

Suppression of an effect of terrain unevenness on accuracy of height measurement in UAV with integrated ultrasound altimeter during landing

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Outline

- Introduction
- Methods
- Scenarios
- Results
- Conclusion

Goal of the paper

- To compare basic methods for filtration of ultrasonic height measurements.
 - Terrain unevenness
 - Measurement noise
- To identify proper usage of the methods.

Motivation of the paper

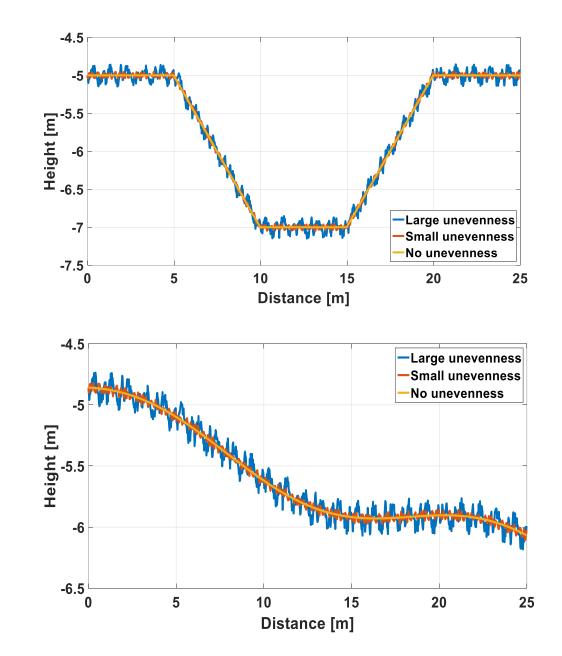
- UAV autonomous landing.
- Proper landing side identification Precision height knowledge.
- Terrain unevenness during landing side search.

Methods

- Moving average
 - $h_e(t) = [h_m(t) + h_m(t-1) + \dots + h_m(t-n)]/[n+1]$
- Kalman filter
 - $\mathbf{x}_{t|t-1} = \mathbf{A}_t \mathbf{x}_{t-1|t-1}$ • $\mathbf{P}_t - \mathbf{A}_t \mathbf{P}_t = \mathbf{A}_t \mathbf{T}_t$
 - $P_{t|t-1} = A_t P_{t-1|t-1} A_t^T + Q_t$
 - $A_t = [1 \Delta t, 0 1]$

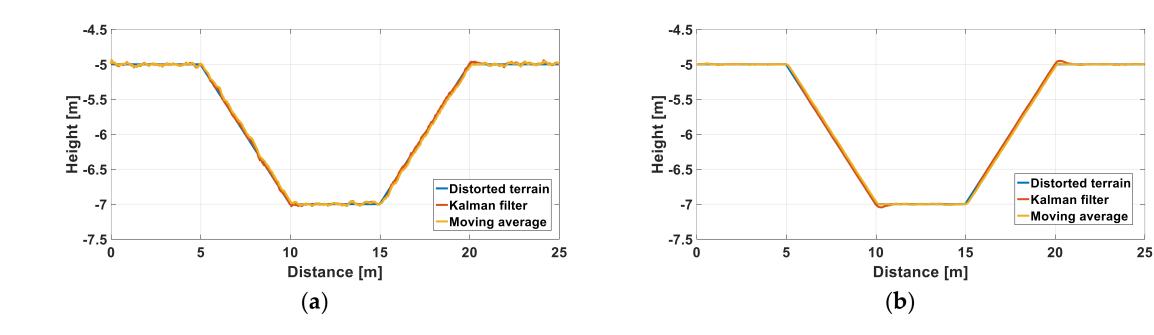
Scenarios

- 2 scenarios
- 2 versions of unevenness
- 2 versions of measurement noise
- 0.1 samples/s, 100 s
- 25 meters



