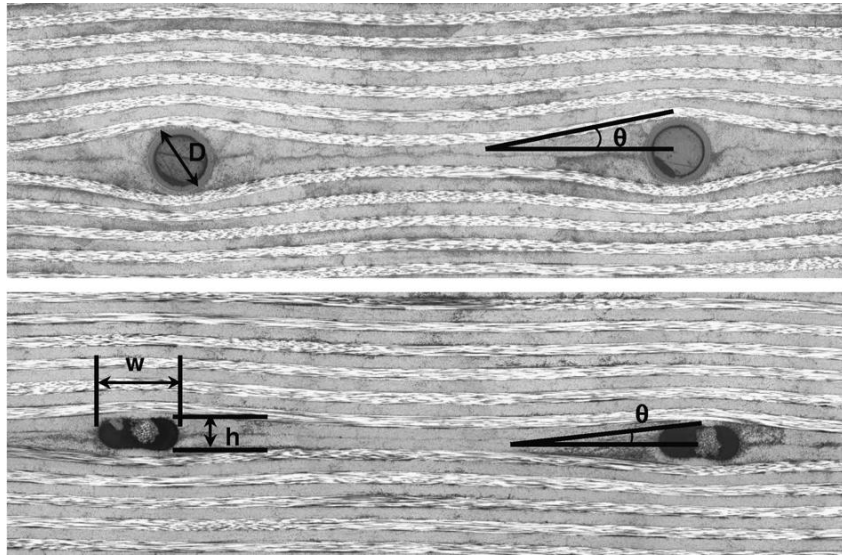


Syntactic foam/glass fibre composite sandwich



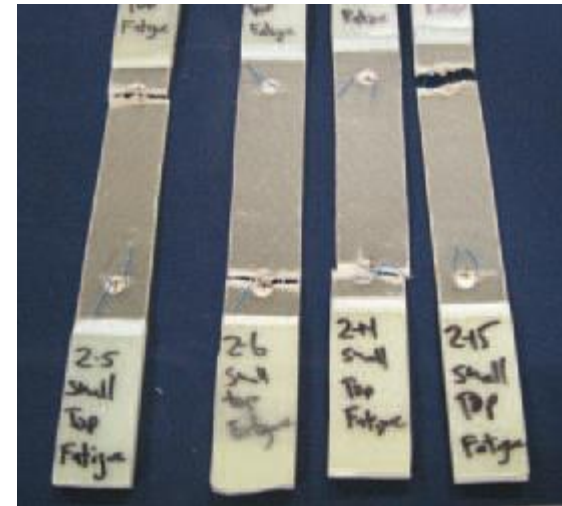
delamination



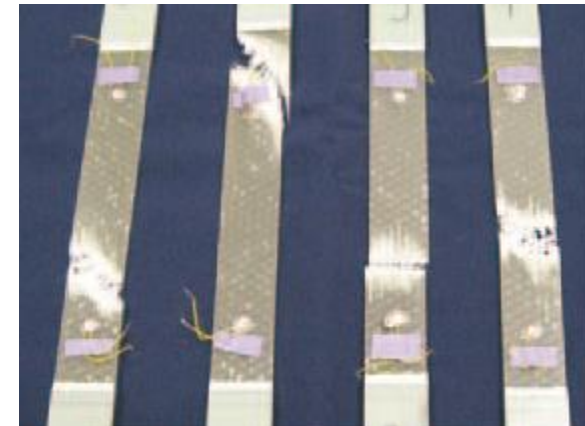


effects of embedded fiber sensors
after Kousourakis et al., Composites (2008)

SHM modifies the stress-carrying capacity of the structural component

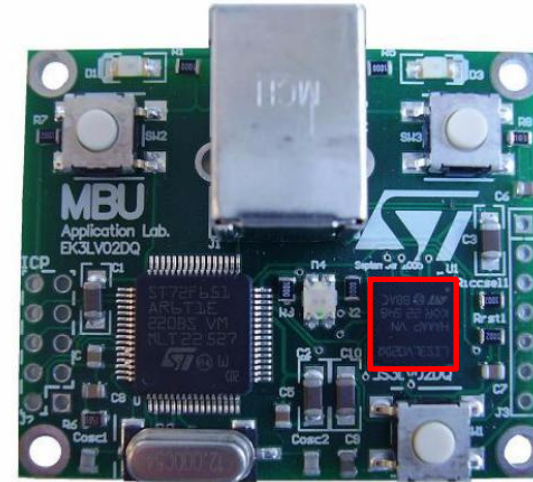
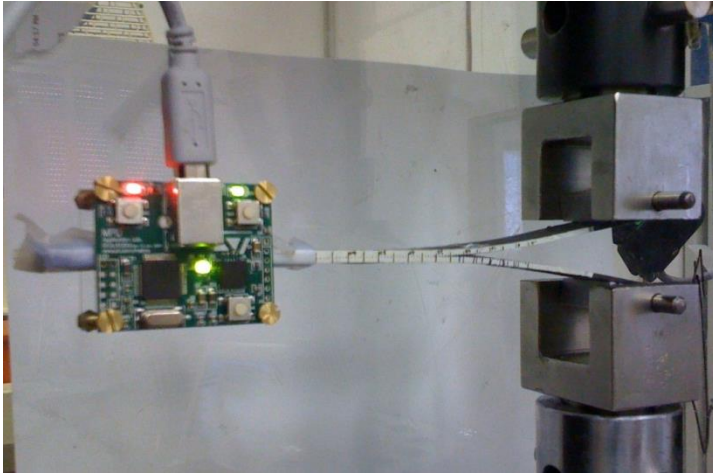
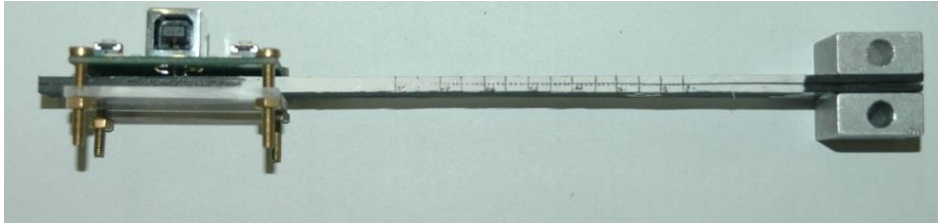


inner (embedded) piezo



surface mounted piezo

after Tang et al., JIM (2011)



