

Damage identification using sub-microstrain FBG data from a pre-stressed concrete beam during progressive damage testing

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Abstract: Vibration-based damage identification can constitute a successful approach for Structural Health Monitoring (SHM) of civil structures. It is a non-destructive condition assessment method, dependent on the identification of changes in the modal characteristics of a structure that are related to damage. However, the damage identification from the modal characteristics of existing structures currently suffers from a low sensitivity of eigenfrequencies and mode shapes to certain types of damage. Furthermore, the sensitivity of eigenfrequencies to environmental influences may be sufficiently high to completely mask the effect even of severe damage. Modal strains and curvatures are more sensitive to local damage, but the direct monitoring of these quantities is challenging when the strain level is very low. In the present work, the identification of the modal strains of a pre-stressed concrete beam, subjected to a progressive damage test, is performed. Dynamic measurements are conducted on the beam at the beginning of each cycle and its response is recorded with multiplexed Fiber-optic Bragg Grating (FBG) strain sensors. Bending, lateral and torsional modes are accurately identified from dynamic strains of the sub-microstrain level. The evolution of the modal characteristics of the beam after each loading cycle is investigated. Changes of the eigenfrequency values, the amplitude and the curvature of the strain mode shapes are observed. The changes in the strain mode shapes appear at the locations where the damage is induced, and are already identified from an early damaged state.

Keywords: Structural health monitoring; damage identification; strain mode shapes; experimental modal analysis; fiber-optic sensors

1. Introduction

Vibration-Based Structural Health Monitoring (VB-SHM), can be a successful approach for damage identification and structural condition assessment of civil structures, e.g. bridges, dams and tunnels. A drawback of the method is that it suffers currently from low sensitivity of the eigenfrequencies to certain types of damage, especially to local damage of moderate severity [1]. Moreover, the influence of the environmental factors (e.g. temperature) on eigenfrequencies can be high enough to completely mask the presence of damage [2]. In contrast, modal characteristics obtained from dynamic strain measurements, such as modal strains and modal curvatures, are much more sensitive to local damage [3]. The introduction of fiber-optic sensing systems, that can accurately measure dynamic strains while also offering ease of installation, resistance in harsh environment and long-term stability, contributed to an increased interest in adopting these systems for VB-SHM applications [4].

The FBG [5] strain sensors have been successfully used for monitoring civil structures but mainly for measuring of static strains while the amount of sensors used was limited. The current challenge

33 for the VBSHM of civil structures is to find monitoring systems that are easily implemented over
34 large areas, sensitive to local damage, able to measure very small strain values and cost-effective. The
35 FBG strain sensors can provide a good trade-off solution to these requirements. In this context, the
36 aim of this study is to directly measure in a dense grid the very small dynamic strains that occur
37 in civil structures, such as bridges, during operational or ambient excitation and to identify the
38 system characteristics from these data. By tracking the shifts in the values of the characteristics, the
39 identification of potential damage is possible.

40 The method is presented through application in a progressive damage test (PDT) on a complex,
41 prestressed fiber-reinforced concrete "roof" beam [6]. The beam is monitored with three chains of
42 multiplexed FBG sensors. It is excited with an impulse hammer at low force amplitudes, resulting in
43 dynamic strains of sub-microstrain amplitude. Dynamic tests are performed at the end of each loading
44 cycle and the data are used in a strain-based modal analysis. The obtained dynamic characteristics of
45 the various damage stages are then compared and shifts in their values are related to the presence and
46 location of structural damage.

47 2. Experimental setup

48 An I-shaped, pre-stressed concrete "roof" beam with two openings in its web serves as test
49 structure (Figure 1). The beam's length is 6.0 m and its height varies linearly between its ends and its
50 middle from 0.75-0.90 m. The beam is supported on a steel table through two supports at 1.0 m from
51 the ends. The static boundary conditions approximate these of a simply supported beam. This is not
52 the case for the dynamic behavior as an interaction between the beam and the steel table is expected as
53 the table and the connecting supports can not be considered as infinitely stiff with respect to the beam.