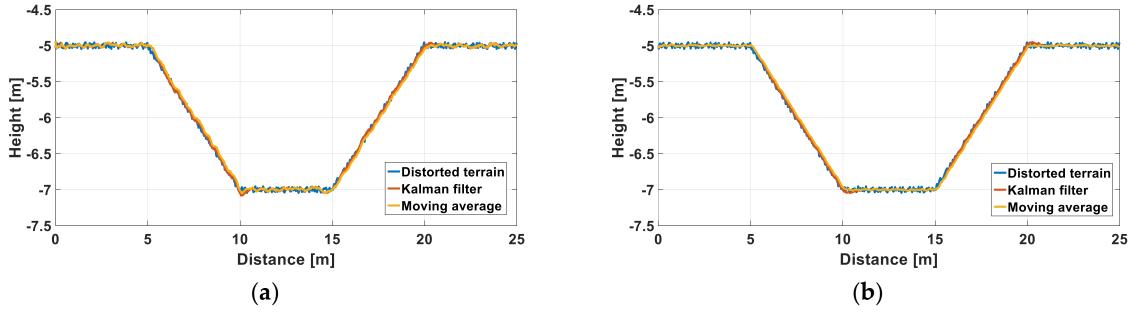
Scenario 1 – no unevenness

- (a) threshold detector
- (b) intra-pulse modulation



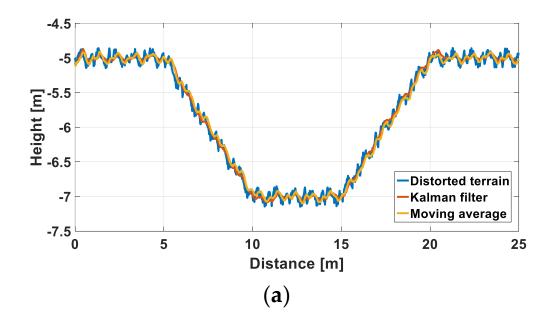
Scenario 1 – small unevenness

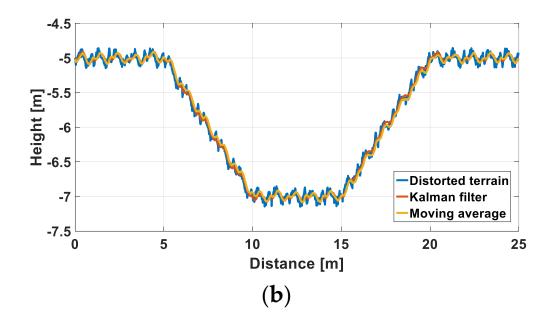
- (a) threshold detector
- (b) intra-pulse modulation



Scenario 1 – large unevenness

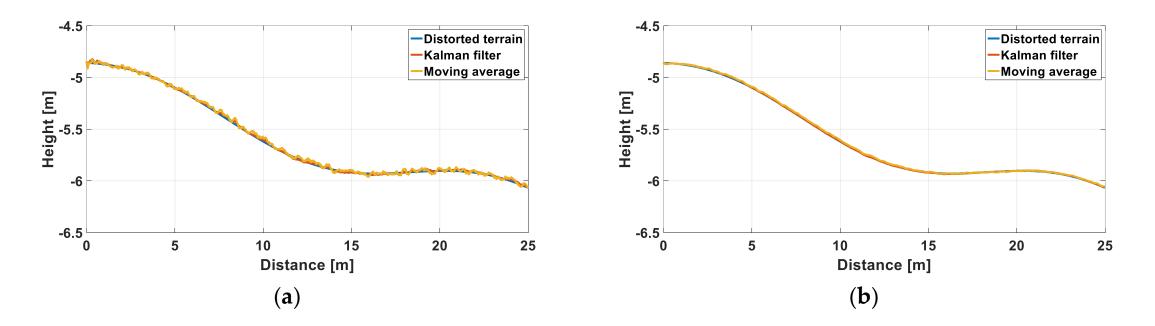
- (a) threshold detector
- (b) intra-pulse modulation





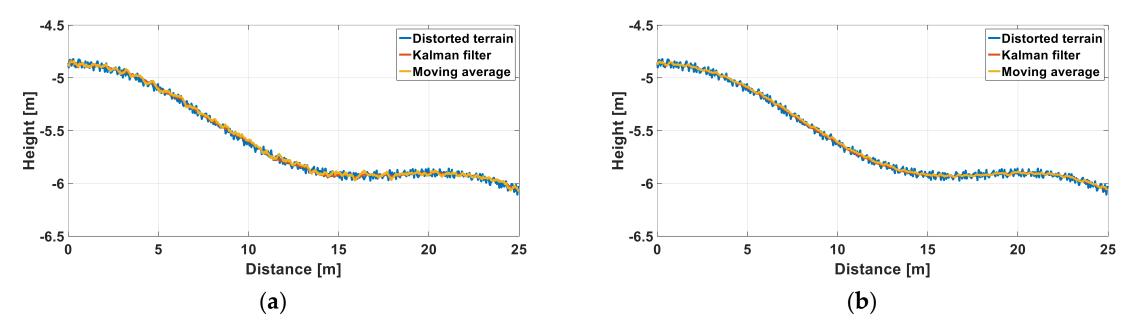
Scenario 2 – no unevenness

- (a) threshold detector
- (b) intra-pulse modulation



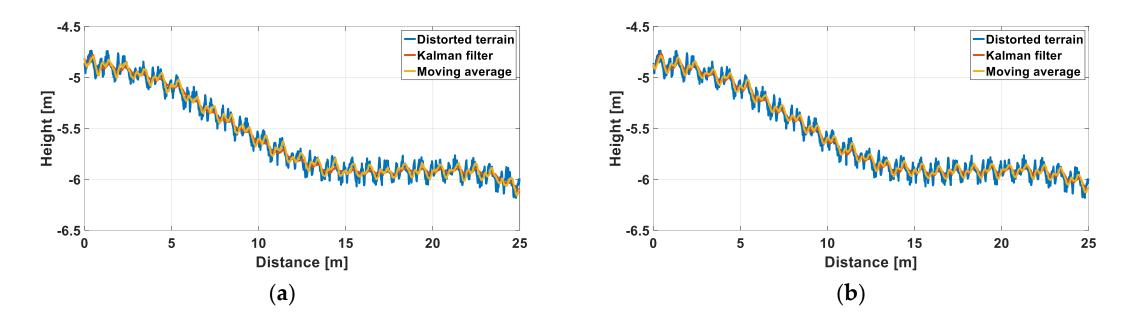
Scenario 2 – small unevenness

- (a) threshold detector
- (b) intra-pulse modulation



Scenario 2 – large unevenness

- (a) threshold detector
- (b) intra-pulse modulation



Conclusion

- Both methods reduce terrain unevenness.
- Moving average is computationally cheaper.
- Moving average generates lag in slope terrain.
- Kalman filter generates overshoots with sharp change of terrain character.
- Kalman filter produces better results with threshold detector as ultrasonic measurement technique, small unevenness and fluent terrain character.

Thank you for attention.