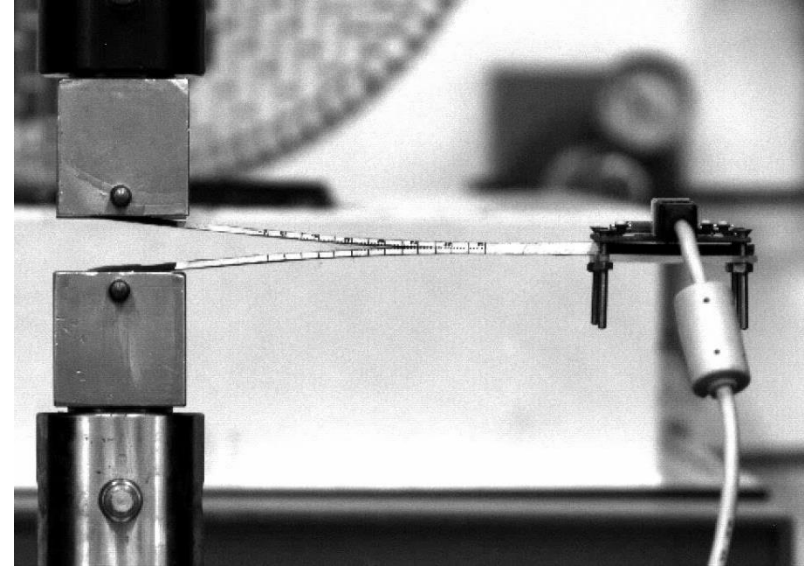
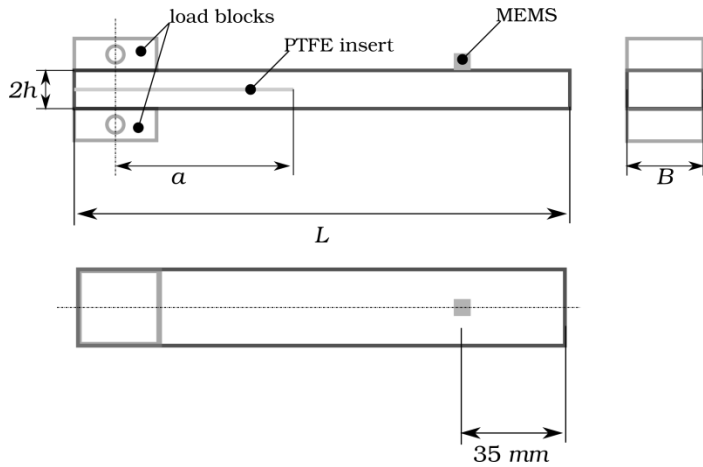
MEMS evaluation board

Features of 3-axis, digital output **MEMS** (micro electro-mechanical sensor) accelerometer **LIS3LV02DQ** (STM):

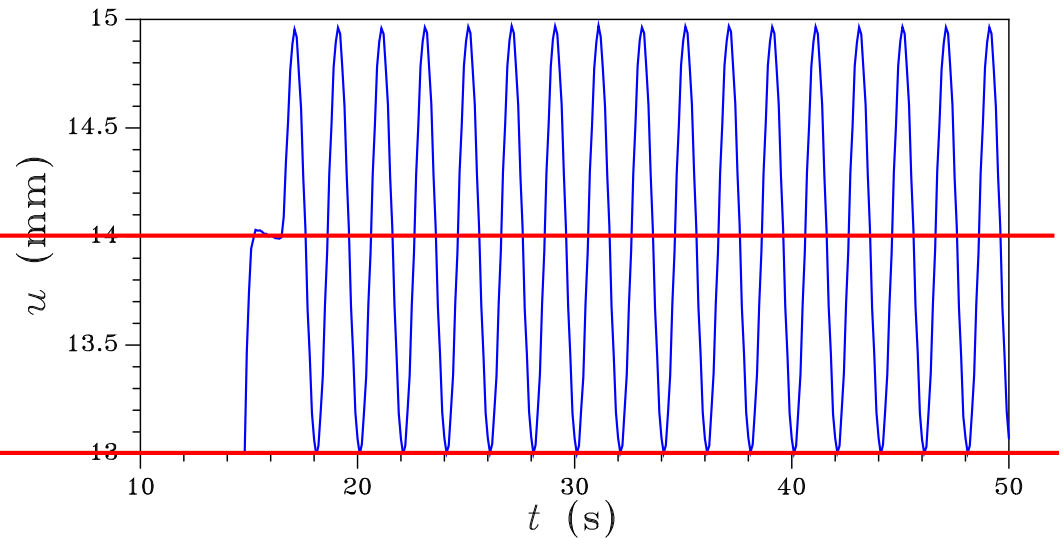
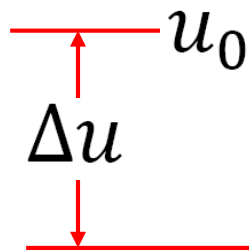
- full scale $\pm 2g$
- bandwidth 640 Hz
- sensitivity 1,000 LSb(Least_Significant_bit)/g
- resolution 1 mg
- weight 0.2 grams