54 2.1. Dynamic tests

55 The dynamic excitation of the beam is performed with hammer impacts in the vertical (z-axis
56 in Figure 2) and the lateral (y-axis, out of plane in Figure 2) direction. The tests are performed at the
57 beginning of each loading cycle, when the applied quasi-static load is zero. The response of the beam
58 to the induced excitation is recorded with three chains of multiplexed Fiber-optic Bragg Grating (FBG)
59 strain sensors; two at the top flange and one at the bottom flange (Figure 2) of the beam. The chains
60 are attached on the side of the top and the bottom flange of the beam along its longitudinal direction
61 through a clamping system, to measure axial dynamic strains, as shown in Figures. 1-2. The fiber is
62 firmly fixed at discrete connections (Figure 2b) to ensure the proper transfer of strains from the beam to
63 the sensors; the distance between two consecutive connections is 25 cm and one sensor exists between
64 them, measuring the average strain or macro-strain over this distance. The fibers are pretensioned to
65 ensure that they would remain in tension due to the applied force during the PDT. Thermal insulation
66 is also provided around the fibers to ensure that temperature fluctuations in the laboratory would
67 not affect the measurements (Figure 1). The strain acquisition system is an FAZ Technology FAZT I4
interrogator. The sampling frequency is 1000 Hz.



Figure 1. The experimental setup of the modal test. (a) Side view of the experimental setup. (b) One of the connections for the FBG sensors.

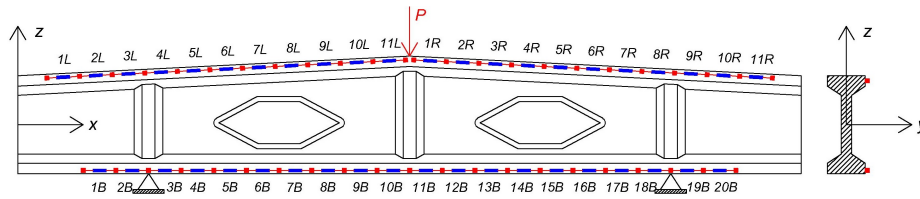


Figure 2. The FBG sensors setup. 1L-11L and 1R-11R correspond to the FBGs of the two fibers of the top flange. 1B-20B correspond to the FBGs of the bottom flange fiber. The quasi-static force P for the PDT is applied in the direction of the red arrow.

69 2.2. Progressive damage test

70 The beam is subjected to a 3-point progressive damage test. The quasi-static load is applied at the
 71 middle of the beam (Figure 2). Eleven loading cycles were performed. In each cycle, the maximum
 72 load was increased by 50 kN with respect to the previous cycle. The beam failed in shear during the
 73 eleventh loading cycle for a load of 592 kN.

74 3. Modal Analysis

75 The modal analysis is performed using the dynamic strain data. The system identification
 76 is conducted with the MACEC software [7], using the covariance-driven Stochastic Subspace
 77 Identification (SSI-cov) [8] algorithm where only the measured response (strains) is used for the
 78 identification. The maximum system order and the half number of Hankel block rows i that need to be
 79 defined in the algorithm are selected to be equal to 100 and 50 respectively. During data processing,
 80 the static or DC offset is removed from all measured signals.

81 3.1. Eigenfrequencies

82 Eleven bending, lateral and torsion modes are identified in the frequency range [0-400] Hz. The
 83 eigenfrequency values for the undamaged beam are summarized in Table 1. High identification
 84 accuracy for the eigenfrequency values is obtained since the 95% confidence interval, as derived from
 85 the SSI-cov identification [8] is narrow. The eigenfrequencies of a validated finite element model (FEM)
 86 that is built in ANSYS are also provided for comparison. High-order solid elements are used for
 87 modeling the beam accurately. The material properties that are used (Young's modulus and density)
 have been experimentally obtained from concrete cube and cylinder specimens.

Table 1. Eigenfrequency values of the undamaged beam. The vertical bending modes are denoted with 'B', the lateral bending modes with 'L' and the torsional modes with 'T'. EMA stands for experimental modal analysis and FEM for finite element model.