Validation of the SHM scheme

Optimal sensor placement

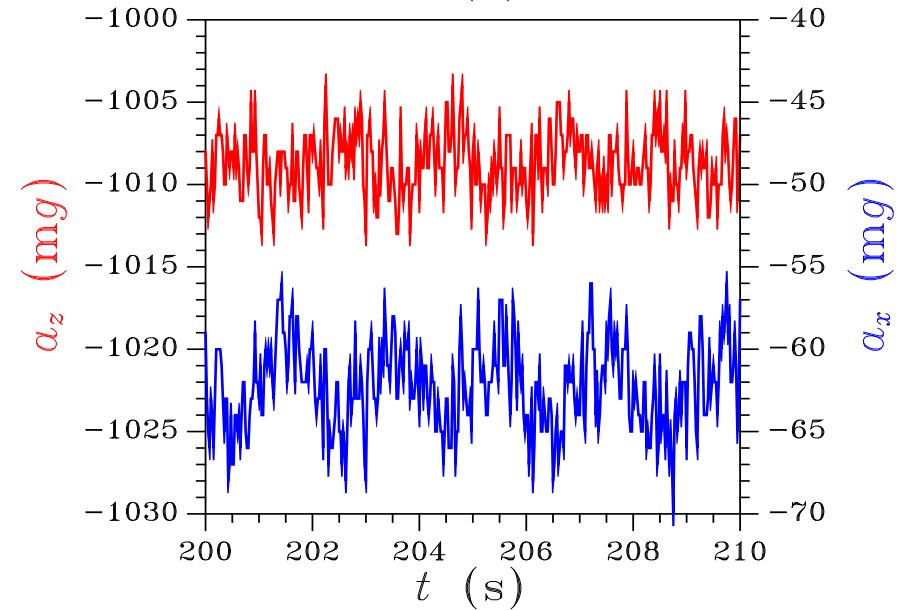
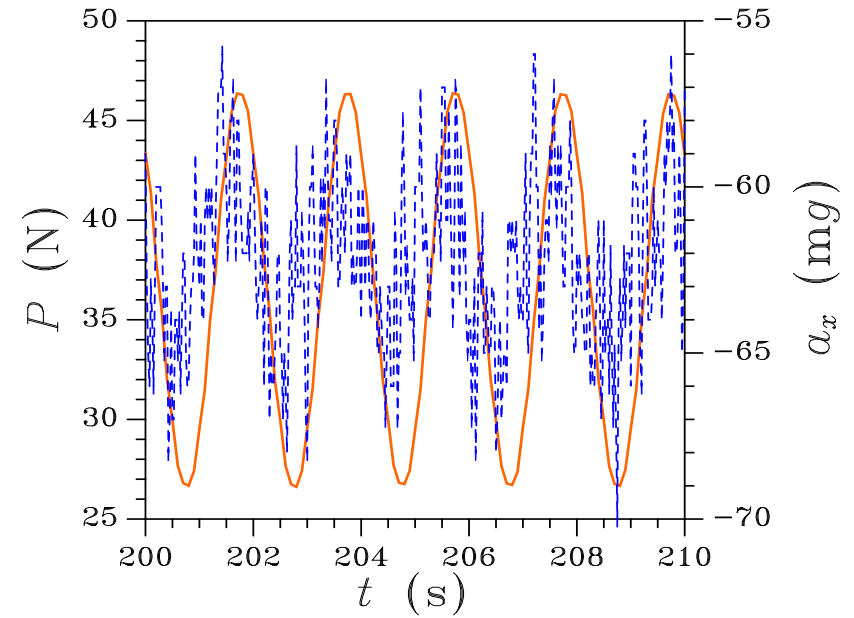


Sinusoidally varying imposed displacement u (at increasing u_0)



Load P varies smoothly

MEMS output shows high-order frequency fluctuation



Validation test: theoretical model (Bernoulli-Euler beam bending)

Specimen compliance: $C = \frac{u}{P} = 8 \frac{a^3}{E_l B h^3}$ a : delamination length

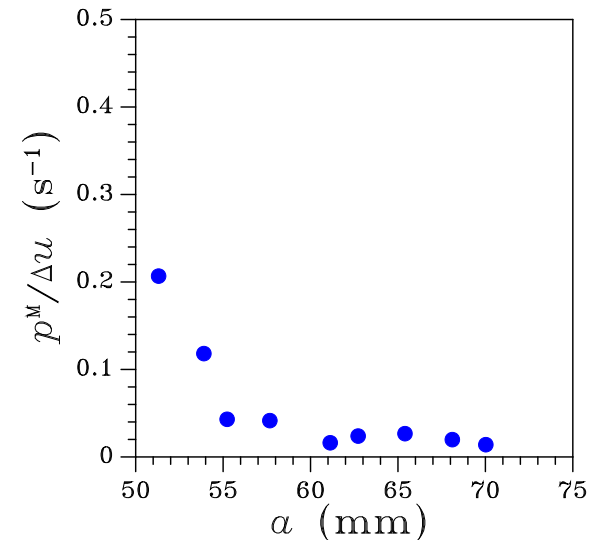
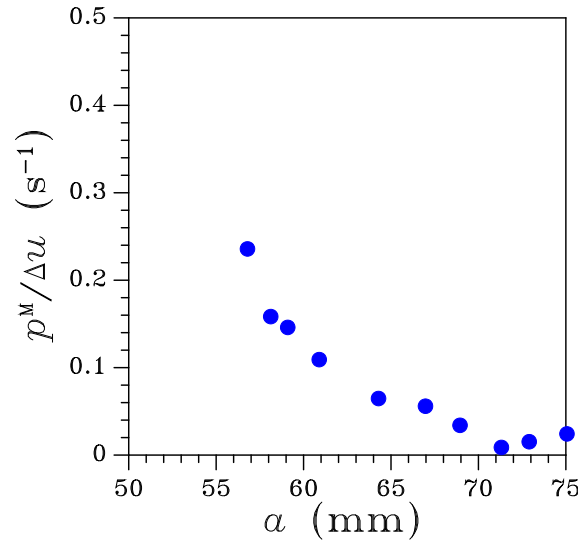
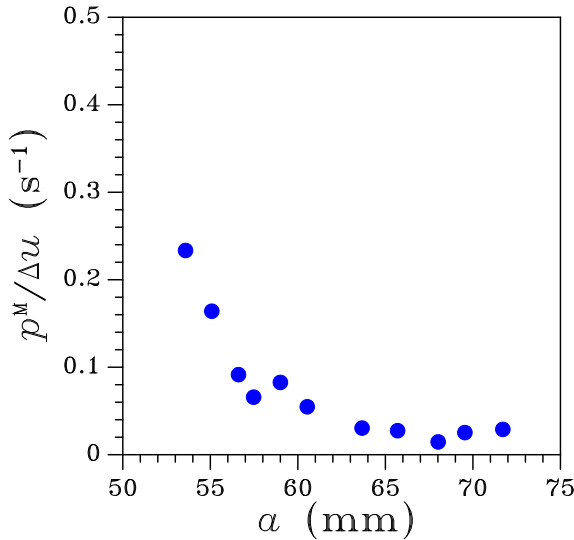
Acceleration-load relation: $\ddot{u} = \varphi P$ φ : assumed constant
(geometry dependent)