Method	Mode L1	Mode T1	Mode L2	Mode T2	Mode B1	Mode L3
EMA	27.20	35.50	75.30	93.00	127.50	131.00
FEM	27.40	55.40	77.15	108.70	115.40	141.90
Method	Mode T3	Mode L4	Mode T4	Mode B2	Mode B3	
EMA	178.00	216.60	244.80	265.90	313.70	
FEM	177.80	234.50	247.70	264.40	314.40	

88 When the experimentally identified and the numerically obtained eigenfrequencies are compared,
 89 a good match is observed for the lateral bending modes L1 and L2, the torsion modes T3 and T4,
 90 and the in-plane bending modes B2 and B3. On the contrary, for the remaining modes, a significant
 91 difference in the eigenfrequency values is observed. This is attributed to the interaction of the "roof"
 92 beam with the supporting beam, which is not taken into account by the FEM. In order to investigate
 93 which modes are influenced by the "roof" beam - supporting beam interaction, the modal assurance
 94

95 criterion (MAC) as a measure of consistency (degree of linearity) between the estimates of the modal
 96 vectors that are identified under different conditions is applied. The MAC values for the first two
 97 lateral modes L1 and L2 and the last two in-plane bending modes B2 and B3 are approximating unity
 98 (> 0.98), indicating a high consistency between the calculated and the experimentally obtained modes.
 99 Therefore, for these modes, the assumption of free-free boundary condition applies and the system
 100 "roof" beam-supporting beam is decoupled. Hence, it is expected that any potential changes on the
 101 dynamic characteristics of these modes will originate from the damage that is induced to the "roof"
 102 beam and not from the interaction with the supporting steel beam.

103 The evolution of the eigenfrequencies throughout the PDT is shown in Figure 3. The presented
 104 eigenfrequencies correspond to the decoupled modes B2 and B3. A similar trend is observed for the
 105 decoupled modes L1 and L2 and thus they are not presented. For the damage-sensitive modes, a
 106 constant reduction of their eigenfrequency values is observed, which is correlated with the increased
 107 level of damage of the beam. The percentile reduction of the eigenfrequency values varies from 4% to
 108 9% for the different modes, depending on the degree that each mode is influenced by the damage.

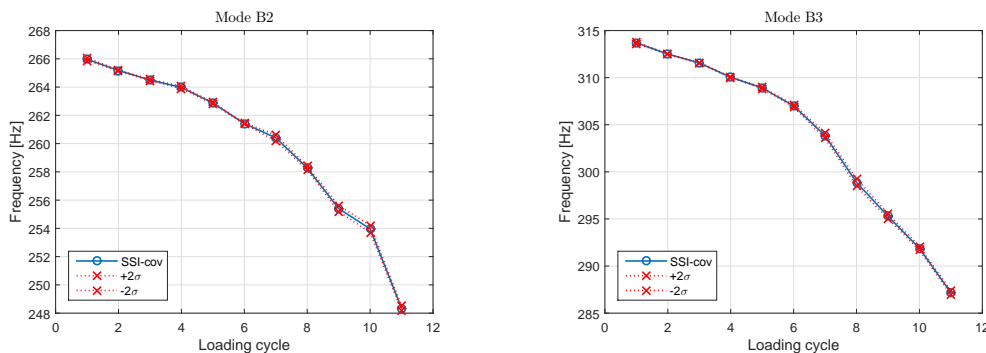


Figure 3. Evolution of the eigenfrequencies as identified from the FBG strain data (solid lines) and their 95% confidence intervals (dotted lines) for modes B2 and B3.

109 3.2. Strain mode shapes

110 The identified strain mode shapes of the beam are given in Figure 4 for four modes (L1, L2, B2
 111 and B3), the same as for the eigenfrequencies. The top subplots correspond to the top flange fibers and
 112 the bottom to the bottom flange fiber. A least-squares fit is applied for the determination of the scale
 113 factor c that links the strain mode shapes of the various cycles with the strain mode shapes of the first
 114 loading cycle. The least-squares fit is calculated to the modal strain values at the ends of the fibers i.e.,
 115 the zones outside of the static supports. Since these zones are not stressed due to the static loading,
 116 their values are not expected to change due to the imposed damage. To demonstrate the evolution of
 117 the modal strain shapes due to the imposed damage, combined graphs of the modal strain shapes that
 118 were identified in each loading cycle are presented.

119 Significant amplitude and curvature changes are observed in the vicinity of the damaged area
 120 (around the openings of the web), as it can be seen from the strain mode shapes in Figure 4. The
 121 increase in curvature and amplitude is directly related to the decrease of stiffness at certain locations of
 122 the beam (around 1500 mm and 4500 mm) where shear cracks were observed during the experiment.
 123 The evolution of the strain mode shapes during the different loading cycles is prominent. The larger
 124 amplitude values correspond to the last loading cycle, before the failure of the beam. The top flange
 125 strain mode shapes appear to be more sensitive to damage, which is in agreement with the observations
 126 during the experiment where most of the cracks were formed at the top of the beam. However, both the
 127 top and the bottom strain mode shape of the third bending mode (mode B3 - Figure 4d) are influenced
 128 from the damage allowing in this way to identify also damage of moderate severity at the bottom
 129 flange of the beam.

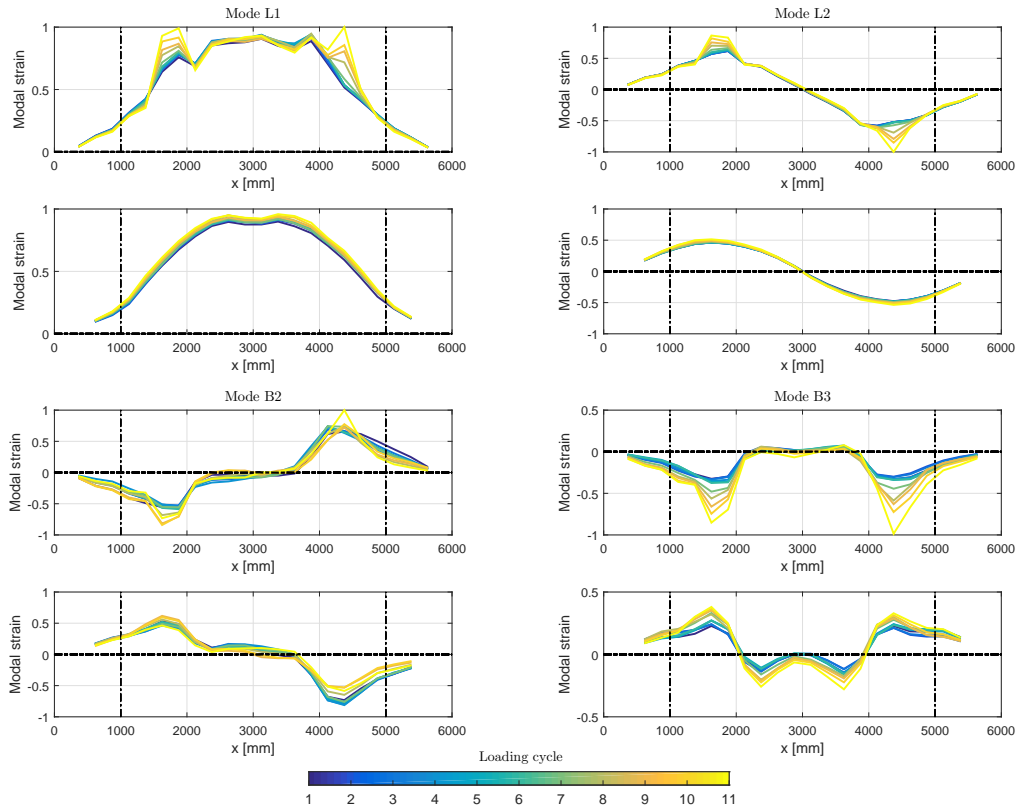


Figure 4. Evolution of the damage-sensitive strain mode shapes for the 11 loading cycles. The top subplots correspond to the top flange fibers while the bottom subplots to the bottom flange fiber. The dash-dotted lines indicate the location of the supports.