In case of sinusoidal load: $\ddot{u} = \varphi \frac{u}{C} = \frac{\varphi}{C} [u_0 + \Delta u \sin(2\pi f_u t)]$

Moving to the frequency domain, through FFT: $|\hat{\ddot{u}}| = \frac{\varphi}{C} \left[u_0 \delta(f) + \frac{\Delta u}{2} \delta(f \pm f_u) \right]$

At the driving frequency: $\frac{|\hat{\ddot{u}}|}{\Delta u} = \frac{\varphi}{2C} \delta(f - f_u)$

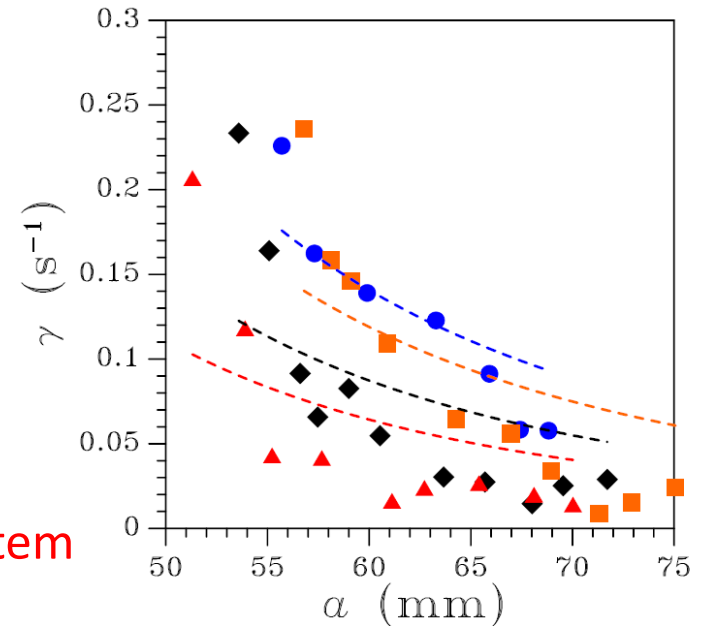
Validation test: theoretical model (Bernoulli-Euler beam bending)



$$\gamma = \frac{|\hat{u}|}{\Delta u} = \frac{\varphi}{2C} \delta(f - f_u)$$

$$C = \frac{u}{P} = 8 \frac{a^3}{E_l B h^3}$$

$$= \frac{\mu}{a^3} \delta(f - f_u)$$

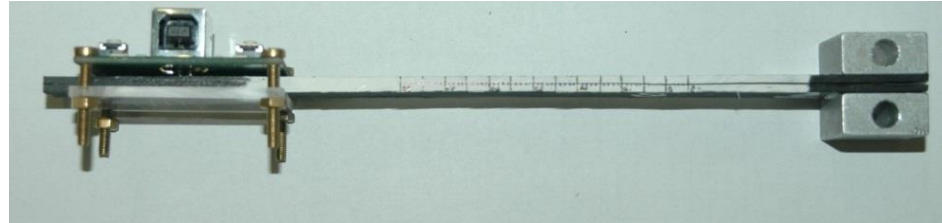


We obtained a delamination length-sensing SHM system
(Mariani et al., MEJ 2013, IEEE Sensors 2014)

Validation of the SHM scheme

Optimal sensor placement

DCB test

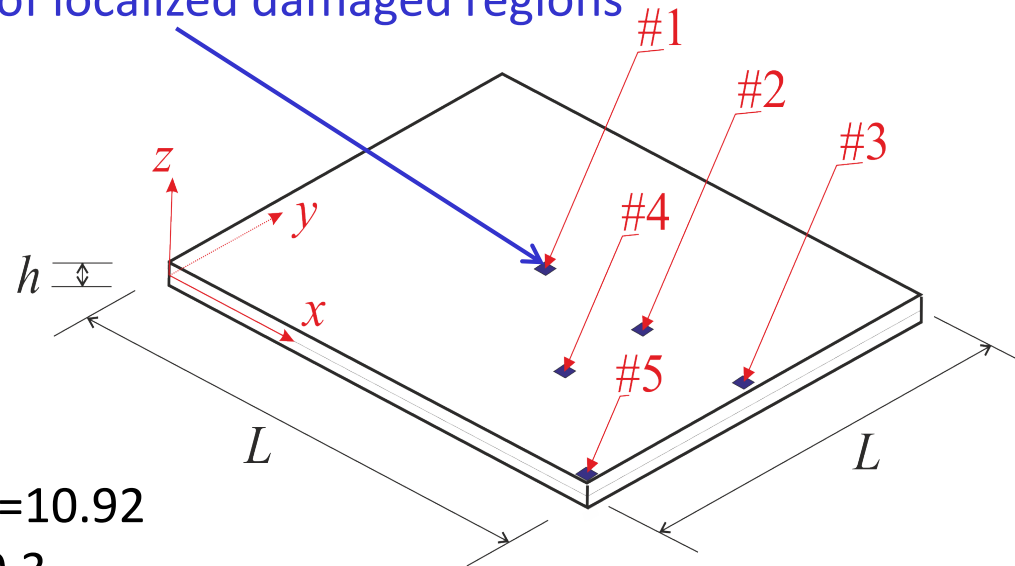


examples of localized damaged regions

Thin square,
simply supported plate:

$$\frac{L}{h} = 1000$$

Isotropic material:
(dimensionless) Young modulus $E=10.92$
Poisson ratio $\nu=0.3$



In case of a **single damaged region** (of known position), to maximize the sensitivity to the effects of damage:

undamaged plate solution

damaged plate solution

$$\begin{cases} \max_x \sum_{i=1}^n x_i^p (u_i - \hat{u}_i)^2 \\ \text{s. t.} \\ \sum_{i=1}^n x_i \leq \bar{N} \\ 0 \leq x_i \leq 1 \end{cases} \quad i = 1, \dots, n$$

penalization term to approach pure 0-1 distributions ($p > 1$)

“sensor density” at the i -th position

number of possible sensor locations (FE)

max allowed number of sensors

(Mariani-Bruggi et al., EO, JIM 2013)

In case of a **multiple damaged regions** (of known positions), to maximize the sensitivity to the magnitude of the effects of damage [FORM-1]:

number of damaged areas

$$\left\{ \begin{array}{l} \max_x \sum_{k=1}^s \left[\sum_{i=1}^n x_i^p (u_{ki} - \hat{u}_i)^2 \right] \\ \text{s. t.} \\ \sum_{i=1}^n x_i \leq \bar{N} \\ 0 \leq x_i \leq 1 \quad i = 1, \dots, n \end{array} \right.$$

or, to maximize the sensitivity to damage [FORM-2]:

$$\left\{ \begin{array}{l} \max_x \sum_{k=1}^s \left[\frac{\sum_{i=1}^n x_i^p (u_{ki} - \hat{u}_i)^2}{\max_i x_i^p (u_{ki} - \hat{u}_i)^2} \right] \\ \text{s. t.} \\ \sum_{i=1}^n x_i \leq \bar{N} \\ 0 \leq x_i \leq 1 \quad i = 1, \dots, n \end{array} \right.$$

To be adopted at **each length-scale** (two concatenated analyses in the cases to follow)

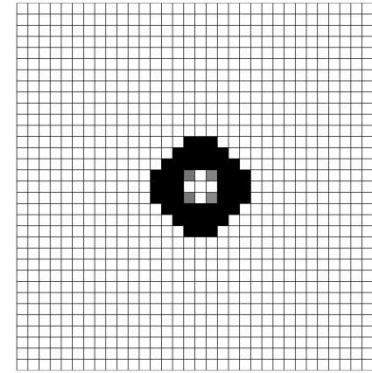
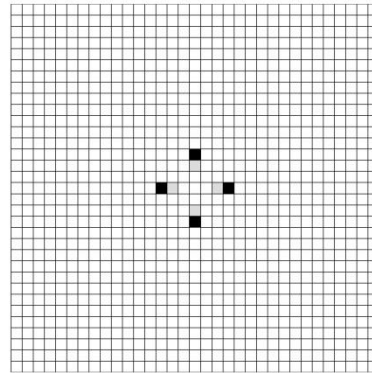
Square plate: optimal sensor placement – damage anywhere at the macroscale simply supported plate

$$\theta = \sqrt{\theta_x^2 + \theta_y^2}$$

$$\bar{N} = 5$$

$$\bar{N} = 50$$

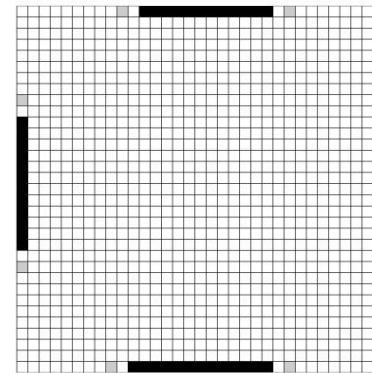
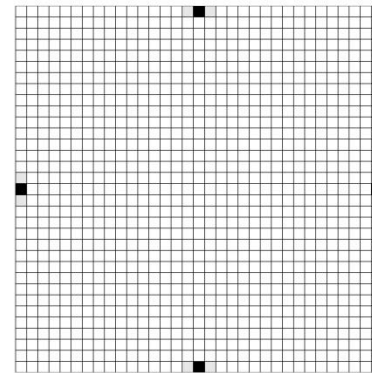
[FORM-1]