Finally, a quantity for damage detection and localization is introduced: the top-to-bottom strain ratio (TBSR), which is defined as:

$$TBSR(x) = |\epsilon_{top}(x)| \setminus |\epsilon_{bottom}(x)| \quad (1)$$

130 where $|\epsilon_{top}(x)|$ is the absolute value of the longitudinal modal strain at the top of the beam, $|\epsilon_{bottom}(x)|$
 131 is the absolute value of the longitudinal modal strain at the bottom of the beam, and x denotes, as
 132 before, the longitudinal coordinate. The TBSR is computed for the well-identified strain mode shapes
 133 of the in plane bending modes, B2 and B3. At the locations that the modal strains are approximating
 134 zero, mainly in the zone between 2700-3300 mm, the criterion is not applied since the division by very
 135 small quantities can yield inaccurate results. As can be clearly seen in Figure 5, where the evolution of
 136 the TBSR values along the beam for modes B2 and B3 throughout the PDT are given, the influence of
 137 the damage is significant. A clear increase or decrease of the TBSR at the locations where the damaged
 138 was mainly observed during the PDT, indicates its high sensitivity as a damage indicator. These
 139 changes appear already from the second loading cycle and become really apparent after the sixth
 140 loading cycle. The largest changes are observed at the zones around 1500 mm and 4500 mm, where the
 141 most severe cracks were observed during the PDT. There, the TBSR values have a percentile increase of
 142 up to 114% between the undamaged beam and the damaged beam of the last loading cycle. Therefore,
 143 the TBSR is considered as a high sensitivity measure of the level of damage.

144 4. Conclusions

145 A new method was presented for VBSHM by means of quasi-distributed longitudinal macro-strain
 146 FBG sensing. The method was demonstrated and validated by progressive damage testing of a

147 "roof" beam displaying more complex structural behavior than regular beam-type structures. While
 148 the dynamic strain amplitudes were very low (sub-microstrain RMS values were observed), the
 149 experimentally identified eigenfrequencies and strain mode shapes were seen to be very accurate.
 150 This indicates that the proposed combination of a high-accuracy tunable laser FBG interrogator
 151 and advanced parametric system identification techniques will be adequate also for large-scale civil
 152 structures. The damage that was induced into the "roof" beam by the PDT caused important changes
 153 in the eigenfrequencies and strain mode shapes identified from the FBG data in a relatively early stage.
 154 This confirms that strain mode shapes are sensitive to local damage even in this rather complex case
 155 where most cracks appear close to the strain sensors. The sensitivity becomes even larger when the
 156 ratio between the modal strain amplitudes at the top and the bottom of the beam (TBSR) is taken.

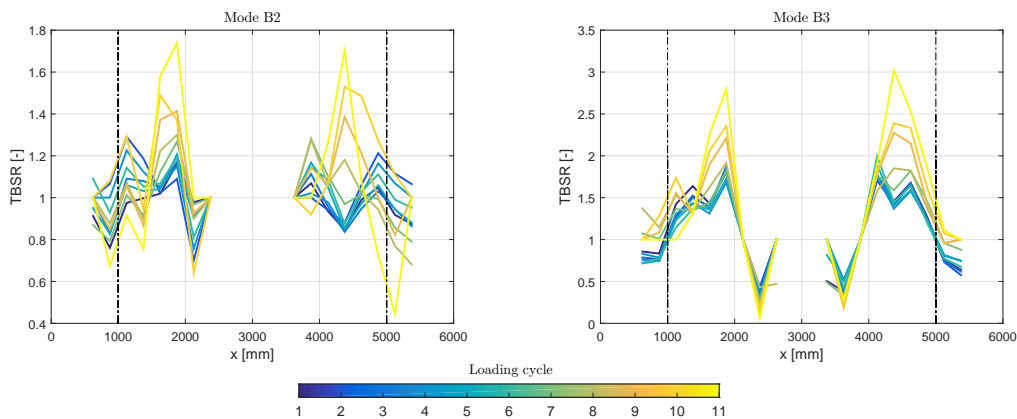


Figure 5. TBSR values between the undamaged beam strain mode shapes and the strain mode shapes of the various damage levels. The black dashed lines indicate the location of the supports. (a) Mode B2 and (b) Mode B3.

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