$$\bar{N} = 5$$

$$\bar{N} = 50$$

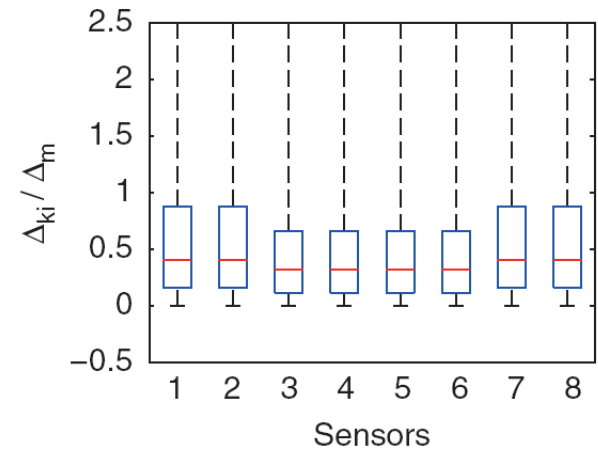
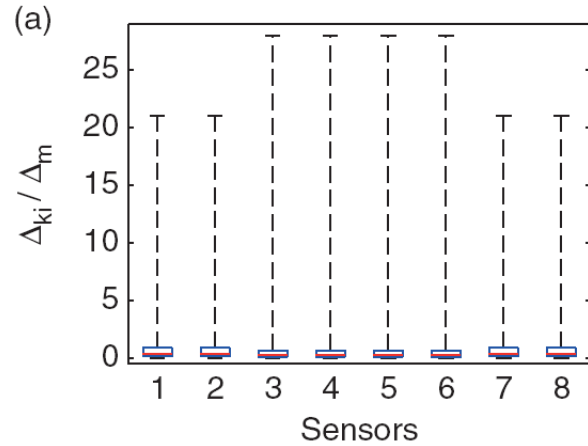
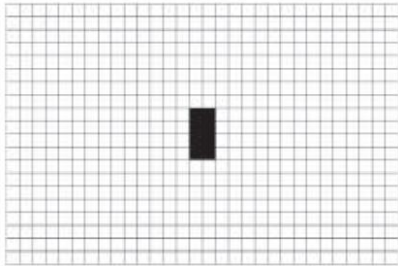
[FORM-2]



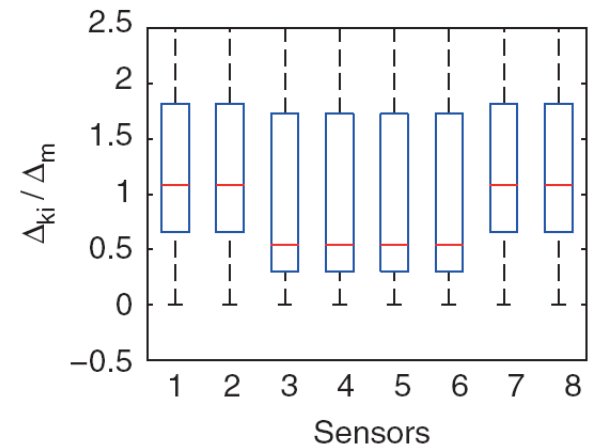
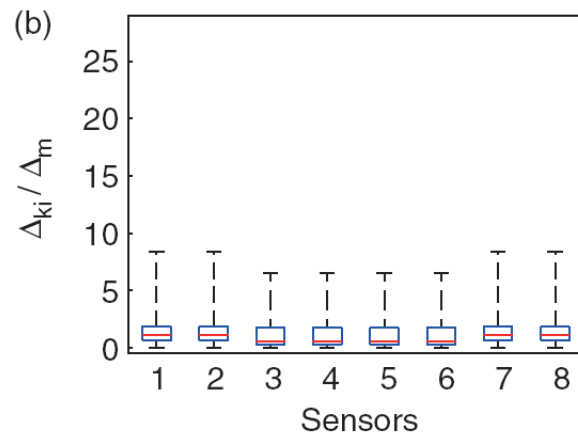
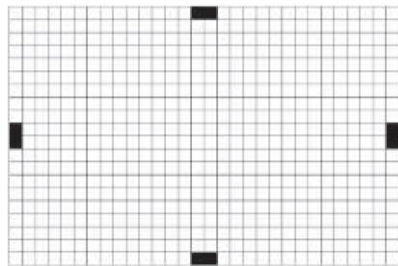
Rectangular plate: optimal sensor placement – damage anywhere at the macroscale simply supported plate

$$\theta = \sqrt{\theta_x^2 + \theta_y^2}$$

[FORM-1]



[FORM-2]



Square plate: optimal sensor placement – damage anywhere at the macroscale simply supported plate

$$\theta = \sqrt{\theta_x^2 + \theta_y^2}$$

$$\bar{N} = 16$$

damaged area

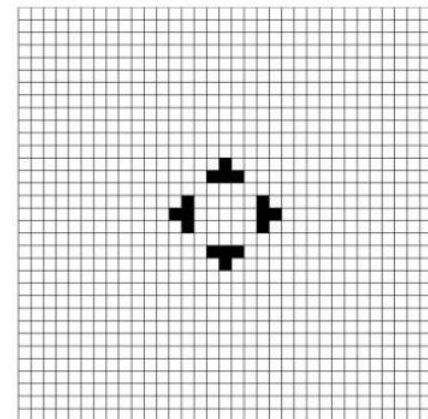
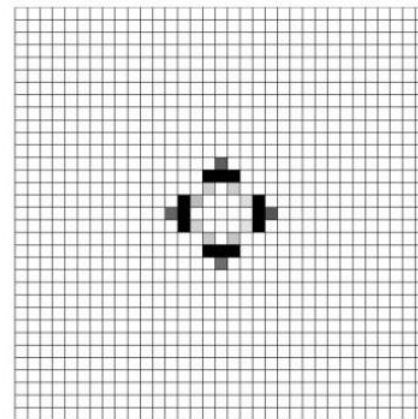
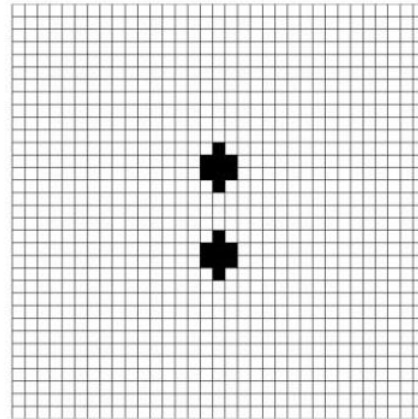
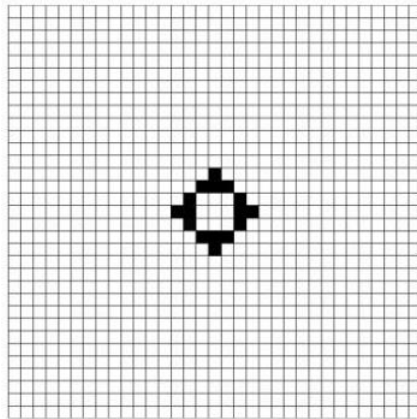
1 × 1

1 × 2

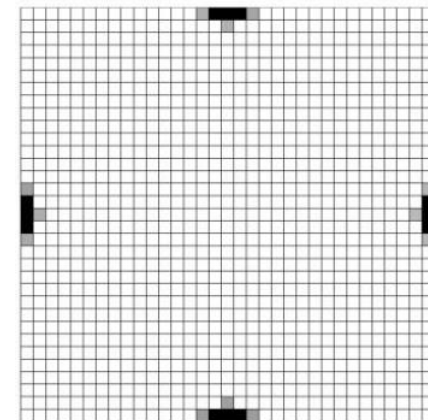
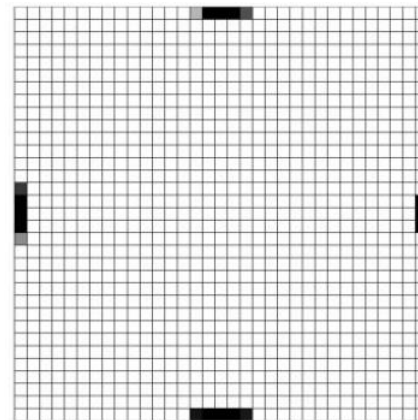
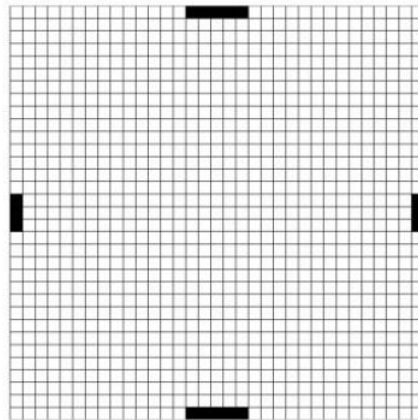
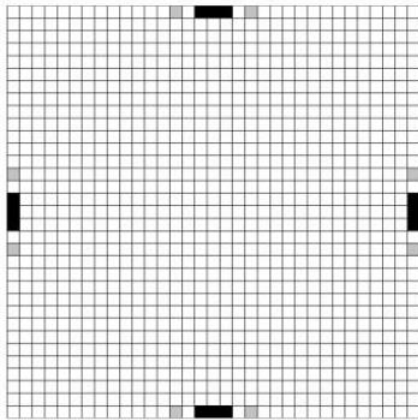
2 × 2

4 × 4

[FORM-1]



[FORM-2]



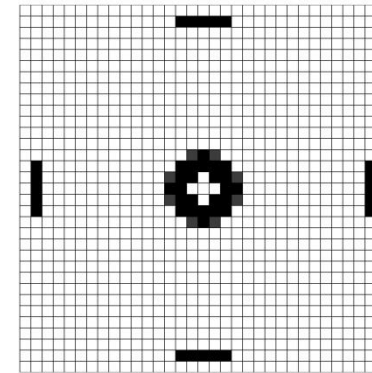
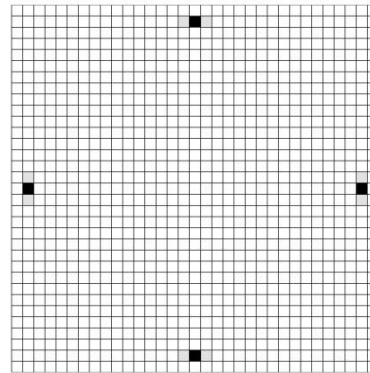
Square plate: optimal sensor placement – damage anywhere at the macroscale clamped plate

$$\theta = \sqrt{\theta_x^2 + \theta_y^2}$$

$$\bar{N} = 5$$

$$\bar{N} = 50$$

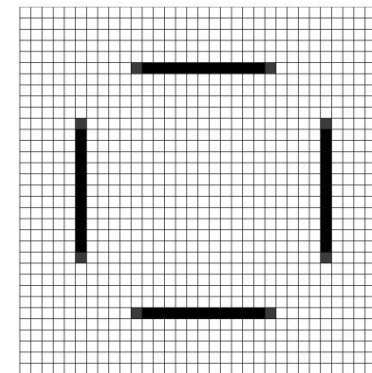
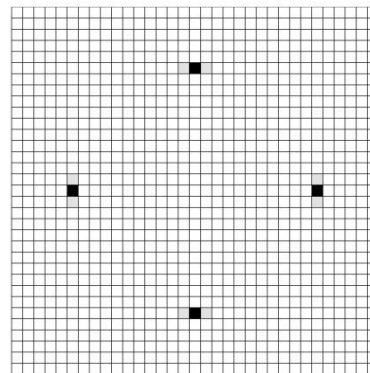
[FORM-1]



$$\bar{N} = 5$$

$$\bar{N} = 50$$

[FORM-2]



Square plate: optimal sensor placement –

damage anywhere

clamped plate, distributed load

[FORM-2], $\bar{N} = 8$

$$\theta = \sqrt{\theta_x^2 + \theta_y^2}$$

Multi-scale analysis:

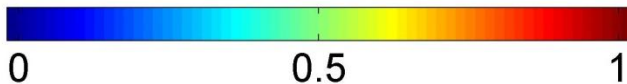
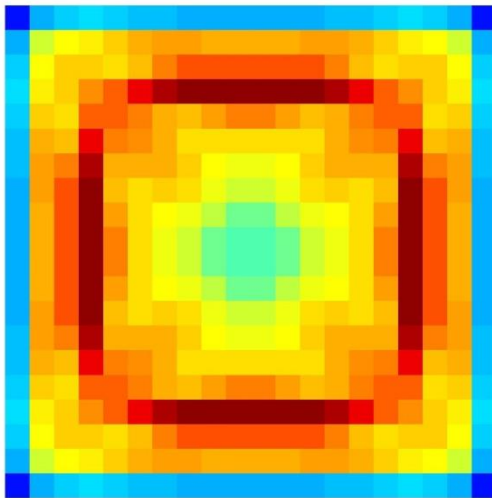
$L=1$ m (side length, or structural size)

$s=5$ cm (element, or damaged area size)

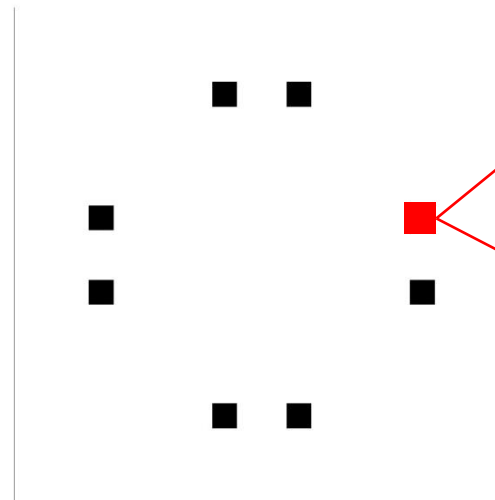
$l=2.5$ mm (sensor size)

$\bar{N} = 1$

objective function



sensor macro-placement



sensor micro-placement

$\bar{N} = 8$



Square plate: optimal sensor placement –

damage anywhere

clamped plate, concentrated load

$$\theta = \sqrt{\theta_x^2 + \theta_y^2}$$

[FORM-2], $\bar{N} = 8$

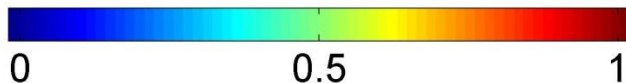
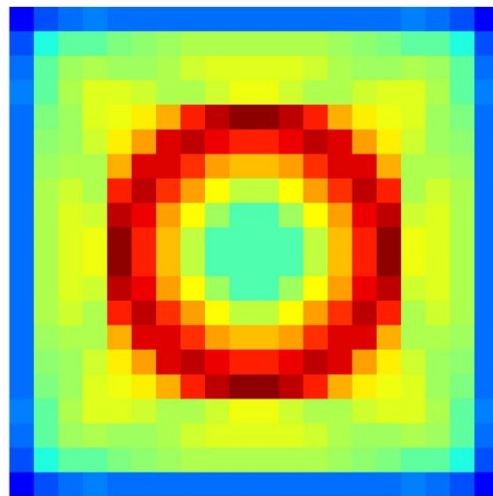
Multi-scale analysis:

$L=1$ m (side length, or structural size)

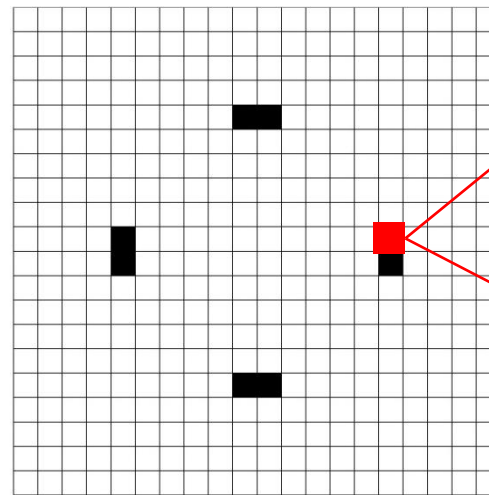
$s=5$ cm (element, or damaged area size)

$l=2.5$ mm (sensor size)

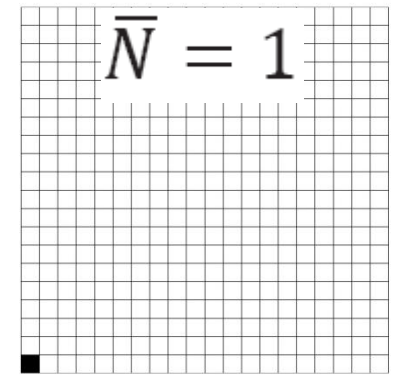
objective function



sensor macro-placement

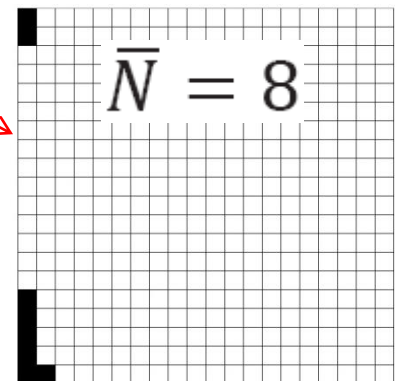


$\bar{N} = 1$



sensor micro-placement

$\bar{N} = 8$



- We proposed a MEMS-based SHM system, sensitive to damage (delamination) extent in composite
- We proposed a multi-scale topology optimization-like procedure to deploy MEMS, so as to maximize sensitivity to damage



Ongoing activities and future work

- robustness of the SHM system
- networking of (possibly self-powered) MEMS sensors
- real-time damage detection and identification for flexible (composite) plates
- Application: engineered bike and ski helmets, to understand links between impacts and brain injuries

Acknowledgments

- Italian MIUR-PRIN project *Mechanics of microstructured materials: multi-scale identification, optimization and active control*
- Italian Consorzio Interuniversitario Nazionale per la Scienza e la Tecnologia dei Materiali (INSTM)
- Regione Lombardia and CILEA Consortium, grant *M²-MEMS*
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